



Telemetry Configuration Guide for Cisco NCS 540 Series Routers, IOS XR Release 7.0.x

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Stream Telemetry Data

This document will help you understand the process of streaming telemetry data and its core components.

- Scope, on page 1
- Need, on page 1
- Benefits, on page 2
- Methods of Telemetry, on page 2

Scope

Streaming telemetry lets users direct data to a configured receiver. This data can be used for analysis and troubleshooting purposes to maintain the health of the network. This is achieved by leveraging the capabilities of machine-to-machine communication.

The data is used by development and operations (DevOps) personnel who plan to optimize networks by collecting analytics of the network in real-time, locate where problems occur, and investigate issues in a collaborative manner.

Need

Collecting data for analyzing and troubleshooting has always been an important aspect in monitoring the health of a network.

IOS XR provides several mechanisms such as SNMP, CLI and Syslog to collect data from a network. These mechanisms have limitations that restrict automation and scale. One limitation is the use of the pull model, where the initial request for data from network elements originates from the client. The pull model does not scale when there is more than one network management station (NMS) in the network. With this model, the server sends data only when clients request it. To initiate such requests, continual manual intervention is required. This continual manual intervention makes the pull model inefficient.

Network state indicators, network statistics, and critical infrastructure information are exposed to the application layer, where they are used to enhance operational performance and to reduce troubleshooting time. A push model uses this capability to continuously stream data out of the network and notify the client. Telemetry enables the push model, which provides near-real-time access to monitoring data.

Streaming telemetry provides a mechanism to select data of interest from IOS XR routers and to transmit it in a structured format to remote management stations for monitoring. This mechanism enables automatic tuning of the network based on real-time data, which is crucial for its seamless operation. The finer granularity

and higher frequency of data available through telemetry enables better performance monitoring and therefore, better troubleshooting. It helps a more service-efficient bandwidth utilization, link utilization, risk assessment and control, remote monitoring and scalability. Streaming telemetry, thus, converts the monitoring process into a Big Data proposition that enables the rapid extraction and analysis of massive data sets to improve decision-making.

Benefits

Streamed real-time telemetry data is useful in:

- **Traffic optimization:** When link utilization and packet drops in a network are monitored frequently, it is easier to add or remove links, re-direct traffic, modify policing, and so on. With technologies like fast reroute, the network can switch to a new path and re-route faster than the SNMP poll interval mechanism. Streaming telemetry data helps in providing quick response time for faster traffic.
- **Preventive troubleshooting:** Helps to quickly detect and avert failure situations that result after a problematic condition exists for a certain duration.

Methods of Telemetry

Telemetry data can be streamed using these methods:

- **Model-driven telemetry:** provides a mechanism to stream data from an MDT-capable device to a destination. The data to be streamed is driven through subscription. There are two methods of configuration:
 - Cadence-based telemetry: Cadence-based Telemetry (CDT) continuously streams data (operational statistics and state transitions) at a configured cadence. The streamed data helps users closely identify patterns in the networks. For example, streaming data about interface counters and so on.
- **Policy-based telemetry:** streams telemetry data to a destination using a policy file. A policy file defines the data to be streamed and the frequency at which the data is to be streamed.



Note

Model-driven telemetry supersedes policy-based telemetry.



Configure Model-driven Telemetry

Model-driven Telemetry (MDT) provides a mechanism to stream data from an MDT-capable device to a destination. The data to be streamed is defined through subscription.

The data to be streamed is subscribed from a data set in a YANG model. The data from the subscribed data set is streamed out to the destination either at a configured periodic interval or only when an event occurs. This behavior is based on whether MDT is configured for cadence-based telemetry.

The following YANG models are used to configure and monitor MDT:

- Cisco-IOS-XR-telemetry-model-driven-cfg.yang and openconfig-telemetry.yang: configure MDT using NETCONF or merge-config over grpc.
- Cisco-IOS-XR-telemetry-model-driven-oper.yang: get the operational information about MDT.

The process of streaming MDT data uses these components:

- **Destination:** specifies one or more destinations to collect the streamed data.
- Sensor path: specifies the YANG path from which data has to be streamed.
- **Subscription:** binds one or more sensor-paths to destinations, and specifies the criteria to stream data. In cadence-based telemetry, data is streamed continuously at a configured frequency.
- Transport and encoding: represents the delivery mechanism of telemetry data.

For more information about the core components, see Core Components of Model-driven Telemetry Streaming, on page 7.

The options to initialize a telemetry session between the router and destination is based on two modes:

- Dial-out mode: The router initiates a session to the destinations based on the subscription.
- Dial-in mode: The destination initiates a session to the router and subscribes to data to be streamed.



Note

Dial-in mode is supported only over gRPC.



Important

From Release 6.1.1 onwards, Cisco introduces support for the 64-bit Linux-based IOS XR operating system. The 64-bit platforms, such as NCS5500, NCS5000, ASR9000 support gRPC, UDP and TCP protocols. All 32-bit IOS XR platforms, such as CRS and legacy ASR9000, support only TCP protocol.

Streaming model-driven telemetry data to the intended receiver involves these tasks:

• Configure Dial-out Mode, on page 4

Configure Dial-out Mode

In a dial-out mode, the router initiates a session to the destinations based on the subscription.

All 64-bit IOS XR platforms (except for NCS 6000 series routers) support gRPC and TCP protocols. All 32-bit IOS XR platforms support only TCP.

For more information about the dial-out mode, see Dial-out Mode, on page 7.

The process to configure a dial-out mode involves:

Create a Destination Group

The destination group specifies the destination address, port, encoding and transport that the router uses to send out telemetry data.

- 1. Identify the destination address, port, transport, and encoding format.
- **2.** Create a destination group.

```
Router(config) #telemetry model-driven
Router(config-model-driven) #destination-group <group-name>

Router(config-model-driven-dest) #address family ipv4 <IP-address> port <port-number>
Router(config-model-driven-dest-addr) #encoding <encoding-format>
Router(config-model-driven-dest-addr) #protocol <transport>
Router(config-model-driven-dest-addr) #commit
```

Example: Destination Group for TCP Dial-out

The following example shows a destination group <code>DGroup1</code> created for TCP dial-out configuration with key-value Google Protocol Buffers (also called self-describing-gpb) encoding:

```
Router(config) #telemetry model-driven
Router(config-model-driven) #destination-group DGroup1
Router(config-model-driven-dest) #address family ipv4 172.0.0.0 port 5432
Router(config-model-driven-dest-addr) #encoding self-describing-gpb
Router(config-model-driven-dest-addr) #protocol tcp
Router(config-model-driven-dest-addr) #commit
```

Create a Sensor Group

The sensor-group specifies a list of YANG models that are to be streamed.

- 1. Identify the sensor path for XR YANG model.
- **2.** Create a sensor group.

```
Router(config) #telemetry model-driven
Router(config-model-driven) #sensor-group <group-name>
Router(config-model-driven-snsr-grp) # sensor-path <XR YANG model>
Router(config-model-driven-snsr-grp) # commit
```

Example: Sensor Group for Dial-out



Note

gRPC is supported in only 64-bit platforms.

The following example shows a sensor group SGroup1 created for dial-out configuration with the YANG model for interface statistics:

```
Router(config) #telemetry model-driven
Router(config-model-driven) #sensor-group SGroup1
Router(config-model-driven-snsr-grp) # sensor-path
Cisco-IOS-XR-infra-statsd-oper:infra-statistics/interfaces/interface/latest/generic-counters
Router(config-model-driven-snsr-grp) # commit
```

What to Do Next:

Create a subscription.

Create a Subscription

The subscription associates a destination-group with a sensor-group and sets the streaming method.

A source interface in the subscription group specifies the interface that will be used for establishing the session to stream data to the destination. If both VRF and source interface are configured, the source interface must be in the same VRF as the one specified under destination group for the session to be established.

```
Router(config) #telemetry model-driven
Router(config-model-driven) #subscription <subscription-name>
Router(config-model-driven-subs) #sensor-group-id <sensor-group> sample-interval <interval>
Router(config-model-driven-subs) #destination-id <destination-group>
Router(config-model-driven-subs) #source-interface <source-interface>
Router(config-mdt-subscription) #commit
```

Example: Subscription for Cadence-based Dial-out Configuration

The following example shows a subscription Sub1 that is created to associate the sensor-group and destination-group, and configure an interval of 30 seconds to stream data:

```
Router(config) #telemetry model-driven
Router(config-model-driven) #subscription Sub1
Router(config-model-driven-subs) #sensor-group-id SGroup1 sample-interval 30000
Router(config-model-driven-subs) #destination-id DGroup1
Router(config-mdt-subscription) # commit
```

Validate Dial-out Configuration

Use the following command to verify that you have correctly configured the router for dial-out.

Router#show telemetry model-driven subscription <subscription-group-name>

Example: Validation for TCP Dial-out



Core Components of Model-driven Telemetry Streaming

The core components used in streaming model-driven telemetry data are:

- Session, on page 7
- Sensor Path, on page 8
- Subscription, on page 8
- Transport and Encoding, on page 8

Session

A telemetry session can be initiated using:

Dial-in Mode

In a dial-in mode, an MDT receiver dials in to the router, and subscribes dynamically to one or more sensor paths or subscriptions. The router acts as the server and the receiver is the client. The router streams telemetry data through the same session. The dial-in mode of subscriptions is dynamic. This dynamic subscription terminates when the receiver cancels the subscription or when the session terminates.

There are two methods to request sensor-paths in a dynamic subscription:

- OpenConfig RPC model: The subscribe RPC defined in the model is used to specify sensor-paths and frequency. In this method, the subscription is not associated with an existing configured subscription. A subsequent cancel RPC defined in the model removes an existing dynamic subscription.
- **IOS XR MDT RPC:** IOS XR defines RPCs to subscribe and to cancel one or more configured subscriptions. The sensor-paths and frequency are part of the telemetry configuration on the router. A subscription is identified by its configured subscription name in the RPCs.

Dial-out Mode

In a dial-out mode, the router dials out to the receiver. This is the default mode of operation. The router acts as a client and receiver acts as a server. In this mode, sensor-paths and destinations are configured and bound together into one or more subscriptions. The router continually attempts to establish a session with each destination in the subscription, and streams data to the receiver. The dial-out mode of subscriptions is persistent.

When a session terminates, the router continually attempts to re-establish a new session with the receiver every 30 seconds.

Sensor Path

The sensor path describes a YANG path or a subset of data definitions in a YANG model with a container. In a YANG model, the sensor path can be specified to end at any level in the container hierarchy.

An MDT-capable device, such as a router, associates the sensor path to the nearest container path in the model. The router encodes and streams the container path within a single telemetry message. A receiver receives data about all the containers and leaf nodes at and below this container path.

The router streams telemetry data for one or more sensor-paths, at the configured frequency (cadence-based streaming) to one or more receivers through subscribed sessions.

Subscription

A subscription binds one or more sensor paths and destinations. An MDT-capable device streams data for each sensor path at the configured frequency (cadence-based streaming) to the destination.

The following example shows subscription SUB1 that associates a sensor-group, sample interval and destination group.

```
Router(config) #telemetry model-driven
Router(config-model-driven) #subscription SUB1
Router(config-model-driven-subs) #sensor-group-id SGROUP1 sample-interval 10000
Router(config-model-driven-subs) #strict-timer
```



Note

With a strict-timer configured for the sample interval, the data collection starts exactly at the configured time interval allowing a more deterministic behavior to stream data.

In 32-bit platforms, strict-timer can be configured only under the subscription. Whereas, 64-bit platforms support configuration at global level in addition to the subscription level. However, configuring at the global level will affect all configured subscriptions.

```
Router(config) #telemetry model-driven Router(config-model-driven) #strict-timer
```

Transport and Encoding

The router streams telemetry data using a transport mechanism. The generated data is encapsulated into the desired format using encoders.

Model-Driven Telemetry (MDT) data is streamed through:

- Transmission Control Protocol (TCP): used for only dial-out mode.
- User Datagram Protocol (UDP): used for only dial-out mode.

The data to be streamed can be encoded into Google Protocol Buffers (GPB) encoding. In GPB, the encoding can either be compact GPB (for optimising the network bandwidth usage) or self-describing GPB. The encodings supported are:

- **GPB encoding:** configuring for GPB encoding requires metadata in the form of compiled .proto files. A .proto file describes the GPB message format, which is used to stream data. The .proto files are available in the Github repository.
 - **Compact GPB encoding:** data is streamed in compressed and non self-describing format. A .proto file corresponding to each sensor-path must be used by the receiver to decode the streamed data.
 - **Key-value** (**KV-GPB**) **encoding:** data of each sensor path streamed is in a self-describing formatted ASCII text. A single .proto file telemetry.proto is used by the receiver to decode any sensor path data. Because the key names are included in the streamed data, the data on the wire is much larger as compared to compact GPB encoding.



Note

Telemetry data is streamed out of the router using an Extensible Manageability Services Deamon (emsd) process. The data of interest is subscribed through subscriptions and streamed through gRPC, TCP or UDP sessions. However, a combination of gRPC, TCP and UDP sessions with more than 150 active sessions leads to emsd crash or process restart.

Transport and Encoding



Example: Configure Event-driven Telemetry for LLDP

Telemetry supports NETCONF event notifications where the NETCONF client is configured to receive event notifications from a NETCONF server through a subscription. The NETCONF client must subscribe using a create-subscription request. Currently, only the events from Link Layer Discovery Protocol (LLDP) is supported. These event notifications are sent until either the NETCONF session or the subscription is terminated.



Note

Configuring a sensor group and a subscription is not required for receiving NETCONF notifications. While sensor path and subscription configurations are required for receiving telemetry events, NETCONF create-subscription is required for receiving NETCONF notifications.

To generate NETCONF notifications:

1. Enable NETCONF agent and SSH sub system.

```
ssh server netconf
netconf-yang agent ssh
```

2. Enable model-driven telemetry.

telemetry model-driven

3. Enable LLDP.

lldp

This example shows event-driven telemetry fo LLDP configuration data.

1. Create a destination group.

```
grpc
port 56782
address-family ipv4
!
telemetry model-driven
destination-group <destination-udp>
   address-family ipv4 <client-ip>1 port <udp port num>
   encoding self-describing-gpb
   protocol udp
```

```
!
! destination-group <destination-tcp>
   address-family ipv4 <client-ip> port <tcp port num>
   encoding gpb
   protocol tcp
! destination-group <destination-grpc>
   address-family ipv4 <grpc client ip>port <grpc port num>
   encoding self-describing-gpb
   protocol grpc no-tls
```

2. Create a sensor group.

```
sensor-group <sensor-group-name>
  sensor-path Cisco-IOS-XR-ethernet-lldp-oper:lldp/global-lldp/lldp-info
  sensor-path Cisco-IOS-XR-ethernet-lldp-oper:lldp/nodes/node/interfaces/interface
  sensor-path Cisco-IOS-XR-ethernet-lldp-oper:lldp/nodes/node/neighbors/details/detail
.
```

3. Create a subscription.

```
subscription udp-out
  sensor-group-id <sensor-group-name> sample-interval 0
  destination-id <destination-udp>
!

subscription <subscription-name>
  sensor-group-id <sensor-group-name> sample-interval 0
  destination-id <destination-tcp>

subscription <subscription-name>
  sensor-group-id <sensor-group-name> sample-interval 0
!
netconf-yang agent
ssh
!
```

4. Set the notification to stream data when an event occurs.

```
Router(config-lldp) #timer 12
Router(config-lldp)#commit
Router(config-lldp) #holdtime 150
Router (config-lldp) #commit
Router (config-lldp) #exit
#506
<?xml version="1.0"?>
<notification xmlns="urn:ietf:params:xml:ns:netconf:notification:1.0">
 <eventTime>Date-and-Time
 <lldp xmlns="http://cisco.com/ns/yang/Cisco-IOS-XR-ethernet-lldp-oper">
  <global-lldp>
  <lldp-info>
   <chassis-id>000b.1bc9.e700</chassis-id>
   <chassis-id-sub-type>4</chassis-id-sub-type>
   <system-name>ios</system-name>
    <timer>12</timer>
    <hold-time>120</hold-time>
   <re-init>2</re-init>
   </lldp-info>
  </global-lldp>
```

```
</lidp>
</notification>
Ready to send a request.
Paste your request or enter 'get', 'get-config', 'create-sub', or 'bye' to quit):
```

5. Validate response received from NETCONF agent.

```
<?xml version="1.0"?>
<notification xmlns="urn:ietf:params:xml:ns:netconf:notification:1.0">
 <eventTime>Date-and-Time
<lidp xmlns="http://cisco.com/ns/yang/Cisco-IOS-XR-ethernet-lldp-oper">
 <global-lldp>
  <lldp-info>
   <chassis-id>000b.1bc9.e700</chassis-id>
   <chassis-id-sub-type>4</chassis-id-sub-type>
   <system-name>ios</system-name>
   <timer>12</timer>
   <hold-time>150</hold-time>
   <re-init>2</re-init>
  </lldp-info>
 </global-lldp>
</lldp>
</notification>
```



Configure Policy-based Telemetry

Policy-based telemetry (PBT) streams telemetry data to a destination using a policy file. A policy file defines the data to be streamed and the frequency at which the data is to be streamed.

ASR9000 series routers and CRS routers do not support PBT.

The process of streaming telemetry data uses three core components:

- Telemetry Policy File specifies the kind of telemetry data to be generated, at a specified frequency.
- **Telemetry Encoder** encapsulates the generated data into the desired format and transmits to the receiver.
- **Telemetry Receiver** is the remote management system that stores the telemetry data.

For more information about the three core components, see Core Components of Policy-based Telemetry Streaming, on page 21.



Note

Model-driven telemetry supersedes policy-based telemetry.

Streaming policy-based telemetry data to the intended receiver involves these tasks:

- Create Policy File, on page 15
- Copy Policy File, on page 17
- Configure Encoder, on page 17
- Verify Policy Activation, on page 19

Create Policy File

You define a telemetry policy file to specify the kind of telemetry data to be generated and pushed to the receiver. Defining the policy files requires a path to stream data. The paths can be schemas, native YANG or allowed list entries.

For more information on the schema paths associated with a corresponding CLI command, see Schema Paths, on page 22.

For more information on policy files, see Telemetry Policy File, on page 21.

1. Determine the schema paths to stream data.

For example, the schema path for interfaces is:

```
RootOper.InfraStatistics.Interface(*).Latest.GenericCounters
```

2. Create a policy file that contains these paths.

Example: Policy File

The following example shows a sample policy file for streaming the generic counters of an interface:

The following example shows the paths with allowed list entries in the policy file. Instead of streaming all the data for a particular entry, only specific items can be streamed using allowed list entries. The entries are allowed using IncludeFields in the policy file. In the example, the entry within the IncludeFields section streams only the latest applied AutoBW value for that TE tunnel, which is nested two levels down from the top level of the path:

```
{
        "Name": "RSVPTEPolicy",
        "Metadata": {
                "Version": 1,
                "Description": "This policy collects auto bw stats",
                "Comment": "This is the first draft"
        },
        "CollectionGroups": {
                "FirstGroup": {
                   "Period": 10,
                        "Paths": {
                             "RootOper.MPLS TE.P2P P2MPTunnel.TunnelHead({'TunnelName':
'tunnel-te10'})": {
                                 "IncludeFields": [{
                                      "P2PInfo": [{
                                          "AutoBandwidthOper": [
                                                "LastBandwidthApplied"
                                          } ]
                                     } ]
                                }
                       }
```

```
}
```

The following example shows the paths with native YANG entry in the policy file. This entry will stream the generic counters of the interface:

```
"Paths": [
"/Cisco-IOS-XR-infra-statsd-oper:infra-statistics/interfaces/interface=*/latest/generic-counters"
]
```

What to Do Next:

Copy the policy file to the router. You may copy the same policy file to multiple routers.

Copy Policy File

Run the Secure Copy Protocol (SCP) command to securely copy the policy file from the server where it is created. For example:

```
$ scp Test.policy <ip-address-of-router>:/telemetry/policies
```

For example, to copy the Test.policy file to the /telemetry/policies folder of a router with IP address 10.0.0.1:

```
$ scp Test.policy cisco@10.0.0.1:/telemetry/policies
cisco@10.0.0.1's password:
Test.policy
100% 779     0.8KB/s     00:00
Connection to 10.0.0.1 closed by remote host.
```

Verify Policy Installation

In this example, the policy is installed in the /telemetry/policies/ folder in the router file system. Run the **show telemetry policies brief** command to verify that the policy is successfully copied to the router.

What to Do Next:

Configure the telemetry encoder to activate and stream data.

Configure Encoder

An encoder calls the streaming Telemetry API to:

- Specify policies to be explicitly defined
- Register all policies of interest

Configure the encoder to activate the policy and stream data. More than one policy and destination can be specified. Multiple policy groups can be specified under each encoder and each group can be streamed to multiple destinations. When multiple destinations are specified, the data is streamed to all destinations.

Configure an encoder based on the requirement.

Configure JSON Encoder

The JavaScript Object Notation (JSON) encoder is packaged with the IOS XR software and provides the default format for streaming telemetry data.

To stream data in JavaScript Object Notation (JSON) format, specify the encoder, policies, policy group, destination, and port:

```
Router# configure
Router(config)#telemetry policy-driven encoder json
Router(config-telemetry-json)#policy group FirstGroup
Router(config-policy-group)#policy Test
Router(config-policy-group)#destination ipv4 10.0.0.1 port 5555
Router(config-policy-group)#commit
```

The names of the policy and the policy group must be identical to the policy and its definition that you create. For more information on policy files, see Create Policy File, on page 15.

For more information about the message format of JSON encoder, see JSON Message Format, on page 25

Configure GPB Encoder

Configuring the GPB (Google Protocol Buffer) encoder requires metadata in the form of compiled .proto files. A .proto file describes the GPB message format, which is used to stream data.

Two encoding formats are supported:

- **Compact encoding** stores data in a compressed and non-self-describing format. A .proto file must be generated for each path in the policy file to be used by the receiver to decode the resulting data.
- **Key-value encoding** uses a single .proto file to encode data in a self-describing format. This encoding does not require a .proto file for each path. The data on the wire is much larger because key names are included.

To stream GPB data, complete these steps:

1. For compact encoding, create .proto files for all paths that are to be streamed using the following tool:

```
telemetry generate gpb-encoding path <path> [file <output_file>]
or
telemetry generate gpb-encoding policy <policy file> directory <output dir>
```



Attention

A parser limitation does not support the use of quotes within paths in the tool. For example, for use in the tool, change this policy path,

```
\label{local_rotation} RootOper.InfraStatistics.Interface (*).Latest.Protocol(['IPV4_UNICAST']) \ to \\ RootOper.InfraStatistics.Interface (*).Latest.Protocol.
```

- 2. Copy the policy file to the router.
- 3. Configure the telemetry policy specifying the encoder, policies, policy group, destination, and port:

```
Router# configure
Router(config) #telemetry policy-driven encoder gpb
Router(config-telemetry-json) #policy group FirstGroup
Router(config-policy-group) #policy Test
Router(config-policy-group) #destination ipv4 10.0.0.1 port 5555
Router(config-policy-group) #commit
```

For more information about the message format of GPB encoder, see GPB Message Format, on page 27

Verify Policy Activation

Verify that the policy is activated using the show telemetry policies command.

```
Router#show telemetry policy-driven policies
Wed Aug 26 02:24:40.556 PDT
  Filename:
                       Test.policy
 Version:
                       25
 Description:
                       This is a sample policy to demonstrate the syntax
  Status:
                        Active
  CollectionGroup: FirstGroup
   Cadence:
                         10s
    Total collections: 2766
    Latest collection: 2015-08-26 02:25:07
   Min collection time: 0.000s
Max collection time: 0.095s
Avg collection time: 0.000s
    Min total time: 0.022s
    Max total time:
                         0.903s
                         0.161s
    Avg total time:
    Collection errors:
    Missed collections: 0
    | Path
                                                                                   | Avg (s)
 | Max (s) | Err |
    | RootOper.InfraStatistics.Interface(*).Latest.GenericCounters
                                                                                | 0.000 |
   0.000 | 0 |
```

After the policy is validated, the telemetry encoder starts streaming data to the receiver. For more information on the receiver, see Telemetry Receiver, on page 30.

Verify Policy Activation



Core Components of Policy-based Telemetry Streaming

The core components used in streaming policy-based telemetry data are:

- Telemetry Policy File, on page 21
- Telemetry Encoder, on page 23
- Telemetry Receiver, on page 30

Telemetry Policy File

A telemetry policy file is defined by the user to specify the kind of telemetry data that is generated and pushed to the receiver. The policy must be stored in a text file with a .policy extension. Multiple policy files can be defined and installed in the /telemetry/policies/ folder in the router file system.

A policy file:

- Contains one or more collection groups; a collection group includes different types of data to be streamed at different intervals
- Includes a period in seconds for each group
- Contains one or more paths for each group
- Includes metadata that contains version, description, and other details about the policy

Policy file syntax

The following example shows a sample policy file:

```
{
"Name": "NameOfPolicy",

"Metadata": {
    "Version": 25,
    "Description": "This is a sample policy to demonstrate the syntax",
    "Comment": "This is the first draft",
    "Identifier": "<data that may be sent by the encoder to the mgmt stn"
},

"CollectionGroups": {
    "FirstGroup": {
        "Period": 10,
        "Paths": [</pre>
```

The syntax of the policy file includes:

- Name the name of the policy. In the previous example, the policy is stored in a file named NameOfPolicy.policy. The name of the policy must match the filename (without the .policy extension). It can contain uppercase alphabets, lower-case alphabets, and numbers. The policy name is case sensitive.
- **Metadata** information about the policy. The metadata can include the version number, date, description, author, copyright information, and other details that identify the policy. The following fields have significance in identifying the policy:
 - Description is displayed in the **show policies** command.
 - Version and Identifier are sent to the receiver as part of the message header of the telemetry messages.
- **CollectionGroups** an encoder object that maps the group names to information about them. The name of the collection group can contain uppercase alphabets, lowercase alphabets, and numbers. The group name is case sensitive.
- **Period** the cadence for each collection group. The period specifies the frequency in seconds at which data is queried and sent to the receiver. The value must be within the range of 5 and 86400 seconds.
- Paths one or more schema paths, allowed list entries or native YANG paths (for a container) for the data to be streamed and sent to the receiver. For example,

Schema path:

```
RootOper.InfraStatistics.Interface(*).Latest.GenericCounters  YANG \ path: \\
```

/ Cisco-IOS-XR-infra-statsd-oper: in fra-statistics/interfaces/interface=*/latest/generic-counters

Allowed list entry:

```
"RootOper.Interfaces.Interface(*)":
{
          "IncludeFields": ["State"]
}
```

Schema Paths

A schema path is used to specify where the telemetry data is collected. A few paths are listed in the following table for your reference:

Table 1: Schema Paths

| Operation | Path | |
|----------------------------|--|--|
| Interface Operational data | RootOper.Interfaces.Interface(*) | |
| Packet/byte counters | RootOper.InfraStatistics.Interface(*).Latest.GenericCounters | |
| Packet/byte rates | RootOper.InfraStatistics.Interface(*).Latest.DataRate | |
| IPv4 packet/byte counters | RootOper.InfraStatistics.Interface(*).Latest.Protocol(['IPV4_UNICAST']) | |
| MPLS stats | RootOper.MPLS_TE.Tunnels.TunnelAutoBandwidth RootOper.MPLS_TE.P2P_P2MPTunnel.TunnelHead RootOper.MPLS_TE.SignallingCounters.HeadSignallingCounters | |
| QOS Stats | • RootOper.QOS.Interface(*).Input.Statistics • RootOper.QOS.Interface(*).Output.Statistics | |
| BGP Data | RootOper.BGP.Instance({'InstanceName': 'default'}).InstanceActive.DefaultVRF.Neighbor([*]) | |
| Inventory data | RootOper.PlatformInventory.Rack(*).Attributes.BasicInfo RootOper.PlatformInventory.Rack(*).Slot(*).Card(*).Sensor(*).Attributes.BasicInfo | |

Telemetry Encoder

The telemetry encoder encapsulates the generated data into the desired format and transmits to the receiver.

An encoder calls the streaming Telemetry API to:

- Specify policies to be explicitly defined
- · Register all policies of interest

Telemetry supports two types of encoders:

JavaScript Object Notation (JSON) encoder

This encoder is packaged with the IOS XR software and provides the default method of streaming telemetry data. It can be configured by CLI and XML to register for specific policies. Configuration is grouped into policy groups, with each policy group containing one or more policies and one or more destinations. JSON encoding is supported over only TCP transport service.

JSON encoder supports two encoding formats:

- **Restconf-style encoding** is the default JSON encoding format.
- Embedded-keys encoding treats naming information in the path as keys.

Google Protocol Buffers (GPB) encoder

This encoder provides an alternative encoding mechanism, streaming the data in GPB format over UDP or TCP. It can be configured by CLI and XML and uses the same policy files as those of JSON.

Additionally, a GPB encoder requires metadata in the form of compiled .proto files to translate the data into GPB format.

GPB encoder supports two encoding formats:

- **Compact encoding** stores data in a compact GPB structure that is specific to the policy that is streamed. This format is available over both UDP and TCP transport services. A .proto file must be generated for each path in the policy file to be used by the receiver to decode the resulting data.
- **Key-value encoding** stores data in a generic key-value format using a single .proto file. The encoding is self-describing as the keys are contained in the message. This format is available over TCP transport service. A .proto file is not required for each policy file because the receiver can interpret the data.

TCP Header

Streaming data over a TCP connection either with a JSON or a GPB encoder and having it optionally compressed by zlib ensures that the stream is flushed at the end of each batch of data. This helps the receiver to decompress the data received. If data is compressed using zlib, the compression is done at the policy group level. The compressor resets when a new connection is established from the receiver because the decompressor at the receiver has an empty initial state.

Header of each TCP message:

| Туре | Flags | Length | Message |
|---------|---|--------|----------|
| 4 bytes | 4 bytes default - Use 0x0 value to set no flags. zlib compression - Use 0x1 value to set zlib compression on the message. | | Variable |

where:

- The Type is encoded as a big-endian value.
- The Length (in bytes) is encoded as a big-endian value.
- The flags indicates modifiers (such as compression) in big-endian format.
- The message contains the streamed data in either JSON or GPB object.

Type of messages:

| Туре | Name | Length | Value |
|------|------------------|----------|-------------------------------|
| 1 | Reset Compressor | 0 | No value |
| 2 | JSON Message | Variable | JSON message (any format) |
| 3 | GPB compact | Variable | GPB message in compact format |

| Туре | Name | Length | Value |
|------|---------------|----------|---------------------------------|
| 4 | GPB key-value | Variable | GPB message in key-value format |

JSON Message Format

JSON messages are sent over TCP and use the header message described in TCP Header, on page 24.

The message consists of the following JSON objects:

```
{
   "Policy": "<name-of-policy>",
   "Version": "<policy-version>",
   "Identifier": "<data from policy file>"
   "CollectionID": <id>,
   "Path": <Policy Path>,
   "CollectionStartTime": <timestamp>,
   "Data": { ... object as above ... },
   "CollectionEndTime": <timestamp>,
}
```

where:

- Policy, Version and Identifier are specified in the policy file.
- CollectionID is an integer that allows messages to be grouped together if data for a single path is split over multiple messages.
- Path is the base path of the corresponding data as specified in the policy file.
- CollectionStartTime and CollectionEndTime are the timestamps that indicate when the data was collected

The JSON message reflects the hierarchy of the router's data model. The hierarchy consists of:

- containers: a container has nodes that can be of different types.
- tables: a table also contains nodes, but the number of child nodes may vary, and they must be of the same type.
- leaf node: a leaf contains a data value, such as integer or string.

The schema objects are mapped to JSON are in this manner:

- Each container maps to a JSON object. The keys are strings that represent the schema names of the nodes; the values represent the values of the nodes.
- JSON objects are also used to represent tables. In this case, the keys are based on naming information that is converted to string format. Two options are provided for encoding the naming information:
 - The default is restconf-style encoding, where naming parameters are contained within the child node to which it refers.
 - The embedded-keys option uses the naming information as keys in a JSON dictionary, with the corresponding child node forming the value.
- Leaf data types are mapped in this manner:

- Simple strings, integers, and booleans are mapped directly.
- Enumeration values are stored as the string representation of the value.
- Other simple data types, such as IP addresses, are mapped as strings.

Example: Rest-conf Encoding

For example, consider the path -

```
Interfaces(*).Counters.Protocols("IPv4")
```

This has two naming parameters - the interface name and the protocol name - and represents a container holding leaf nodes which are packet and byte counters. This would be represented as follows:

```
"Interfaces": [
 {
    "Name": "GigabitEthernet0/0/0/1"
    "Counters": {
      "Protocols": [
          "ProtoName": "IPv4",
          "CollectionTime": 12345678,
          "InputPkts": 100,
          "InputBytes": 200,
      ]
    }
  },{
    "Name": "GigabitEthernet0/0/0/2"
    "Counters": {
      "Protocols": [
          "ProtoName": "IPv4",
          "CollectionTime": 12345678,
          "InputPkts": 400,
          "InputBytes": 500,
      ]
    }
  }
]
```

A naming parameter with multiple keys, for example Foo.Destination(IPAddress=10.1.1.1, Port=2000) would be represented as follows:

Example: Embedded Keys Encoding

The embedded-keys encoding treats naming information in the path as keys in the JSON dictionary. The key name information is lost and there are extra levels in the hierarchy but it is clearer which data constitutes the key which may aid collectors when parsing it. This option is provided primarily for backwards-compatibility with 6.0.

```
"Interfaces": {
    "GigabitEthernet0/0/0/1": {
      "Counters": {
        "Protocols":
          "IPv4": {
            "CollectionTime": 12345678,
            "InputPkts": 100,
            "InputBytes": 200,
        }
      }
    "GigabitEthernet0/0/0/2": {
      "Counters": {
        "Protocols":
          "IPv4": {
            "CollectionTime": 12345678,
            "InputPkts": 400,
            "InputBytes": 500,
      }
   }
  }
```

A naming parameter with multiple keys, for example Foo.Destination(IPAddress=10.1.1.1, Port=2000), would be represented by nesting each key in order:

GPB Message Format

The output of the GPB encoder consists entirely of GPBs and allows multiple tables in a single packet for scalability.

GPB (Google Protocol Buffer) encoder requires metadata in the form of compiled .proto files. A .proto file describes the GPB message format, which is used to stream data.

For TCP, the message body is either a Telemetry message or a TelemetryHeader message, depending on which of the following encoding types is configured:

- **Compact GPB format** stores data in a compressed and non-self-describing format. A .proto file must be generated for each path in the policy file to be used by the receiver to decode the resulting data.
- **Key-value GPB format** uses a single .proto file to encode data in a self-describing format. This encoding does not require a .proto file for each path. The data on the wire is much larger because key names are included.

In the following example, the policy group, *alpha* uses the default configuration of compact encoding and UDP transport. The policy group, *beta* uses compressed TCP and key-value encoding. The policy group, *gamma* uses compact encoding over uncompressed TCP.

```
telemetry policy-driven encoder gpb
 policy group alpha
   policy foo
   destination ipv4 192.168.1.1 port 1234
   destination ipv4 10.0.0.1 port 9876
 policy group beta
   policy bar
   policy whizz
   destination ipv4 10.20.30.40 port 3333
   transport tcp
     compression zlib
  policy group gamma
   policy bang
   destination ipv4 10.11.1.1 port 4444
    transport tcp
     encoding-format gpb-compact
```

Compact GPB Format

The compact GPB format is intended for streaming large volumes of data at frequent intervals. The format minimizes the size of the message on the wire. Multiple tables can be sent in in a single packet for scalability.



Note

The tables can be split over multiple packets but fragmenting a row is not supported. If a row in the table is too large to fit in a single UDP frame, it cannot be streamed. Instead either switch to TCP, increase the MTU, or modify the .proto file.

The following proto file shows the header, which is common to all packets sent by the encoder:

```
message TelemetryHeader {
  optional uint32 encoding = 1

  optional string policy_name = 2;
  optional string version = 3;
  optional string identifier = 4;

  optional uint64 start_time = 5;
  optional uint64 end_time = 6;

  repeated TelemetryTable tables = 7;
}

message TelemetryTable {
  optional string policy_path = 1;
  repeated bytes row = 2;
  }

where:
```

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- encoding is used by receivers to verify that the packet is valid.
- policy name, version and identifier are metadata taken from the policy file.
- start time and end time indicate the duration when the data is collected.
- tables is a list of tables within the packet. This format indicates that it is possible to receive results for multiple schema paths in a single packet.
- For each table:
 - policy path is the schema path.
 - row is one or more byte arrays that represents an encoded GPB.

Key-value GPB Format

The self-describing key-value GPB format uses a generic .proto file. This file encodes data as a sequence of key-value pairs. The field names are included in the output for the receiver to interpret the data.

The following proto file shows the field containing the key-value pairs:

```
message Telemetry
  uint64 collection id = 1;
  string base path = 2;
  string subscription identifier = 3;
  string model_version = 4;
  uint64 collection_start_time = 5;
uint64 msg_timestamp = 6;
  repeated TelemetryField fields = 14;
  uint64 collection end time = 15;
message TelemetryField {
  uint64     timestamp = 1;
string     name = 2;
  string
             augment_data = 3;
  bool
  oneof value_by_type {
    bytes bytes_value = 4;
string string_value = 5;
               string_value = 5;

bool_value = 6;

uint32_value = 7;

uint64_value = 8;

sint32_value = 9;

sint64_value = 10;

double_value = 11;

float_value = 12.
     string
    bool
     uint32
    uint64
     sint32
sint64
     double
     float
  repeated TelemetryField fields = 15;
```

where:

- collection_id, base_path, collection_start_time and collection_end_time provide streaming details.
- subscription_identifier is a fixed value for cadence-driven telemetry. This is used to distinguish from event-driven data.
- model_version contains a string used for the version of the data model, as applicable.

Telemetry Receiver

A telemetry receiver is used as a destination to store streamed data.

A sample receiver that handles both JSON and GPB encodings is available in the Github repository.

A copy of the cisco.proto file is required to compile code for a GPB receiver. The cisco.proto file is available in the Github repository.

If you are building your own collector, use the standard protoc compiler. For example, for the GPB compact encoding:

 $\label{lem:protoc} \verb|protoc --python_out . -I=/sw/packages/protoc/current/google/include/:. generic_counters.proto-ipv4_coun$

where:

- --python_out <out_dir> specifies the location of the resulting generated files. These files are of the form <name>_pb2.py.
- -I <import_path> specifies the path to look for imports. This must include the location of descriptor.proto from Google. (in /sw/packages) and cisco.proto and the .proto files that are compiled.

All files shown in the above example are located in the local directory.