



Network Synchronization Configuration Guide for Cisco NCS 560 Series Routers, IOS XR Release 25.1.x, 25.2.x

First Published: 2025-02-07

Last Modified: 2025-06-13

Americas Headquarters

Cisco Systems, Inc.
170 West Tasman Drive
San Jose, CA 95134-1706
USA
<http://www.cisco.com>
Tel: 408 526-4000
800 553-NETS (6387)
Fax: 408 527-0883

THE SPECIFICATIONS AND INFORMATION REGARDING THE PRODUCTS IN THIS MANUAL ARE SUBJECT TO CHANGE WITHOUT NOTICE. ALL STATEMENTS, INFORMATION, AND RECOMMENDATIONS IN THIS MANUAL ARE BELIEVED TO BE ACCURATE BUT ARE PRESENTED WITHOUT WARRANTY OF ANY KIND, EXPRESS OR IMPLIED. USERS MUST TAKE FULL RESPONSIBILITY FOR THEIR APPLICATION OF ANY PRODUCTS.

THE SOFTWARE LICENSE AND LIMITED WARRANTY FOR THE ACCOMPANYING PRODUCT ARE SET FORTH IN THE INFORMATION PACKET THAT SHIPPED WITH THE PRODUCT AND ARE INCORPORATED HEREIN BY THIS REFERENCE. IF YOU ARE UNABLE TO LOCATE THE SOFTWARE LICENSE OR LIMITED WARRANTY, CONTACT YOUR CISCO REPRESENTATIVE FOR A COPY.

The Cisco implementation of TCP header compression is an adaptation of a program developed by the University of California, Berkeley (UCB) as part of UCB's public domain version of the UNIX operating system. All rights reserved. Copyright © 1981, Regents of the University of California.

NOTWITHSTANDING ANY OTHER WARRANTY HEREIN, ALL DOCUMENT FILES AND SOFTWARE OF THESE SUPPLIERS ARE PROVIDED "AS IS" WITH ALL FAULTS. CISCO AND THE ABOVE-NAMED SUPPLIERS DISCLAIM ALL WARRANTIES, EXPRESSED OR IMPLIED, INCLUDING, WITHOUT LIMITATION, THOSE OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE AND NON-INFRINGEMENT OR ARISING FROM A COURSE OF DEALING, USAGE, OR TRADE PRACTICE.

IN NO EVENT SHALL CISCO OR ITS SUPPLIERS BE LIABLE FOR ANY INDIRECT, SPECIAL, CONSEQUENTIAL, OR INCIDENTAL DAMAGES, INCLUDING, WITHOUT LIMITATION, LOST PROFITS OR LOSS OR DAMAGE TO DATA ARISING OUT OF THE USE OR INABILITY TO USE THIS MANUAL, EVEN IF CISCO OR ITS SUPPLIERS HAVE BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES.

Any Internet Protocol (IP) addresses and phone numbers used in this document are not intended to be actual addresses and phone numbers. Any examples, command display output, network topology diagrams, and other figures included in the document are shown for illustrative purposes only. Any use of actual IP addresses or phone numbers in illustrative content is unintentional and coincidental.

All printed copies and duplicate soft copies of this document are considered uncontrolled. See the current online version for the latest version.

Cisco has more than 200 offices worldwide. Addresses and phone numbers are listed on the Cisco website at www.cisco.com/go/offices.

Cisco and the Cisco logo are trademarks or registered trademarks of Cisco and/or its affiliates in the U.S. and other countries. To view a list of Cisco trademarks, go to this URL: <https://www.cisco.com/c/en/us/about/legal/trademarks.html>. Third-party trademarks mentioned are the property of their respective owners. The use of the word partner does not imply a partnership relationship between Cisco and any other company. (1721R)

© 2025 Cisco Systems, Inc. All rights reserved.



CONTENTS

CHAPTER 1	Using YANG Data Models 1
CHAPTER 2	Synchronous Ethernet ESMC and SSM 3
	Frequency Synchronization Timing Concepts 4
	Sources 4
	Selection Points 5
	Restrictions 5
	Configuring Frequency Synchronization 5
	Enabling Frequency Synchronization on the Router 5
	Configuring Frequency Synchronization on an Interface 6
	Configuring Frequency Synchronization on a Clock Interface 6
	SyncE Preference for PTP Receiver Interface 7
	Configure SyncE Preference for PTP Receiver Interface 8
	Verifying the Frequency Synchronization Configuration 9
	Verifying the ESMC Configuration 11
	Verifying Synchronous Ethernet LEDs 12
CHAPTER 3	Understanding PTP 13
	Why PTP? 14
	Routers and Delays 15
	Message-Based Synchronization 15
	PTP Event Message Sequences 15
	Synchronizing with Boundary Clocks 15
	Synchronizing the Local Clock 17
	PTP Clocks 17
	Restrictions for PTP 17

PTP Phase Difference Threshold Between Passive and Secondary Ports	18
Isolate Foreign Masters Causing Packet Timing Signal Fail	20
PTP Profiles	21
ITU-T Telecom Profiles for PTP	21
G.8265.1	21
G.8275.1	22
G.8275.2	23
PTP Virtual Port	25
Configuring the G.8275.1 Profile	26
Multiple PTP profile interoperability	27
Restrictions and guidelines for multiple PTP profile interoperability	27
How multiple PTP profile interoperation works	28
Configure multiple PTP profile interoperability	29
Configuring Virtual Port	30
Slow Tracking	30
PTP Holdover Traceability Suppression	31
IEEE Default Profile	32
Example: Hybrid Default Profile	32
PTP Hybrid Mode	33
Configuring PTP Hybrid Mode	33
Configure PTP for SyncE and PTP Traceability	34
Verifying the PTP Hybrid Mode Configurations	35
Configure PTP Delay Asymmetry	36
Performance Monitoring for PTP Networks	38
Configure PTP Performance Monitoring	40

CHAPTER 4
External Timing Source 45

GPS	45
Configuring GPS Settings for the Grandmaster Clock	46
Verifying the GPS Input	46
Building Integrated Timing Supply (BITS)	47
Prerequisite for BITS	47
Configuring BITS-IN	47
Configuring BITS-OUT	48

Verifying BITS-IN Configuration	48
Verifying BITS-OUT Configuration	49
Verify Quality Level Received and Clock Interfaces	49

CHAPTER 5

Implementing NTP 51

Information About Implementing NTP	51
Configuring NTP	52
PTP-NTP Interworking	52
Enable PTP-NTP Interworking	53
Configuring Poll-Based Associations	54
Configuring Broadcast-Based Associations	54
Configuring NTP Access Groups	54
Configuring NTP Authentication	55
Disabling NTP on an Interface	55
Configuring the System as an Authoritative NTP Server	55
Updating the Hardware Clock	56
Configuring NTP Server Inside VRF Interface	56

CHAPTER 6

Workflow and Use Case 57

CHAPTER 7

Configure the Global Navigation Satellite System 61

Overview of GNSS	61
Operation of GNSS Module	62
Prerequisites for GNSS	64
Restrictions for GNSS	64
Configure GNSS	64

CHAPTER 8

Network Synchronization Design Best Practices 67

Network Synchronization Decision Tree	67
General Guidelines for Successful Synchronization Deployments	68
Guidelines for Phase Synchronization Deployments	69
PTP over IP Network Design	70
Selecting the Correct Profile For Network Synchronization	71
Reducing Asymmetry	72

Reducing Packet Delay Variation	72
Remediating Transport Asymmetry	72
Synchronizing Across Networks	73



CHAPTER 1

Using YANG Data Models

Cisco IOS XR supports a programmatic way of configuring and collecting operational data of a network device using YANG data models. Although configurations using CLIs are easier and human-readable, automating the configuration using model-driven programmability results in scalability.

The data models are available in the release image, and are also published in the [Github](#) repository. Navigate to the release folder of interest to view the list of supported data models and their definitions. Each data model defines a complete and cohesive model, or augments an existing data model with additional XPath. To view a comprehensive list of the data models supported in a release, navigate to the **Available-Content.md** file in the repository. The unsupported sensor paths are documented as deviations. For example, `openconfig-acl.yang` provides details about the supported sensor paths, whereas `cisco-xr-openconfig-acl-deviations.yang` shows the unsupported sensor paths for `openconfig-acl.yang` model on Cisco IOS XR routers.

You can also view the data model definitions using the [YANG Data Models Navigator](#) tool. This GUI-based and easy-to-use tool helps you explore the nuances of the data model and view the dependencies between various containers in the model. You can view the list of models supported across Cisco IOS XR releases and platforms, locate a specific model, view the containers and their respective lists, leaves, and leaf lists presented visually in a tree structure. This visual tree form helps you get insights into nodes that can help you automate your network.

To get started with using the data models, see the Programmability Configuration Guide for Cisco NCS 560 Series Routers.



CHAPTER 2

Synchronous Ethernet ESMC and SSM

Table 1: Feature History Table

Feature name	Release Information	Feature Description
Enhanced SyncE and extended ESMC	Release 7.8.1	ITU-T G.8262.1 recommendation defines the requirements for timing devices used in synchronizing network equipment. For example, bandwidth, frequency accuracy, holdover, and noise generation. With eSyncE and eESMC support, the routers are capable of handling the following SyncE clocks on the network: <ul style="list-style-type: none">• Enhanced ethernet equipment clock (eEEEC)• Enhanced primary reference clock (ePRC)• Enhanced primary reference timing clock (ePRTC)
Support for Frequency Synchronization on the Cisco N560-IMA8Q interface module	Release 7.4.1	Based on the ITU-T G.8262 recommendations, precision frequency is enabled on timing devices to deliver frequency synchronization for bandwidth, frequency accuracy, holdover, and noise generation. This support allows for correct network operations when synchronous equipment is timed from either another synchronous equipment clock or a higher-quality clock.

Synchronous Ethernet is an extension of Ethernet designed to provide the reliability found in traditional SONET/SDH and T1/E1 networks to Ethernet packet networks by incorporating clock synchronization features.

It supports the Synchronization Status Message (SSM) and Ethernet Synchronization Message Channel (ESMC) for synchronous Ethernet clock synchronization.

Synchronous Ethernet incorporates the Synchronization Status Message (SSM) used in Synchronous Optical Networking (SONET) and Synchronous Digital Hierarchy (SDH) networks. While SONET and SDH transmit the SSM in a fixed location within the frame, Ethernet Synchronization Message Channel (ESMC) transmits the SSM using a protocol: the IEEE 802.3 Organization-Specific Slow Protocol (OSSP) standard.

The ESMC carries a Quality Level (QL) value identifying the clock quality of a given synchronous Ethernet timing source. Clock quality values help a synchronous Ethernet node derive timing from the most reliable source and prevent timing loops.

When configured to use synchronous Ethernet, the router synchronizes to the best available clock source. If no better clock sources are available, the router remains synchronized to the current clock source.

The router supports QL-enabled mode.

- [Frequency Synchronization Timing Concepts, on page 4](#)
- [Configuring Frequency Synchronization, on page 5](#)
- [Verifying the Frequency Synchronization Configuration, on page 9](#)
- [Verifying the ESMC Configuration, on page 11](#)
- [Verifying Synchronous Ethernet LEDs, on page 12](#)

Frequency Synchronization Timing Concepts

The Cisco IOS XR frequency synchronization infrastructure is used to select between different frequency sources to set the router backplane frequency and time-of-day. There are two important concepts that must be understood with respect to the frequency synchronization implementation.

Sources

A source is a piece of hardware that inputs frequency signals into the system or transmits them out of the system. There are four types of sources:

- Line interfaces: This includes SyncE interfaces.
- Clock interfaces: These are external connectors for connecting other timing signals, such as, GPS, BITS.
- PTP clock: If IEEE 1588 version 2 is configured on the router, a PTP clock may be available to frequency synchronization as a source of the time-of-day and frequency.
- Internal oscillator: This is a free-running internal oscillator chip.

Each timing source has a Quality Level (QL) associated with it which gives the accuracy of the clock. This QL information is transmitted across the network via SSMs over the Ethernet Synchronization Messaging Channel (ESMC) or SSMs contained in the SONET/SDH frames so that devices know the best available source to synchronize to. In order to define a preferred network synchronization flow, and to help prevent timing loops, you can assign priority values to particular timing sources on each router. The combination of QL information and user-assigned priority levels allows each router to choose a timing source to use to clock its SyncE and SONET/SDH interfaces, as described in the ITU standard G.781.

Priority Levels

You can specify the priority of the frequency source on a controller or an interface. Values can range from 1 (highest priority) to 254 (lowest priority). The default value is 100. The priority is used in the clock-selection algorithm to choose between two sources that have the same quality level (QL). Lower priority values are preferred. For example, you can set the priority value for a GNSS clock source by using this command:

```
Router(config-gnss-freqsync)# priority 5
```

The router first considers the QL advertised by different timing sources. If two sources have the same QL, the router selects the source with a lower priority value for network synchronization.

Selection Points

A selection point is any point where a choice is made between several frequency signals, and possibly one or more of them are selected. Selection points form a graph representing the flow of timing signals between the different cards in a router running Cisco IOS XR software. For example, one or multiple selection points select between the different Synchronous Ethernet inputs available on a single line card, and the result of these selection points is forwarded to a selection point on the RSP to select between the selected source from each card.

The input signals to the selection points can be:

- Received directly from a source.
- The output from another selection point on the same card.
- The output from a selection point on a different card.

The output of a selection point can be used in a number of ways:

- Used to drive the signals sent out of a set of sources.
- As input into another selection point on the card.
- As input into a selection point on another card.

Use the `show frequency synchronization selection` command to see a detailed view of the different selection points within the system.

Restrictions

- SyncE ESMC and SSM are not supported on 1G fibre interfaces of N540X-16Z4G8Q2C-A and N540X-16Z4G8Q2C-D variants.
- SyncE isn't supported on Gigabit Ethernet 0/0/0/24 to 0/0/0/31 ports.
- The Precision Time Protocol (PTP) session flaps during Route Processor Failover (RPFO).

Configuring Frequency Synchronization

Enabling Frequency Synchronization on the Router

This task describes the router-level configuration required to enable frequency synchronization.

```
RP/0/RP0/CPU0:Router# configure
RP/0/RP0/CPU0:Router(config)# frequency synchronization
RP/0/RP0/CPU0:Router(config-freqsync)# clock-interface timing-mode system
RP/0/RP0/CPU0:Router(config-freqsync)# quality itu-t option 1 generation 1
RP/0/RP0/CPU0:Router(config-freqsync)# log selection changes
RP/0/RP0/CPU0:Router(config-freqsync)# commit
```

Configuring Frequency Synchronization on an Interface

By default, there is no frequency synchronization on line interfaces. Use this task to configure an interface to participate in frequency synchronization.

Before You Begin

You must enable frequency synchronization globally on the router.

```
RP/0/RP0/CPU0:R1#config terminal
RP/0/RP0/CPU0:R1(config)#interface TenGigabitEthernet 0/0/0/0
RP/0/RP0/CPU0:R1(config-if)#frequency synchronization
RP/0/RP0/CPU0:R1(config-if-freqsync)#selection input
RP/0/RP0/CPU0:R1(config-if-freqsync)#wait-to-restore 10
RP/0/RP0/CPU0:R1(config-if-freqsync)#priority 5
RP/0/RP0/CPU0:R1(config-if-freqsync)#quality transmit exact itu-t option 1 PRC
RP/0/RP0/CPU0:R1(config-if-freqsync)#quality receive exact itu-t option 1 PRC
RP/0/RP0/CPU0:R1(config-if-freqsync)#commit
or
RP/0/RP0/CPU0:router(config-freqsync)# commit
```

Configuring Frequency Synchronization on a Clock Interface

To enable a clock interface to be used as frequency input or output, you must configure the port parameters and frequency synchronization, as described in this task.

```
RP/0/RP0/CPU0:R1#configure
RP/0/RP0/CPU0:R1(config)# clock-interface sync 2 location 0/RP0/CPU0
RP/0/RP0/CPU0:R1(config-clock-if)# port-parameters
RP/0/RP0/CPU0:R1(config-clk-parms)# gps-input tod-format cisco pps-input ttl
RP/0/RP0/CPU0:R1(config-clk-parms)# exit
RP/0/RP0/CPU0:R1(config-clock-if)# frequency synchronization
RP/0/RP0/CPU0:R1(config-clk-freqsync)# selection input
RP/0/RP0/CPU0:R1(config-clk-freqsync)# wait-to-restore 1
RP/0/RP0/CPU0:R1(config-clk-freqsync)# quality receive exact itu-t option 1 PRC
```

SyncE Preference for PTP Receiver Interface

Table 2: Feature History Table

Feature Name	Release Information	Feature Description
SyncE Preference for PTP Receiver Interface	Release 24.4.1	<p>You can now mitigate synchronization issues when SyncE and PTP sources come from different, non-traceable origins. This feature ensures that SyncE selection among sources with equal Quality Levels (QL) and user priority prefers the interface on which the PTP receiver is selected. If the PTP source fails or its quality degrades, causing the system to switch to another PTP source, SyncE switches to the new PTP source, provided the new interface has the same SyncE QL and priority as the previously selected interface.</p> <p>This feature introduces these changes:</p> <p>CLI:</p> <ul style="list-style-type: none"> <code>synchronous-ethernet prefer-interface ptp-receiver</code>

In network deployments, users often utilize multiple clock sources to ensure redundancy, achieving synchronization through T-GM clocks powered by Primary Reference Time Clocks (PRTC) sources like GNSS. These clocks deliver frequency and time synchronization to other network nodes using both SyncE and PTP in hybrid mode. However, issues can arise when SyncE and PTP sources come from different, non-traceable origins, leading to synchronization failures in PTP.

To mitigate this issue, you can configure the **synchronous-ethernet prefer-interface ptp-receiver** command. When this command is configured, the SyncE selection among sources with equal Quality Levels (QL) and user priority prefers the interface on which the PTP receiver is selected.

- If either the QL or the user priority of the sources differ, then the syncE selection would follow the G.781 requirements.
- If the PTP source goes down or if the PTP quality degrades causing the system to switch to another PTP source, then with the above command, the SyncE selection also switches to the new PTP source, provided that the new interface has the same SyncE QL and priority as the previously selected interface.

Benefits of SyncE Preference for PTP Receiver Interface

- Enhanced Synchronization - Ensures that SyncE and PTP sources are traceable to the same clock source, preventing synchronization issues.
- Improved Reliability - Reduces the risk of PTP synchronization failures caused by rapid clock drifts.

- Simplified Configuration - Automates the selection process of SyncE sources to align with the PTP receiver, simplifying network management.

Restrictions for SyncE Preference for PTP Receiver Interface

SyncE auto-selection to the PTP-receiver interface happens only if the interface is part of the **show frequency synchronization selection** list of SyncE interfaces. If more than two SyncE interfaces are configured, it is possible that the PTP-receiver interface isn't part of the selection list, and auto-switching doesn't occur.

Configure SyncE Preference for PTP Receiver Interface

Enable SyncE preference for PTP Receiver Interface.

Procedure

Step 1 Enter the frequency synchronization mode.

Example:

```
Router#configure
Router(config)#frequency synchronization
```

Step 2 Configure SyncE to prefer the PTP receiver interface.

Example:

```
Router(config-freqsync)#synchronous-ethernet prefer-interface ptp-receiver
Router(config-freqsync)#commit
```

Step 3 Verify that SyncE is configured to prefer the PTP receiver interface.

Example:

```
Router#show ptp interfaces brief
```

Intf Name	Port Number	Port State	Encap	Line State	Mechanism
Te0/0/0/18	2	Passive	Ethernet	up	-
Te0/0/0/19	1	Slave	Ethernet	up	-

The **show ptp interfaces brief** command gives information about the ptp interfaces and then you can verify that the PTP receiver (Slave) interface is selected for frequency synchronization in **show frequency synchronization interfaces brief** command output.

```
Router#show frequency synchronization interfaces brief
```

```
Flags:  > - Up           D - Down           S - Assigned for selection
         d - SSM Disabled x - Peer timed out   i - Init state
         s - Output squelched

Fl  Interface          QLrcv  QLuse  Pri  QLsnd  Output driven by
====
>S  TenGigE0/0/0/18     PRC    PRC    100  DNU    TenGigE0/0/0/19
>S  TenGigE0/0/0/19     PRC    PRC    100  PRC    TenGigE0/0/0/19
```

Verifying the Frequency Synchronization Configuration

After performing the frequency synchronization configuration tasks, use this task to check for configuration errors and verify the configuration.

1. show frequency synchronization selection

```
RP/0/RP0/CPU0:R5# show frequency synchronization selection
Fri Apr 24 12:49:32.833 UTC
Node 0/RP1/CPU0:
=====
Selection point: T0-SEL-B (3 inputs, 1 selected)
  Last programmed 3d04h ago, and selection made 3d04h ago
  Next selection points
    SPA scoped      : None
    Node scoped     : CHASSIS-TOD-SEL
    Chassis scoped: LC_TX_SELECT
    Router scoped   : None
  Uses frequency selection
  Used for local line interface output
  S  Input                               Last Selection Point      QL  Pri  Status
  == =====
  4  HundredGigE0/7/0/0                 0/RP1/CPU0 ETH_RXMUX 4    PRC  10  Locked
      PTP [0/RP1/CPU0]                   n/a                       PRC  254 Available
      Internal0 [0/RP1/CPU0]              n/a                       SEC  255 Available

Selection point: 1588-SEL (2 inputs, 1 selected)
  Last programmed 3d04h ago, and selection made 3d04h ago
  Next selection points
    SPA scoped      : None
    Node scoped     : None
    Chassis scoped: None
    Router scoped   : None
  Uses frequency selection
  S  Input                               Last Selection Point      QL  Pri  Status
  == =====
  4  HundredGigE0/7/0/0                 0/RP1/CPU0 ETH_RXMUX 4    PRC  10  Locked
      Internal0 [0/RP1/CPU0]              n/a                       SEC  255 Available

Selection point: CHASSIS-TOD-SEL (2 inputs, 1 selected)
  Last programmed 3d04h ago, and selection made 3d04h ago
  Next selection points
    SPA scoped      : None
    Node scoped     : None
    Chassis scoped: None
    Router scoped   : None
  Uses time-of-day selection
  S  Input                               Last Selection Point      Pri  Time  Status
  == =====
  1  PTP [0/RP1/CPU0]                   n/a                       100  Yes   Available
      HundredGigE0/7/0/0                 0/RP1/CPU0 T0-SEL-B 4    100  No    Available

Selection point: ETH_RXMUX (1 inputs, 1 selected)
  Last programmed 3d04h ago, and selection made 3d04h ago
  Next selection points
    SPA scoped      : None
    Node scoped     : T0-SEL-B 1588-SEL
    Chassis scoped: None
    Router scoped   : None
  Uses frequency selection
  S  Input                               Last Selection Point      QL  Pri  Status
  == =====
```

```
4 HundredGigE0/7/0/0          n/a          PRC    10    Available
```

2. show frequency synchronization configuration-errors

```
RP/0/RP0/CPU0:router# show frequency synchronization configuration-errors
Node 0/2/CPU0:
=====
interface GigabitEthernet0/2/0/0 frequency synchronization
  * Frequency synchronization is enabled on this interface, but isn't enabled globally.
interface GigabitEthernet0/2/0/0 frequency synchronization quality transmit exact itu-t
  option 2 generation 1 PRS
  * The QL that is configured is from a different QL option set than is configured
globally.
```

Displays any errors that are caused by inconsistencies between shared-plane (global) and local-plane (interface) configurations. There are two possible errors that can be displayed:

- Frequency Synchronization is configured on an interface (line interface or clock-interface), but is not configured globally.
- The QL option configured on some interface does not match the global QL option. Under an interface (line interface or clock interface), the QL option is specified using the quality transmit and quality receive commands. The value specified must match the value configured in the global quality itu-t option command, or match the default (option 1) if the global quality itu-t option command is not configured.

Once all the errors have been resolved, meaning there is no output from the command, continue to the next step.

3. show frequency synchronization interfaces brief

```
RP/0/RP0/CPU0:R5# show frequency synchronization interfaces brief
Thu Feb 1 06:30:02.945 UTC
Flags: > - Up
      d - SSM Disabled
      s - Output squelched
Fl Interface
D - Down          S - Assigned for selection
x - Peer timed out i - Init state
Last Selection Point
Pri Time
Status

=====
>S TenGigE0/0/0/0          PRC    PRC    1 DNU    TenGigE0/0/0/0
>x TenGigE0/0/0/1          Fail   n/a    100 PRC    TenGigE0/0/0/0
>x TwentyFiveGigE0/0/0/30 Fail   n/a    100 PRC    TenGigE0/0/0/0

=====
```

```
RP/0/RP0/CPU0:R5#
```

Verifies the configuration. Note the following points:

- All line interface that have frequency synchronization configured are displayed.
- All clock interfaces and internal oscillators are displayed.
- Sources that have been nominated as inputs (in other words, have selection input configured) have 'S' in the Flags column; sources that have not been nominated as inputs do not have 'S' displayed.



Note Internal oscillators are always eligible as inputs.

- ‘>’ or ‘D’ is displayed in the flags field as appropriate.

If any of these items are not true, continue to the next step.

4. show processes fsyncmgr location node-id

This command verifies that the fsyncmgr process is running on the appropriate nodes.

```
RP/0/RP0/CPU0:R5# show processes fsyncmgr location 0/0/cPU0
Thu Feb 1 06:26:32.979 UTC
Job Id: 181
PID: HYPERLINK "tel:3411"3411
Process name: fsyncmgr
Executable path:
/opt/cisco/XR/packages/ncs560-iosxr-fwding-1.0.0.0-r63226I/all/bin/fsyncmgr Instance #:
1
Version ID: 00.00.0000
Respawn: ON
Respawn count: 1
Last started: Tue Jan 23 04:26:57 HYPERLINK "tel:2018"2018
Process state: Run
Package state: Normal
core: MAINMEM
Max. core: 0
Level: 100
Placement: None
startup_path:
/opt/cisco/XR/packages/ncs560-iosxr-fwding-1.0.0.0-r63226I/all/startup/fsyncmgr.startup
Ready: 2.063s
Process cpu time: 168.480 user, 129.980 kernel, 298.460 total
JID TID Stack pri state NAME rt_pri
181 HYPERLINK "tel:3411"3411 OK 20 Sleeping fsyncmgr 0
181 HYPERLINK "tel:3572"3572 OK 20 Sleeping lwm_debug_threa 0
181 HYPERLINK "tel:3573"3573 OK 20 Sleeping fsyncmgr 0
181 HYPERLINK "tel:3574"3574 OK 20 Sleeping lwm_service_thr 0
181 HYPERLINK "tel:3575"3575 OK 20 Sleeping qsm_service_thr 0
181 HYPERLINK "tel:3622"3622 OK 20 Sleeping fsyncmgr 0
181 HYPERLINK "tel:3781"3781 OK 20 Sleeping fsyncmgr 0
181 HYPERLINK "tel:3789"3789 OK 20 Sleeping fsyncmgr 0
```

Verifying the ESMC Configuration

show frequency synchronization interfaces

```
RP/0/RP0/CPU0:R5# show frequency synchronization interfaces
Thu Feb 1 06:33:26.575 UTC
Interface TenGigE0/0/0/0 (up)
Assigned as input for selection
Wait-to-restore time 0 minutes
SSM Enabled
Peer Up for 2d01h, last SSM received 0.320s ago
Peer has come up 1 times and timed out 0 times
ESMC SSMs Total Information Event DNU/DUS
Sent: HYPERLINK "tel:178479"178479 HYPERLINK "tel:178477"178477 2 HYPERLINK "tel:178463"178463
```

```

Received: HYPERLINK "tel:178499"178499 HYPERLINK "tel:178499"178499 0
0
Input:
Up
Last received QL: Opt-I/PRC
Effective QL: Opt-I/PRC, Priority: 1, Time-of-day Priority 100
Supports frequency
Output:
Selected source: TenGigE0/0/0/0
Selected source QL: Opt-I/PRC
Effective QL: DNU
Next selection points: ETH_RXMUX
Interface TenGigE0/0/0/1 (up)
Wait-to-restore time 5 minutes
SSM Enabled
Peer Timed Out for 2d01h, last SSM received never
Peer has come up 0 times and timed out 1 times
ESMC SSMs Total Information Event DNU/DUS
Sent: HYPERLINK "tel:178479"178479 HYPERLINK "tel:178477"178477 2 0
Received: 0 0 0 0
Input:
Down - not assigned for selection
Supports frequency
Output:
Selected source: TenGigE0/0/0/0
Selected source QL: Opt-I/PRC
Effective QL: Opt-I/PRC
Next selection points: ETH_RXMUX
Interface TwentyFiveGigE0/0/0/30 (up)
Wait-to-restore time 5 minutes
SSM Enabled
Peer Timed Out for 01:50:24, last SSM received 01:50:30 ago
Peer has come up 1 times and timed out 1 times
ESMC SSMs Total Information Event DNU/DUS
Sent: HYPERLINK "tel:75086"75086 HYPERLINK "tel:75085"75085 1 0
Received: HYPERLINK "tel:68457"68457 HYPERLINK "tel:68455"68455 2 HYPERLINK "tel:68443"68443
Input:
Down - not assigned for selection
Supports frequency
Output:
Selected source: TenGigE0/0/0/0
Selected source QL: Opt-I/PRC
Effective QL: Opt-I/PRC
Next selection points: ETH_RXMUX

```

Verifying Synchronous Ethernet LEDs

```

RP/0/RP0/CPU0:ios# show led
Mon Nov 2 09:29:34.637 UTC
=====
Location LED Name Mode Color
=====
0/FT0
Status OPERATIONAL GREEN
0/RP0/CPU0
Alarm OPERATIONAL AMBER
Status OPERATIONAL GREEN
Sync OPERATIONAL AMBER

```



CHAPTER 3

Understanding PTP

The Precision Time Protocol (PTP), as defined in the IEEE 1588 standard, synchronizes withnanosecond accuracy the real-time clocks of the devices in a network. The clocks in are organized into a server-client hierarchy. PTP identifies the port that is connected to a device with the most precise clock. This clock is referred to as the server clock. All the other devices on the network synchronize their clocks with the server clock and are referred to as members. Constantly-exchanged timing messages ensure continued synchronization.

Precision Time Protocol (PTP) is defined in IEEE 1588 as Precision Clock Synchronization for Networked Measurements and Control Systems, and was developed to synchronize the clocks in packet-based networks that include distributed device clocks of varying precision and stability. PTP is designed specifically for industrial, networked measurement and control systems, and is optimal for use in distributed systems because it requires minimal bandwidth and little processing overhead.

Table 3: Nodes within a PTP Network

Network Element	Description
Grandmaster (GM)	A network device physically attached to the primary time source. All clocks are synchronized to the grandmaster clock.
Ordinary Clock (OC)	An ordinary clock is a 1588 clock with a single PTP port that can operate in one of the following modes: <ul style="list-style-type: none">• Server mode—Distributes timing information over the network to one or more client clocks, thus allowing the client to synchronize its clock to the server clock.• Client mode—Synchronizes its clock to a server clock. You can enable the client mode on up to two interfaces simultaneously in order to connect to two different server clocks.

Network Element	Description
Boundary Clock (BC)	<p>The device participates in selecting the best server clock and can act as the server clock if no better clocks are detected.</p> <p>Boundary clock starts its own PTP session with a number of downstream clients. The boundary clock mitigates the number of network hops and results in packet delay variations in the packet network between the Grandmaster and client.</p>
Transparent Clock (TC)	A transparent clock is a device or a switch that calculates the time it requires to forward traffic and updates the PTP time correction field to account for the delay, making the device transparent in terms of time calculations.

- [Why PTP?, on page 14](#)
- [Routers and Delays, on page 15](#)
- [Message-Based Synchronization, on page 15](#)
- [PTP Event Message Sequences, on page 15](#)
- [PTP Clocks, on page 17](#)
- [Restrictions for PTP, on page 17](#)
- [PTP Phase Difference Threshold Between Passive and Secondary Ports, on page 18](#)
- [Isolate Foreign Masters Causing Packet Timing Signal Fail, on page 20](#)
- [PTP Profiles, on page 21](#)
- [Slow Tracking, on page 30](#)
- [PTP Holdover Traceability Suppression, on page 31](#)
- [IEEE Default Profile, on page 32](#)
- [PTP Hybrid Mode, on page 33](#)
- [Verifying the PTP Hybrid Mode Configurations, on page 35](#)
- [Configure PTP Delay Asymmetry, on page 36](#)
- [Performance Monitoring for PTP Networks, on page 38](#)

Why PTP?

Smart grid power automation applications, such as peak-hour billing, virtual power generators, and outage monitoring and management, require extremely precise time accuracy and stability. Timing precision improves network monitoring accuracy and troubleshooting ability.

In addition to providing time accuracy and synchronization, the PTP message-based protocol can be implemented on packet-based networks, such as Ethernet networks. The benefits of using PTP in an Ethernet network include:

- Low cost and easy setup in existing Ethernet networks
- Limited bandwidth requirement for PTP data packets

Routers and Delays

In an IP network, routers provide a full-duplex communication path between network devices. Routers send data packets to packet destinations using IP address information contained in the packets. When the router attempts to send multiple packets simultaneously, the router buffers some packets so that they are not lost before they are sent. When the buffer is full, the router delays sending packets. This delay can cause device clocks on the network to lose synchronization with one another.

Additional delays can occur when packets entering a router are stored in its local memory while the router searches the address table to verify packet fields. This process causes variations in packet forwarding time latency, and these variations can result in asymmetrical packet delay times.

Adding PTP to a network can compensate for these latency and delay problems by correctly adjusting device clocks so that they stay synchronized with one another. PTP enables network routers to function as PTP devices, including boundary clocks (BCs) and transparent clocks (TCs).

For more information about PTP clock devices and their role in a PTP network, see the *PTP Clocks* section.

Message-Based Synchronization

To ensure clock synchronization, PTP requires an accurate measurement of the communication path delay between the time source (server) and the receiver (client). PTP sends messages between the server and client device to determine the delay measurement. Then, PTP measures the exact message transmit and receive times and uses these times to calculate the communication path delay.

PTP then adjusts current time information contained in network data for the calculated delay, resulting in more accurate time information.

This delay measurement principle determines path delay between devices on the network. The local clocks are adjusted for this delay using a series of messages sent between servers and clients. The one-way delay time is calculated by averaging the path delay of the transmit and receive messages. This calculation assumes a symmetrical communication path; however, routed networks do not necessarily have symmetrical communication paths, due to the various asymmetries in the network.

Using transparent clocks, PTP provides a method to measure and account for the delay in a time-interval field in network timing packets. This makes the routers temporarily transparent to the server and client nodes on the network. An end-to-end transparent clock forwards all messages on the network in the same way that a router does.

To read a detailed description of synchronization messages, see the *PTP Event Message Sequences* section. To learn more about how transparent clocks calculate network delays, refer to [Transparent Clock, on page 7](#).

PTP Event Message Sequences

This section describes the PTP event message sequences that occur during synchronization.

Synchronizing with Boundary Clocks

The ordinary and boundary clocks configured for the delay request-response mechanism use the following event messages to generate and communicate timing information:

- Sync
- Delay_Req
- Follow_Up
- Delay_Resp

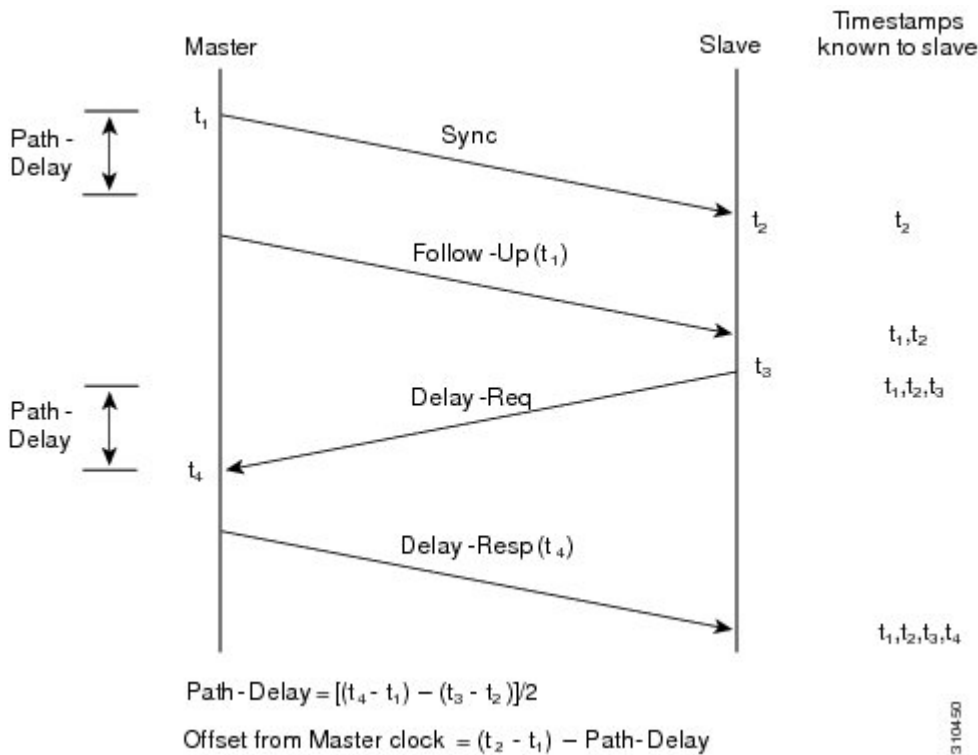
These messages are sent in the following sequence:

- The server sends a Sync message to the client and notes the time (t_1) at which it was sent.
- The client receives the Sync message and notes the time of reception (t_2).
- The server conveys to the client the timestamp t_1 by embedding the timestamp t_1 in a Follow_Up message.
- The client sends a Delay_Req message to the server and notes the time (t_3) at which it was sent.
- The server receives the Delay_Req message and notes the time of reception (t_4).
- The server conveys to the client the timestamp t_4 by embedding it in a Delay_Resp message.

After this sequence, the client possesses all four timestamps. These timestamps can be used to compute the offset of the client clock relative to the server, and the mean propagation time of messages between the two clocks.

The offset calculation is based on the assumption that the time for the message to propagate from server to client is the same as the time required from client to server. This assumption is not always valid on an Ethernet/IP network due to asymmetrical packet delay times.

Figure 1: Detailed Steps—Boundary Clock Synchronization



Synchronizing the Local Clock

In an ideal PTP network, the server and client clock operate at the same frequency. However, drift can occur on the network. Drift is the frequency difference between the server and client clock. You can compensate for drift by using the time stamp information in the device hardware and follow-up messages (intercepted by the router) to adjust the frequency of the local clock to match the frequency of the server clock.

PTP Clocks

A PTP network is made up of PTP-enabled devices and devices that are not using PTP. The PTP-enabled devices typically consist of the following clock types.

Grandmaster Clock

Within a PTP domain, the grandmaster clock is the primary source of time for clock synchronization using PTP. The grandmaster clock usually has a very precise time source, such as a GPS or atomic clock. When the network does not require any external time reference and only needs to be synchronized internally, the grandmaster clock can free run.

Ordinary Clock

An ordinary clock is a PTP clock with a single PTP port. It functions as a node in a PTP network and can be selected by the BMCA as a server or client within a subdomain. Ordinary clocks are the most common clock type on a PTP network because they are used as end nodes on a network that is connected to devices requiring synchronization. Ordinary clocks have various interfaces to external devices.

Boundary Clock

A boundary clock in a PTP network operates in place of a standard network router. Boundary clocks have more than one PTP port, and each port provides access to a separate PTP communication path. Boundary clocks provide an interface between PTP domains. They intercept and process all PTP messages, and pass all other network traffic. The boundary clock uses the BMCA to select the best clock seen by any port. The selected port is then set as a client. The server port synchronizes the clocks connected downstream, while the client port synchronizes with the upstream server clock.

Transparent Clock

The role of transparent clocks in a PTP network is to update the time-interval field that is part of the PTP event message. This update compensates for switch delay and has an accuracy of within one picosecond.

Restrictions for PTP

PTP over MPLS is not supported.

PTP Phase Difference Threshold Between Passive and Secondary Ports

Table 4: Feature History Table

Feature Name	Release Information	Feature Description
PTP Phase Difference Threshold Between Passive and Secondary Ports	Release 24.2.1	<p>Passive ports can now be included in the Delay Request-Response Mechanism (DRRM), which allows for the monitoring of PTP phase differences between a passive port and a secondary port. If these PTP phase differences surpass a predefined limit, system logs are triggered. This feature enables you to detect potential errors such as fiber asymmetry or a clock failure in the PTP network.</p> <p>This feature introduces these changes:</p> <p>CLI:</p> <ul style="list-style-type: none"> • phase-difference-threshold-breach • The show ptp foreign-masters command output is enhanced to include phase difference values and servo status. <p>YANG Data Models:</p> <p>The following data models are enhanced:</p> <ul style="list-style-type: none"> • <code>Cisco-IOS-XR-ptp-cfg.yang</code> • <code>Cisco-IOS-XR-um-ptp-cfg.yang</code>

The Precision Time Protocol (PTP), as defined in the IEEE 1588 standard, is designed for precise time synchronization across networked devices. It operates by having Foreign Masters (FMs) broadcast timing information to interfaces within the network. The selection of the Grandmaster (GM), the primary reference clock, is determined by the Best Master Clock Algorithm (BMCA). Devices synchronize their clocks to the GM through a process known as the Delay Request-Response Mechanism (DRRM), wherein ports that are directly synchronizing with the GM enter a secondary state.

Historically, ports in a passive state—those that receive timing messages from FMs but aren't used for synchronization to the GM were not monitored by the router. Starting with Cisco IOS XR Software Release 24.2.1, these passive ports are enabled for the calculation of PTP phase differences between the FMs on passive ports and the GM.

This calculated PTP phase difference provides a valuable insight into the timing characteristics of other foreign masters in the network by using the grandmaster as a reference point. It can be utilized on any boundary clock or slave clock that has connections to at least one other foreign master.

You can access these measurements and the calculated PTP phase differences using show commands through the router's CLI. Also, the information can be retrieved programmatically through operational data models in YANG, providing flexibility in how you can access and utilize this synchronization data.

Phase Difference Alarm

PTP phase difference can also be used to monitor the timing properties of the network. You can configure a value at which a bistate alarm is triggered when the PTP phase difference of a FM exceeds the threshold. The PTP phase difference can have a negative or positive value, but the threshold can only be the absolute value. You can configure the PTP phase difference threshold using the **phase-difference-threshold-breach** command.

System Log for PTP Phase Difference

When the configured threshold is reached, system logs (syslogs) are displayed. The following syslog is triggered if the configured PTP phase difference threshold is passed through by any master.

```
Phase difference for clock ACDE48FFFE234567, steps removed 1, receiving-port 1, received  
on interface GigabitEthernet0/2/0/3 is 40ns, configured threshold is 30ns. Raising phase  
difference alarm.
```

Isolate Foreign Masters Causing Packet Timing Signal Fail

Table 5: Feature History Table

Feature Name	Release Information	Feature Description
Isolate Foreign Masters Causing Packet Timing Signal Fail	Release 24.2.1	<p>This feature permits the flexible selection of timing sources by filtering out Foreign Master (FM) clocks that exhibit unstable timing. This filtering causes the secondary clocks to produce a signal deemed Packet Timing Signal Fail (PTSF)-unusable, from consideration within the Best Master Clock Algorithm (BMCA). The system continuously monitors these clocks for timing stabilization, and upon detecting enhanced stability, it may reevaluate and possibly reintegrate them as suitable time sources.</p> <p>This feature introduces these changes:</p> <p>CLI:</p> <ul style="list-style-type: none"> • detect-ptsf-unusable • The show ptp foreign-masters command output is enhanced to include phase difference values and servo status. <p>YANG Data Models:</p> <p>The following data models are enhanced:</p> <ul style="list-style-type: none"> • <code>Cisco-IOS-XR-ptp-cfg.yang</code> • <code>Cisco-IOS-XR-um-ptp-cfg.yang</code>

Starting Cisco IOS XR Software Release 24.2.1, the servo mechanism now has the ability to detect unusable clocks due to packet timing signal fail by analyzing timestamps from foreign masters. This enhancement allows the system to identify foreign masters with unstable timing as unsuitable for use. A platform supports multiple masters, such a master can be excluded from the BMCA selection process while remaining under observation for potential recovery. Even after a master is deemed unusable, the DRRM continues to operate and timestamps from it are still provided to the servo. This ongoing monitoring enables PTP to detect and respond to any improvements in the primary's timing, allowing it to be reconsidered as usable.

System Log for PTSF-unusable

When the master becomes PTSF-unusable, and if its the current Grandmaster, the following system log (syslogs) is displayed:

```
Foreign master with clock ID ACDE48FFFE234567, steps removed 1, receiving-port 1, received  
on interface GigabitEthernet0/2/0/4 is now PTSF-unusable and disqualified from selection.
```

PTP Profiles

ITU-T Telecom Profiles for PTP

Cisco IOS XR software supports ITU-T Telecom Profiles for PTP as defined in the ITU-T recommendation. A profile consists of PTP configuration options applicable only to a specific application.

Separate profiles can be defined to incorporate PTP in different scenarios based on the IEEE 1588-2008 standard. A telecom profile differs in several ways from the default behavior defined in the IEEE 1588-2008 standard and the key differences are mentioned in the subsequent sections.

The following sections describe the ITU-T Telecom Profiles that are supported for PTP.

G.8265.1

G.8265.1 profile fulfills specific frequency-distribution requirements in telecom networks. Features of G.8265.1 profile are:

- Clock advertisement: G.8265.1 profile specifies changes to values used in Announce messages for advertising PTP clocks. The clock class value is used to advertise the quality level of the clock, while the other values are not used.
- Clock Selection: G.8265.1 profile also defines an alternate BMCA to select port states and clocks is defined for the profile. This profile also requires to receive Sync messages (and optionally, Delay-Response messages) to qualify a clock for selection.
- Port State Decision: The ports are statically configured to be Server or Client instead of using FSM to dynamically set port states.
- Packet Rates: The packet rates higher than rates specified in the IEEE 1588-2008 standard are used. They are:
 - Sync/Follow-Up Packets: Rates from 128 packets-per-second to 16 seconds-per-packet.
 - Delay-Request/Delay-Response Packets: Rates from 128 packets-per-second to 16 seconds-per-packet.
 - Announce Packets: Rates from 8 packets-per-second to 64 packets-per-second.
- Transport Mechanism: G.8265.1 profile only supports IPv4 PTP transport mechanism.
- Mode: G.8265.1 profile supports transport of data packets only in unicast mode.
- Clock Type: G.8265.1 profile only supports Ordinary Clock-type (a clock with only one PTP port).
- Domain Numbers: The domain numbers that can be used in a G.8265.1 profile network ranges from 4 to 23. The default domain number is 4.

- Port Numbers: Multiple ports can be configured; however, all ports must be of the same type, either Server or Client.



Note The G.8265.1 profile is not supported in this release.

G.8275.1

G.8275.1 profile fulfills the time-of-day and phase synchronization requirements in telecom networks with all network devices participating in the PTP protocol. G.8275.1 profile with SyncE provides better frequency stability for the time-of-day and phase synchronization.

Features of G.8275.1 profile are:

- Synchronization Model: G.8275.1 profile adopts hop-by-hop synchronization model. Each network device in the path from Server to Client clock synchronizes its local clock to upstream devices and provides synchronization to downstream devices.
- Clock Selection: G.8275.1 profile also defines an alternate BMCA that selects a clock for synchronization and port state for the local ports of all devices in the network is defined for the profile. The parameters defined as a part of the BMCA are:
 - Clock Class
 - Clock Accuracy
 - Offset Scaled Log Variance
 - Priority 2
 - Clock Identity
 - Steps Removed
 - Port Identity
 - notSlave flag
 - Local Priority
- Port State Decision: The port states are selected based on the alternate BMCA algorithm. A port is configured to a server-only port state to enforce the port to be a server for multicast transport mode.
- Packet Rates: The nominal packet rate for Announce packets is 8 packets-per-second and 16 packets-per-second for Sync/Follow-Up and Delay-Request/Delay-Response packets.
- Transport Mechanism: G.8275.1 profile only supports Ethernet PTP transport mechanism.
- Mode: G.8275.1 profile supports transport of data packets only in multicast mode. The forwarding is done based on forwardable or non-forwardable multicast MAC address.
- Clock Type: G.8275.1 profile supports the following clock types:
 - Telecom Grandmaster (T-GM)
 - Telecom Time subordinate/client Clock (T-TSC)

- Telecom Boundary Clock (T-BC)
- Domain Numbers: The domain numbers that can be used in a G.8275.1 profile network ranges from 24 to 43. The default domain number is 24.

The G.8275.1 supports the following:

- T-GM: The telecom grandmaster (T-GM) provides timing to all other devices on the network. It does not synchronize its local clock with any other network element other than the Primary Reference Time Clock (PRTC).
- T-BC: The telecom boundary clock (T-BC) synchronizes its local clock to a T-GM or an upstream T-BC, and provides timing information to downstream T-BCs or T-TSCs. If at a given point in time there are no higher-quality clocks available, T-BC continues to provide its own timing information to its peers, although derived clock is not as accurate as the T-GM.
- T-TSC: The telecom time subordinate/client clock (T-TSC) synchronizes its local clock to another PTP clock (in most cases, the T-BC), and does not provide synchronization through PTP to any other device.

Performance Requirements

The router is compliant with Class B performance requirements for T-TSC and T-BC as documented in G.8273.2.

G.8275.2

The G.8275.2 is a PTP profile for use in telecom networks where phase or time-of-day synchronization is required. It differs from G.8275.1 in that it is not required that each device in the network participates in the PTP protocol. Also, G.8275.2 uses PTP over IPv4 in unicast mode.

The G.8275.2 profile is based on the partial timing support from the network. Hence nodes using G.8275.2 are not required to be directly connected.

The G.8275.2 profile is used in mobile cellular systems that require accurate synchronization of time and phase. For example, the fourth generation (4G) of mobile telecommunications technology.

Features of G.8275.2 profile are:

- Clock Selection: G.8275.2 profile also defines an alternate BMCA that selects a clock for synchronization and port state for the local ports of all devices in the network is defined for the profile. The parameters defined as a part of the BMCA are:
 - Clock Class
 - Clock Accuracy
 - Offset Scaled Log Variance
 - Priority 2
 - Clock Identity
 - Steps Removed
 - Port Identity
 - notSlave flag
 - Local Priority



Note See ITU-T G.8275.2 document to determine the valid values for Clock Class parameter.

- Port State Decision: The port states are selected based on the alternate BMCA algorithm. A port can be configured as "server-only", "client-only", or "any" mode.
- Packet Rates:
 - Synchronization/Follow-Up—minimum is one packet-per-second and maximum of 128 packets-per-second.
 - Packet rate for Announce packets—minimum of one packet-per-second and maximum of eight packets-per-second.
 - Delay-Request/Delay-Response packets—minimum is one packet-per-second and maximum of 128 packets-per-second.
- Transport Mechanism: G.8275.2 profile supports only IPv4 PTP transport mechanism.
- Mode: G.8275.2 profile supports transport of data packets only in unicast mode.
- Clock Type: G.8275.2 profile supports the following clock types:
 - Telecom Grandmaster (T-GM): Provides timing for other network devices and does not synchronize its local clock to other network devices. However, T-GM can be connected to a GPS or GNSS for deriving better clock information.
 - Telecom Time Subordinate/Client Clock (T-TSC) and Partial-Support Telecom Time Subordinate/Client Clocks (T-TSC-P): A client clock synchronizes its local clock to another PTP clock, but does not provide PTP synchronization to any other network devices.
 - Telecom Boundary Clock (T-BC) and Partial-Support Telecom Boundary Clocks (T-BC-P): Synchronizes its local clock to a T-GM or an upstream T-BC clock and provides timing information to downstream T-BC or T-TSC clocks.
- Domain Numbers: The domain numbers that can be used in a G.8275.2 profile network ranges from 44 to 63. The default domain number is 44.

PTP Virtual Port

Feature Name	Release Information	Feature Description
PTP Virtual Port Support for Cisco NCS 560 routers	Release 7.9.1	<p>You can now select the best available timing source for your routers by using the PTP Virtual Port feature.</p> <p>This feature allows you to compare, select, and advertise the best clock source between a PTP server and other local timing sources connected to the routers.</p> <p>Virtual Port is an external frequency, phase, and time input interface on a Telecom Boundary Clock (T-BC), and thus participates in the timing source selection.</p>

G.8275.1 introduces the concept of a virtual port on the T-BC. A virtual port is an external frequency, phase, and time input interface on a T-BC, which can participate in the source selection.

Limitations

- Assisted Partial Timing Support (APTS) is supported only for the G8275.2 non hybrid mode.
- Virtual port is supported for G8275.1 and G8275.2 in hybrid and non-hybrid modes.
- Virtual port configuration is not allowed under Ordinary Clocks.
- Virtual port cannot be configured if the time of day (ToD) priority is not set under the global PTP configuration mode. Use the **time-of-day priority** command to set the ToD.

Assisted Partial Timing Support

Table 6: Feature History Table

Feature Name	Release Information	Description
Assisted Partial Timing Support on this routers	Release 7.9.1	<p>Assisted Partial Timing Support (APTS) enables you to select timing and synchronization for mobile backhaul networks.</p> <p>APTS allows for proper distribution of phase and time synchronization in the network.</p>

In a network having GNSS or GPS reference, all nodes (or secondary clocks) at the edge of the network follow the GNSS primary clock that runs at the core. When GNSS or GPS reference fails at the core, the secondary clocks running at the edge no longer receive accurate time stamps from the primary clock.

With the use of APTS, the nodes at the edge of the network identify GNSS or GPS as primary clock source, and PTP as the secondary source. So even if the GNSS reference is lost, the nodes fall back to the backup PTP session running between the primary clock at core and the nodes at the edge, and are thereby able to maintain an accurate time stamp.

Configuring the G.8275.1 Profile



Note The Sync 2 port and GNSS receiver configuration listed below are not supported simultaneously for network synchronization. Choose only one synchronization method at a time.

Configuring the Global Settings: Example

```
ptp
clock
  domain 24
  profile g.8275.1 clock-type [T-BC | TGM | TTSC]
!
profile profile1
  transport ethernet
  sync frequency 16
  announce frequency 8
  delay-request frequency 16
!
profile profile2
  transport ethernet
  sync frequency 16
  announce frequency 8
  delay-request frequency 16
!
!
  physical-layer-frequency
!
```

Configuring Client Port: Example

```
interface GigabitEthernet0/0/0/3
 ptp
  profile profile1
  multicast target-address ethernet 01-1B-19-00-00-00
  transport ethernet
  port state slave-only
  local-priority 10
!
  frequency synchronization
  selection input
  priority 1
  wait-to-restore 0
!
```

Configuring Server Port: Example

```
interface GigabitEthernet0/0/0/1
 ptp
  profile profile2
  multicast target-address ethernet 01-1B-19-00-00-00
  port state master-only
  transport ethernet
  sync frequency 16
```



```

announce frequency 8
delay-request frequency 16
!
frequency synchronization
!
!
```

Multiple PTP profile interoperability

Multiple PTP profile interoperability is a clock synchronization method that allows a Cisco router to run a profile while you configure an interface to synchronize with a peer clock running a different profile.

Table 7: Feature History Table

Feature Name	Release Information	Feature Description
PTP profile interoperation	Release 25.2.1	PTP profile interoperability is now extended to the A900-IMA8CS1Z-M NCS 560 router variant.
PTP profile interoperation	Release 7.5.1	<p>PTP profile interoperation enables users to deploy newer profiles in a network containing older devices that do not support these profiles. This support allows for a gradual upgrade path.</p> <p>This feature is supported on these NCS 560 router variants:</p> <ul style="list-style-type: none"> • N560-IMA1W • N560-IMA-8Q/4L <p>For this release, interoperation is supported only between the G.8275.1 and G.8275.2 profiles.</p>

Restrictions and guidelines for multiple PTP profile interoperability

To effectively configure and manage PTP profile interoperability, it is essential to understand the specific restrictions and guidelines that govern the process. These elements ensure accurate clock synchronization and seamless operation across different profiles.

Restrictions

To ensure proper configuration and operation, these restrictions must be observed:

- Peer clock profile specification: Specify the profile of the peer clock; if not specified, the local clock's profile is used.
- Domain number specification: Use the domain number of the peer clock; if not specified, the local clock's domain number is used. Drop incoming PTP messages with a different domain number.

- Priority values mapping: Apply the default mapping for Priority1 and Priority2 values if not specified.
- Clock accuracy mapping: Apply the default mapping for **ClockAccuracy** value if not specified.
- Offset scaled log variance mapping: Apply the default mapping for **OffsetScaledLogVariance** value if not specified.

Guidelines

To ensure that accurate attributes of a clock are applied to define its behavior, these guidelines must be followed:

- Ingress-conversion behavior: Convert clock properties received in incoming **Announce** messages using Ingress-Conversion behavior.
- Clock-class mappings: Override default mappings with any number of **Clock-Class-Mappings** whenever present.
- Clock-class default value usage: Use **Clock-Class-Default** value for all clock class values without a more specific mapping.
- Egress-conversion behavior: Convert clock properties sent in outgoing **Announce** messages using Egress-Conversion behavior, with options such as Ingress-Conversion.

How multiple PTP profile interoperation works

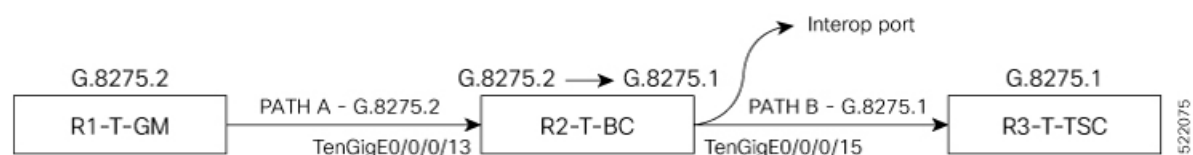
Summary

The key components that are involved in the process are:

- R1: Acts as the grandmaster clock.
- R2: Acts as a boundary clock.
- R3: Acts as the timeReceiver or ordinary clock.

Workflow

Figure 2: PTP profile interoperation



These stages describe how multiple PTP profile interoperation works.

1. R1 runs the G.8275.2 profile and sends synchronization information to R2.
2. R2 initially runs the G.8275.2 profile. The egress interface of R2 is configured with the **interop** command. The egress interface converts the profile from G.8275.2 to G.8275.1 before sending it to R3.
3. R3 receives the synchronization information from R2 and synchronizes its clock.

Result

This setup ensures that R2 can interoperate between different PTP profiles, converting the synchronization data from one profile to another as needed.

Configure multiple PTP profile interoperability

The purpose of this task is to configure multiple PTP profile interoperability. Use [Figure: PTP profile interoperation](#) to configure these steps. We have used interface TenGigE0/0/0/15 to configure the interoperability.

Follow these steps to configure multiple PTP profile interoperability.

Procedure

-
- Step 1** Enter the **interop** command to configure the egress interface for multiple PTP profile interoperability.
- ```
R2(config)#interface TenGigE0/0/0/15
R2(config-if)#ptp
R2(config-if-ptp)#interop
```
- Step 2** Enter the **profile** *<profile number>* command to configure the PTP profile to be used on this interface.
- ```
R2(config-if-ptp-interop)#profile g.8275.1
```
- Step 3** Enter the **domain** *<domain number>* command to configure the domain of the peer clock.
- ```
R2(config-if-ptp-interop)#domain 24
```
- Figure 3:**
- Step 4** Enter the **ptp multicast target-address ethernet** *<forwarding MAC address>* command to specify the Ethernet multicast group address to send multicast messages.
- ```
R2(config-if)#ptp multicast target-address ethernet 01-1B-19-00-00-00
```
- Step 5** Enter the **transport ethernet** command to configure the transport type as Ethernet in the PTP profile.
- ```
R2(config-ptp-profile)#transport ethernet
```
- Step 6** Enter the **port state master-only** command to configure the PTP port to operate exclusively as a timeTransmitter.
- ```
R2(config-if-ptp)#port state master-only
```
- The port will only send PTP timing information to downstream devices.
- Step 7** Enter these commands to configure frequency synchronization.
- ```
R2(config-if-ptp)#sync frequency 64
R2(config-if-ptp)#clock operation one-step
R2(config-if-ptp)#announce interval 1
R2(config-if-ptp)#delay-request frequency 32
R2(config-if-ptp)#frequency synchronization
```
- Step 8** Run the **show ptp interop** command to view the egress profile conversion.
- ```
R2#show ptp interop
Sat Jul 3 17:28:53.477 UTC
```

```

Interface TenGigE0/0/0/15

Egress Conversions:
  Profile:                G.8275.2 -> G.8275.1
  Domain:                 44 -> 24
  Priority1:              128 -> 128
  Priority2:              128 -> 128
  ClockClass:             6 -> 6
  ClockAccuracy:          0x21 -> 0x21
  OffsetScaledLogVariance: 0x4e5d -> 0x4e5d

Ingress Conversions:
  This port is not receiving Announce messages

```

Configuring Virtual Port

Effective Cisco IOS XR Release 7.4.1, you can configure virtual port on the G8275.1 and G8275.2 profiles in hybrid and non-hybrid modes.

For virtual port configuration to work, GNSS or Sync2 must be configured.

```

ptp
clock
domain 44
profile g.8275.2 clock-type T-BC
!
profile profile1
transport ipv4
sync frequency 64
clock operation one-step
announce frequency 8
delay-request frequency 64
!
virtual-port
offset-scaled-log-variance 20061
priority2 128
clock-class 6
clock-accuracy 33
local-priority 127
!
frequency priority 254
time-of-day priority 90    <<--time-of-day priority is a required parameter if you want
to configure virtual port-->>
log

```

Slow Tracking

Under normal configured conditions, any change in offset triggers an immediate reaction in the servo. With the Slow Tracking feature enabled, the servo corrects the phase offset based on the configured value. If the phase offset exceeds the acceptable range, servo goes into Holdover state. In such a condition, the Slow Tracking feature becomes inactive and the servo corrects itself to the latest offset and goes into Phase locked state. Slow Tracking becomes active again.

**Note**

- The supported slow tracking rate range is from 8-894 nanoseconds per second and must be in multiples of 8.
- This feature is active only when servo is in Phase locked mode.

```
Router:# config
ptp
clock
domain 24
profile g.8275.1 clock-type T-BC
!
profile profile1
multicast target-address ethernet 01-1B-19-00-00-00
transport ethernet
sync frequency 16
clock operation one-step
announce frequency 8
delay-request frequency 16
!
physical-layer-frequency
servo-slow-tracking 16
!
```

PTP Holdover Traceability Suppression

Table 8: Feature History Table

Feature Name	Release Information	Feature Description
PTP Holdover Traceability Suppression	Release 7.4.1	When a device which is configured as a Boundary clock (T-BC) loses synchronization with a quality Primary clock, to ensure that the downstream nodes continue to receive the configured clock class for a specified duration, and it's traceable you can configure this feature.

When the device loses synchronization with a quality Primary clock, to ensure that the downstream nodes continue to receive the configured clock class, and it's traceable you can configure this feature.

This feature enables the device which is configured as a boundary clock (T-BC) with PTP Profiles G.8275.1 or G.8275.2 to send out the configured clock-class as holdover clock-class and the time traceability flag to be set as TRUE for the specified duration. This is to ensure the down-stream nodes do not have an impact as this is a deviation from prescribed G.8275.1 ITU-T standards.

**Note**

- There are PTP flaps during switchovers or ISSU as the PTP holdover timer is running on the active RSP.
- Once the configured holdover override duration has lapsed and the device is unable to receive a quality Primary clock within this duration, the device sends the prescribed default clock class of 165, and the traceability flag will be set as FALSE to advertise loss of clock to downstream nodes.

Configuring PTP Holdover traceability suppression

This section describes how to configure the PTP holdover traceability suppression feature:

```
Router# config
Router(config)# ptp
Router(config-ptp)# holdover-spec-duration 1000
Router(config-ptp)# holdover-spec-clock-class 135
Router(config-ptp)# uncalibrated-traceable-override
Router(config-ptp)# holdover-spec-traceable-override
```

IEEE Default Profile

The IEEE 1588 standard defines one profile, the default profile A telecom profile defines:

- Restrictions on network technology
- Required PTP options
- Allowed PTP options
- Forbidden PTP options

The IEEE 1588 Default Profile can be configured only over IP and MPLS networks.

The Default Profile requires the following PTP options:

- The standard BMCA, with both priority fields set to 128.
- All management messages implemented
- Domain number zero

**Note**

Under the default profile, only hybrid boundary clock is supported in Cisco IOS XR Release 6.3.2.

Example: Hybrid Default Profile

Global PTP Configuration:

```
ptp
 clock
  domain 0
 exit
```

```

profile slave
  transport ipv4
  sync frequency 32
  announce frequency 2
  delay-request frequency 32
exit
profile master
  transport ipv4
exit
uncalibrated-clock-class 255 unless-from-holdover
freerun-clock-class 255
startup-clock-class 255
physical-layer-frequency <-- This is a mandatory command -->
exit

```

PTP Hybrid Mode

Your router allows the ability to select separate sources for frequency and time-of-day (ToD). Frequency selection can be between any source of frequency available to the router, such as: GPS, SyncE or IEEE 1588 PTP. The ToD selection is between the source selected for frequency and PTP, if available (ToD selection is from GPS or PTP). This is known as hybrid mode, where a physical frequency source (SyncE) is used to provide frequency synchronization, while PTP is used to provide ToD synchronization.

Frequency selection uses the algorithm described in ITU-T recommendation G.781, and is described in the Configuring Frequency Synchronization module in this document. The ToD selection is controlled using the time-of-day priority configuration. This configuration is found under the source interface frequency synchronization configuration mode and under the global PTP configuration mode. It controls the order for which sources are selected for ToD. Values in the range of 1 to 254 are allowed, with lower numbers.

Configuring PTP Hybrid Mode



Note You must configure the PTP hybrid mode when using the G.8275.1 PTP profile.

Configure hybrid mode by selecting PTP for the time-of-day (ToD) and another source for the frequency. This task summarizes the hybrid configuration. See the other PTP configuration modules for more detailed information regarding the PTP configurations. For more information on SyncE configurations, see the *Configuring Ethernet Interfaces* section in the *Interface and Hardware Component Configuration Guide for Cisco NCS 560 Series Routers*.

To configure PTP Hybrid mode:

1. Configure Global Frequency Synchronization

```

RP/0/RP0/CPU0:router(config)# frequency synchronization
RP/0/RP0/CPU0:router(config)# commit
RP/0/RP0/CPU0:router(config)# quality itu-t option [1 | 2]

```

2. Configure Frequency Synchronization in Interface.

```

RP/0/RP0/CPU0:router(config)# interface GigabitEthernet 0/0/0/0
RP/0/RP0/CPU0:router(config-if)# frequency synchronization
RP/0/RP0/CPU0:router(config-if-freqsync)# selection input
RP/0/RP0/CPU0:router(config-if-freqsync)# time-of-day-priority 100
RP/0/RP0/CPU0:router(config-if-freqsync)# commit

```

3. Configure Global PTP

```
RP/0/RP0/CPU0:router(config)# ptp
RP/0/RP0/CPU0:router(config-ptp)# time-of-day priority 1
RP/0/RP0/CPU0:router(config)# commit
```

4. Configure Client Port

```
RP/0/RP0/CPU0:router(config)# interface GigabitEthernet0/0/0/2
RP/0/RP0/CPU0:router(config-if)# ptp
RP/0/RP0/CPU0:router(config-if)# profile slave
RP/0/RP0/CPU0:router(config-if)# multicast target-address ethernet 01-1B-19-00-00-00
RP/0/RP0/CPU0:router(config-if)# transport ethernet sync frequency 16
RP/0/RP0/CPU0:router(config-if)# announce frequency 8
RP/0/RP0/CPU0:router(config-if)# delay-request frequency 16
RP/0/RP0/CPU0:router(config-if)# frequency synchronization
RP/0/RP0/CPU0:router(config-if-freqsync)# selection input
RP/0/RP0/CPU0:router(config-if-freqsync)# priority 1
RP/0/RP0/CPU0:router(config-if-freqsync)# wait-to-restore 0
```

5. Configure Server Port

```
RP/0/RP0/CPU0:router(config)# interface GigabitEthernet0/0/0/3
RP/0/RP0/CPU0:router(config)# ptp
RP/0/RP0/CPU0:router(config)# profile master
RP/0/RP0/CPU0:router(config)# multicast target-address ethernet 01-1B-19-00-00-00
RP/0/RP0/CPU0:router(config)# port state master-only
RP/0/RP0/CPU0:router(config)# transport ethernet
RP/0/RP0/CPU0:router(config)# sync frequency 16
RP/0/RP0/CPU0:router(config)# announce frequency 8
RP/0/RP0/CPU0:router(config)# delay-request frequency 16
RP/0/RP0/CPU0:router(config)# frequency synchronization
RP/0/RP0/CPU0:router(config-if-freqsync)# exit
```

Configure PTP for SyncE and PTP Traceability

In the hybrid mode of operation, if the SyncE and PTP clocks are coming from separate nodes and are not traceable to each other, and if the offset between the clocks is high, then the PTP-receiver may fail to synchronize with the PTP-transmitter node.

Starting with Cisco IOS XR Release 24.4.1, a new command, **synchronous-ethernet prefer-interface ptp-receiver** is introduced in the global frequency-synchronisation mode to ensure traceability between the PTP and SyncE clocks.

If you configure this CLI, note these points:

- A SyncE source among *equal sources*¹ is selected on the same interface on which PTP is selected by the router.
- If the SyncE source on the PTP receiver interface is inferior (in terms of QL and user configured priority) than any other available SyncE source, then the SyncE source is selected using the default criteria (based on the ITU-T G.781 requirements).
- In the event that the selected PTP source goes down or if the PTP source's quality degrades, the system may switch to another PTP source. In such case, use the **synchronous-ethernet prefer-interface ptp-receiver** command so that the SyncE source selection would also switch to the new PTP receiver interface. Here, the preferred switching of SyncE source to the new PTP receiver interface shall happen only if the new interface uses the same SyncE QL and the user configured priority as the previously selected interface.

¹ sources equal in their advertised QL and user configured priority



Note The router can monitor only limited number of interfaces for SyncE selection. The **synchronous-ethernet prefer-interface ptp-receiver** command selects a SyncE source from the PTP receiver interface only if the interface is part of the list displayed using the **show frequency synchronization selection** command.

This example shows how to configure the **synchronous-ethernet prefer-interface ptp-receiver** command.

```
RP/0/RP0/CPU0:router(config)# frequency synchronization synchronous-ethernet prefer-interface
ptp-receiver
RP/0/RP0/CPU0:router(config)# commit
```

This example verifies the **synchronous-ethernet prefer-interface ptp-receiver** configuration.

```
RP/0/RP0/CPU0:router(config)# show running-config frequency synchronization
Thu Aug 8 04:50:13.638 UTC
frequency-synchronization
synchronous-ethernet prefer-interface ptp-receiver
!
```

Verifying the PTP Hybrid Mode Configurations

Use the following show commands to verify the configurations:

- **show ptp platform servo**

```
RP/0/RP0/CPU0:ios# show ptp platform servo
Tue Mar 5 07:08:00.134 UTC
Servo status: Running
Servo stat_index: 2
Device status: PHASE_LOCKED
Servo Mode: Hybrid
Servo log level: 0
Phase Alignment Accuracy: 0 ns
Sync timestamp updated: 8631
Sync timestamp discarded: 0
Delay timestamp updated: 8631
Delay timestamp discarded: 0
Previous Received Timestamp T1: 22521.011765183 T2: 22521.011766745 T3: 22521.018061685
T4: 22521.018063247
Last Received Timestamp T1: 22521.073747183 T2: 22521.073748745 T3: 22521.080054957
T4: 22521.080056515
Offset from master: 0 secs, 2 nsecs
Mean path delay : 0 secs, 1560 nsecs
setTime():1 stepTime():1 adjustFreq():0
Last setTime: 21984.000000000 flag:0 Last stepTime:-276573300 Last adjustFreq:0
RP/0/RP1/CPU0:ios#
```

- **show running-config ptp**

```
RP/0/RP0/CPU0:router# show running-config ptp
ptp
clock
domain 24
profile g.8275.1 clock-type T-BC
!
profile slave
transport ethernet
sync frequency 16
announce frequency 8
delay-request frequency 16
```

```

!
profile master
transport ethernet
sync frequency 16
announce frequency 8
delay-request frequency 16
!
!
physical-layer frequency
!

```

- **show running-config frequency synchronization**

```

RP/0/RP0/CPU0:router# show running-config frequency synchronization
Tue Feb 6 06:36:26.472 UTC
frequency synchronization
quality itu-t option 1
clock-interface timing-mode system
!

```

- **show frequency synchronization interface brief**

```

RP/0/RP0/CPU0:P3# show frequency synchronization interface brief

Tue Feb 6 06:37:49.234 UTC
Flags: > - Up D - Down S - Assigned for selection
d - SSM Disabled x - Peer timed out i - Init state
s - Output squelched
Fl Interface QLrcv QLuse Pri QLsnd Output driven by
=====
>S GigabitEthernet0/0/0/2 PRC PRC 1 DNU GigabitEthernet0/0/0/2
>x GigabitEthernet0/0/0/3 Fail n/a 100 PRC GigabitEthernet0/0/0/2
>x GigabitEthernet0/0/0/4 Fail n/a 100 PRC GigabitEthernet0/0/0/2
RP/0/RP0/CPU0:P3#

```

Configure PTP Delay Asymmetry

Configure PTP delay asymmetry to offset the static delays on a PTP path that occur due to different route selection for forward and reverse PTP traffic. Delays can also be due to any node having different delay for ingress or egress path. These delays can impact PTP accuracy due to the asymmetry in PTP. With this feature, you can enable a higher degree of accuracy in the PTP server performance leading to better synchronization between real-time clocks of the devices in a network.

Configuration of this delay asymmetry provides an option to configure static delays on a client clock for every server clock. You can configure this delay value in microseconds and nanoseconds. Configured PTP delay asymmetry is also synchronized with the Servo algorithm.


Note

- If you configure multiple PTP delay asymmetries for the same PTP profile, the latest PTP delay asymmetry that you configure is applied to the PTP profile.
- For G8275.1 and G8275.2 PTP profiles, PTP delay asymmetry is supported for both, client port and dynamic port that act as a client.
- Fixed delay can be measured by using any test and measurement tool. Fixed delay can be compensated by using the positive or negative values. For example, if the fixed delay is +10 nanoseconds, configure -10 nanoseconds to compensate the fixed delay.

A positive value indicates that the server-to-client propagation time is longer than the client-to-server propagation time, and conversely for negative values.

Supported PTP Profiles

The following PTP profiles support the configuration of PTP delay asymmetry:

- PTP over IP (G8275.2 or default profile)
- PTP over L2 (G8275.1)

Restrictions

- PTP delay asymmetry can be configured only on the PTP port of the grandmaster clock, which can either be a boundary clock or an ordinary clock.
- PTP delay asymmetry is supported for delay compensation of fixed cables and not for variable delay in the network.
- PTP delay asymmetry can be configured within the range of 3 microseconds and -3 microseconds or 3000 nanoseconds and -3000 nanoseconds.

Configuration

To configure PTP delay asymmetry:

1. Configure an interface with PTP.
2. Configure PTP delay asymmetry on the client side.

Configuration Example

```
/* Configure an interface with PTP. */
Router# configure
Router(config)# interface HundredGigE 0/1/0/0
Router(config-if)# ptp

/* Configure PTP delay asymmetry on the client side. */
Router(config-if-ptp)# delay-asymmetry 3 microseconds
Router(config-if-ptp)# commit
```

Running Configuration

```
interface preconfigure HundredGigE 0/1/0/0
 ptp
 delay-asymmetry 3 microseconds
```

Verification

To verify if PTP delay asymmetry is applied, use the **show ptp foreign-masters** command:

```
Router# show ptp foreign-masters
Sun Nov 1 10:19:21.874 UTC
Interface HundredGigE0/1/0/0 (PTP port number 1)
IPv4, Address 209.165.200.225, Unicast
Configured priority: 1
Configured clock class: None
Configured delay asymmetry: 3 microseconds <- configured variable delay asymmetry value
```

```

Announce granted: every 2 seconds, 300 seconds
Sync granted: 16 per-second, 300 seconds
Delay-resp granted: 16 per-second, 300 seconds
Qualified for 2 minutes, 45 seconds
Clock ID: 80e01dffffe8ab73f
Received clock properties:
Domain: 0, Priority1: 128, Priority2: 128, Class: 6
Accuracy: 0x22, Offset scaled log variance: 0xcd70
Steps-removed: 1, Time source: GPS, Timescale: PTP
Frequency-traceable, Time-traceable
Current UTC offset: 37 seconds (valid)
Parent properties:
Clock ID: 80e01dffffe8ab73f
Port number: 1

```

To validate the approximate compensated delay value, use the **show ptp platform servo** command:

```

Router# show ptp platform servo
Mon Jun 27 22:32:44.912 UTC
Servo status: Running
Servo stat_index: 2
Device status: PHASE_LOCKED
Servo Mode: Hybrid
Servo log level: 0
Phase Alignment Accuracy: -2 ns
Sync timestamp updated: 18838
Sync timestamp discarded: 0
Delay timestamp updated: 18837
Delay timestamp discarded: 0
Previous Received Timestamp T1: 1657002314.031435081 T2: 1657002314.031436686 T3:
1657002314.026815770 T4: 1657002314.026814372
Last Received Timestamp T1: 1657002314.031435081 T2: 1657002314.031436686 T3:
1657002314.088857790 T4: 1657002314.088856392
Offset from master: 0 secs, 1502 nsecs <---compensated value shows 1.5 microseconds
because the asymmetry configured under the interface is
3 microseconds.-->
Mean path delay : 0 secs, 103 nsecs
setTime():0 stepTime():0 adjustFreq():2
Last setTime: 0.000000000 flag:0 Last stepTime:0 Last adjustFreq:-5093

```

Performance Monitoring for PTP Networks

Performance Monitoring in PTP involves tracking and analyzing the performance of PTP networks to ensure accurate time synchronization across devices. This includes monitoring various metrics such as clock accuracy, synchronization status, and network delays. The goal is to identify and address any issues that may affect the precision and reliability of time synchronization in the network.

Performance Monitoring now has the ability to provide performance monitoring and time-stamp analysis information in a PTP network as per Annex J IEEE 1588-2019. This feature also includes additional monitoring granularity for time synchronization in telecommunication networks as per Annex F from the G8275 standard. For more information on PTP, Best Time Transmitter Clock Algorithm (BTCA), see [PTP Overview](#).

You can use the following parameters to define the Performance Monitoring in a PTP Network:

- Performance Monitoring Parameters
- Port Specific Parameters

Performance Monitoring Parameters

In addition to using the timestamps received from the grandmaster to sync to the grandmaster's clock, the timestamps can now be used to calculate parameters that are of your interest in performance monitoring:

- **TimeTransmitter - TimeReceiver Delay:** corrected propagation time from TimeTransmitter to TimeReceiver.
- **TimeReceiver - TimeTransmitter Delay:** corrected propagation time from TimeReceiver to TimeTransmitter.
- **Mean Path Delay:** mean propagation time over the PTP Communication Path.
- **Offset from TimeTransmitter:** time difference between a TimeTransmitter PTP instance and a TimeReceiver PTP instance as computed by the TimeReceiver PTP instance.

For each of these parameters, you can measure the average, minimum, maximum, and standard deviation for each measurement. These values are calculated and maintained for the following time intervals over the specified time periods:

- **3-minute:** maintained for the current 1-hour period.
- **15-minute:** maintained for the current 24-hour period.
- **1-hour:** maintained for the current 2-hour period.
- **24-hour:** maintained for the current 48-hour period.

The platform actively calculates the end-to-end latency between the TimeTransmitter and TimeReceiver through the Delay-Request-Response-Mechanism (DRRM), allowing Precision Time Protocol (PTP) to seamlessly operate across networks equipped with Transparent clocks, non-PTP aware switches, or a mix of both. Upon a request, PTP dynamically extracts these calculated values from the servo using a platform specific API, allowing you to make proactive changes to the network to ensure precise time synchronization essential for applications that depend on accurate timing.

Additional Port Specific Parameters

The parameters mentioned above apply to the entire Precision Time Protocol (PTP) instance, and there is an additional set of parameters specific to individual ports. These parameters include the counters for various packet types,

- received (rx) and
- transmitted (tx)

It is important to collect and maintain these counters for performance monitoring purposes, which follows the same time intervals and periods as those used for monitoring clock performance.

Port-specific parameters play a crucial role in ensuring accurate time synchronization. These packet types are essential for maintaining the accuracy and reliability of time synchronization in a PTP network:

- **Sync Packets:** These packets are sent by the master clock to the slave clocks to synchronize their time. They contain the precise time at which the packet was sent.
- **Delay Request Packets:** Sent by the slave clock to the master clock, these packets measure the delay between the master and slave clocks. The master clock responds with a Delay Response packet.

- **Follow-Up Packets:** These packets are sent by the master clock immediately after the Sync packet. They contain the exact time the Sync packet was sent, which helps in correcting any delays introduced by the network.
- **Announce Packets:** These packets are used by the master clock to announce its presence and capabilities to the slave clocks. They help in the selection of the best master clock in the network.
- **Management Packets:** These packets are used for configuration and management purposes within the PTP network. They allow for the adjustment of various parameters and settings.

Record format

Record format refers to the structure or layout of data within a record, which is used to store information about time synchronization events and measurements. This format can include various fields such as timestamps, event types, and other relevant data that PTP uses to maintain accurate time synchronization across a network. It is a single buffer for both annexes.

The format is the same for both clock and port performance monitoring parameters that is presented in the operational data. The data is stored over a 48-hour period, resulting in a list of records as per Annex J 1588-2019, composed of the following:

- 1 record for the current 15-minute set of statistics (stored at position 0 in the buffer).
- 96 records for the 15-minute sets of statistics over the last 24-hour period (stored between positions 1-96 in the buffer).
- 1 record for the current 24-hour set of statistics (stored at position 97 in the buffer).
- 1 record for the previous 24-hour set of statistics (stored at position 98 in the buffer).

The data buffer records data at 3-minute intervals over the most recent 1-hour period, creating a list of records that includes:

- 1 record for the current 3-minute set of statistics (stored at position 100 in the buffer).
- 20 records for the 3-minute set of statistics over the last 1-hour period (stored between positions 101-120).
- 1 record for the current 1-hour set of statistics (stored at position 121 in the buffer).
- 1 record for the previous 1-hour set of statistics (stored at position 122 in the buffer).

Configure PTP Performance Monitoring

The purpose of this task is to configure and verify PTP performance monitoring.

Procedure

-
- Step 1** Configure the **performance-monitoring** command to enable collection of performance monitoring statistics and for the users to make performance monitoring requests.

Example:

```
Router(config)# ptp
```

```
Router(config-ptp)# performance-monitoring
Router(config-ptp)# commit
```

Step 2 Run the **sh ptp platform performance-counters** command to display the details of all 123 records.

The existing command **show ptp platform** is extended to include the performance monitoring data for the local clock. The detail mode of the command displays all 123 records while the brief mode displays only the current windows for 15 minutes, 24 hours, 3minutes, and 1hour.

Example:

```
Router#sh ptp platform performance-counters detail
```

```
PTP Current record index 15 min: 96
PTP Current record index 3 min: 119
```

```
PTP performance monitoring statistics:
```

```
15 min stats
```

```
[0] 12 August 2024 07:08:59 UTC 15 min statistics
```

deviation	Stat Samples	Min(sec.nsec)	Max(sec.nsec)	Mean(sec.nsec)	Std
Master-slave-delay	-000000000.15937	000000000.333	-000000000.1780		
000000000.71191	154				
Slave-master-delay	000000000.319	000000000.16593	000000000.2437		
000000000.74103	154				
mean-path-delay	000000000.322	000000000.334	000000000.327		
000000000.4057	154				
offset-from-master	-000000000.16263	000000000.6	-000000000.2108		
000000000.72546	154				
Complete	Valid	PmRef	ServoAtStart	ServoAtEnd	
LastServoFlapTime					
FALSE	FALSE	TRUE	PHASE_LOCKED	HOLDOVER	12
Apr 2024 07:09:09 UTC					

```
=====
```

```
...
```

Step 3 Run the **show ptp dataset performance clock** command to display the performance monitoring data-set details in 15 minutes intervals.

Example:

```
Router#show ptp dataset performance clock
```

```
performanceMonitoringDS for the current 15-minute window:
Clock ID cccfffecccc00, steps removed 1, receiving-port 2:
  Start of time window: Thursday, April 11, 2024 14:18:59
  Measurement is valid
  Period is complete
  Measurement has been taken with reference to system clock
```

```

Master slave delay:
  Average: 50ns
  Min: 50ns
  Max: 70ns
  Std: 1ns
Slave master delay:
  Average: 51ns
  Min: 51ns
  Max: 71ns
  Std: 2ns
Mean path delay:
  Average: 52ns
  Min: 52ns
  Max: 72ns
  Std: 3ns
Offset from master:
  Average: 53ns
  Min: 53ns
  Max: 73ns
  Std: 4ns

Clock ID aaaabbbbecccc00, steps removed 1, receiving-port 2:
Start of time window: Thursday, April 11, 2024 14:18:59
Measurement is not valid
Period is not complete
Measurement has been taken with reference to system clock
Master slave delay:
  Average: 50ns
  Min: 50ns
  Max: 70ns
  Std: 1ns
Slave master delay:
  Average: 51ns
  Min: 51ns
  Max: 71ns
  Std: 2ns
Mean path delay:
  Average: 52ns
  Min: 52ns
  Max: 72ns
  Std: 3ns
Offset from master:
  Average: 53ns
  Min: 53ns
  Max: 73ns
  Std: 4ns

```

Step 4 Run the **show ptp dataset performance port** to display the Performance Monitoring Port Data-set in 15 minutes intervals.

Example:

```
Router#show ptp dataset performance port GigabitEthernet 0/0/0/1
```

```
performanceMonitoringPortDS for the current 15-minute window:
```

```
Interface GigabitEthernet 0/0/0/1
```

```
Start of time window: Thursday, April 11, 2024 14:18:59
```

```
Measurement is valid
```

```
Period is not complete
```

```
Measurement has been taken with reference to system clock
```

Packets	Sent	Received	Dropped
Announce	3	83	11
Sync	0	32	5
Follow-Up	0	31	0

Delay-Req	22	0	0
Delay-Resp	0	21	7
Pdelay-Req	0	7	0
Pdelay-Resp	0	0	0
Pdelay-Resp-Follow-Up	0	0	0
Signaling	2	1	0
Management	0	0	0
Other	0	3	12
	----	----	----
TOTAL	27	178	35



CHAPTER 4

External Timing Source

Clock interfaces are external connectors for connecting other timing signals, such as, GPS, BITS.

- [GPS, on page 45](#)
- [Building Integrated Timing Supply \(BITS\), on page 47](#)

GPS

The router can receive 1PPS, 10 MHz, and ToD signals from an external clocking and timing source. The three inputs are combined as a Sync-2 interface to form the external timing source or the GPS input.

The GPS front panel connector details are:

- ToD—RS422 format as input
- 1PPS—RS422 or DIN connector as input
- 10MHz—DIN connector as input

GPS input starts only when all the three signals – 1PPS, 10MHz, and ToD are UP.

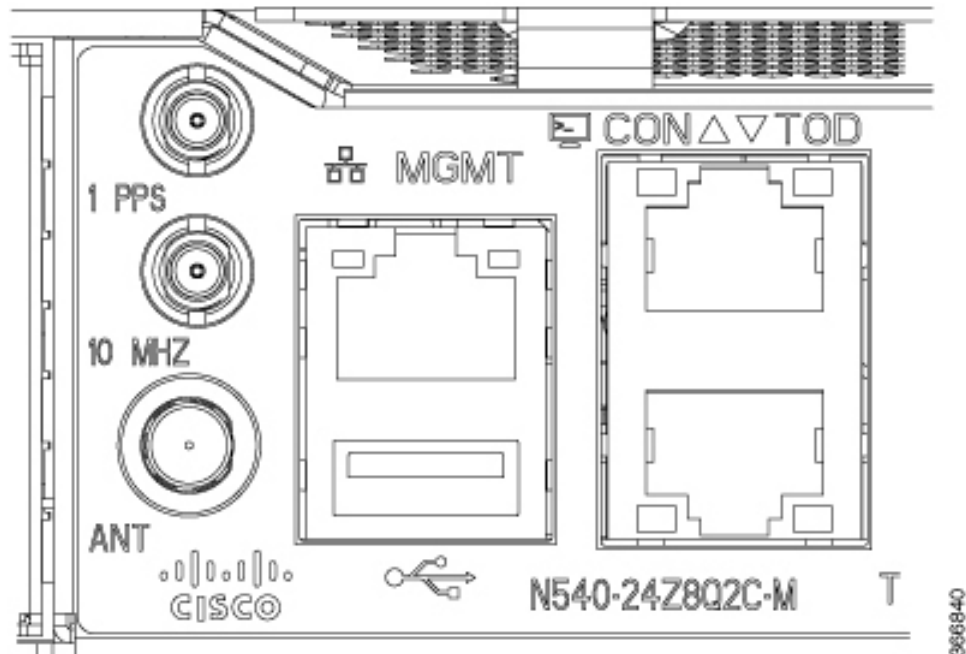


Note Unlike the Ethernet interface, the Sync-2 interface cannot receive or transmit QL. Ensure that you assign a QL value to the Sync-2 interface.

By default, 1PPS and 10MHz are in output mode. ToD output mode is not configurable.

For these variants - N540-24Z8Q2C-SYS, N540X-ACC-SYS, N540-ACC-SYS, N540-28Z4C-SYS, 10MHZ and 1PPS can operate in output mode only when PTP Client or BC mode are configured.

Figure 4: 1PPS, 10MHz, and the ToD ports on the Router's Front Panel



Configuring GPS Settings for the Grandmaster Clock

```
RP/0/RP0/CPU0:router# configure
RP/0/RP0/CPU0:router(config)# clock-interface sync 2 location 0/RP0/CPU0
RP/0/RP0/CPU0:router(config-clock-if)# port-parameters
RP/0/RP0/CPU0:router(config-clk-parms)# gps-input tod-format cisco pps-input ttl
RP/0/RP0/CPU0:router(config-clk-parms)# exit
RP/0/RP0/CPU0:router(config-clock-if)# frequency synchronization
RP/0/RP0/CPU0:router(config-clk-freqsync)# selection input
RP/0/RP0/CPU0:router(config-clk-freqsync)# wait-to-restore 0
RP/0/RP0/CPU0:router(config-clk-freqsync)# quality receive exact itu-t option 1 PRC
RP/0/RP0/CPU0:router(config-clk-freqsync)# exit
RP/0/RP0/CPU0:router(config-clock-if)# frequency synchronization
RP/0/RP0/CPU0:router(config-clk-freqsync)# quality itu-t option 1
RP/0/RP0/CPU0:router(config-clk-freqsync)# clock-interface timing-mode system
RP/0/RP0/CPU0:router(config-clk-freqsync)# end
or
RP/0/RP0/CPU0:router(config-clk-freqsync)# commit
```

Verifying the GPS Input

```
RP/0/RP0/CPU0:R1# show controllers timing controller clock
```

```
SYNCC Clock-Setting: -1 -1 6 -1
  Port 0  Port 1  Port 2  Port 3
Config :      No      No      Yes      No
Mode : -      -      GPS      -
Submode1 : -      -      CISCO    -
Submode2 : -      -      UTC      -
Submode3 : 0      0      0      0
Shutdown : 0      0      0      0
Direction : RX/TX  RX/TX  RX      RX/TX
```

```
Baud-Rate :      -      -      9600      -
QL Option :    01      01      -      -
RX_ssm(raw) :    -      -      -      -
TX_ssm :        -      -      -      -
If_state :    DOWN    DOWN    UP      DOWN  << Port 2 is UP when GPS input is
valid.
```

```
RP/0/RP0/CPU0:R1#
```

When the front panel timing LED is Green, it indicates that the GPS is configured and 1PPS, ToD, and 10M inputs are valid.

Timing LED Behavior:

- Timing LED is off: Indicates that no GPS is configured or the GPS port is down.
- Timing LED is green: Indicates that the GPS port is up.

SYNC LED Behavior:

- SYNC LED is applicable: Only when the timing configuration is applied.
- SYNC LED is green: Indicates that SyncE is locked.
- SYNC LED is amber: Indicates a holdover or free-running state.
- SYNC LED is off: Indicates that the configuration is removed.

Building Integrated Timing Supply (BITS)

Router supports receiving (Rx) and transmitting (Tx) of frequency via BITS interface. To receive and transmit BITS signals, configuration is done under the clock-interface sync 0 on the route processor (RP).

Prerequisite for BITS

Frequency synchronization must be configured with the required quality level option at the global level.

```
RP/0/RP0/CPU0:ios#show running-config frequency synchronization
Wed Aug 21 12:37:32.524 UTC
frequency synchronization
quality itu-t option 1
!
```



Note BITS-In and BITS-Out on the peer nodes must be configured with the same mode and format.

Configuring BITS-IN

```
RP/0/RP0/CPU0:ios#configure
Wed Aug 21 12:29:59.162 UTC
RP/0/RP0/CPU0:ios(config)#clock-interface sync 0 location 0/RP0/CPU0
RP/0/RP0/CPU0:ios(config-clock-if)#port-parameters
RP/0/RP0/CPU0:ios(config-clk-parms)#bits-input e1 crc-4 sa4 ami
RP/0/RP0/CPU0:ios(config-clk-parms)#exit
```

```

RP/0/RP0/CPU0:ios(config-clock-if)#frequency synchronization
RP/0/RP0/CPU0:ios(config-clk-freqsync)#selection input
RP/0/RP0/CPU0:ios(config-clk-freqsync)#wait-to-restore 0
RP/0/RP0/CPU0:ios(config-clk-freqsync)#priority 1
RP/0/RP0/CPU0:ios(config-clk-freqsync)#commit
Wed Aug 21 12:30:53.296 UTC

RP/0/RP0/CPU0:ios#show running-config clock-interface sync 0 location 0/RP0/CPU0
Wed Aug 21 12:31:43.350 UTC
clock-interface sync 0 location 0/RP0/CPU0
  port-parameters
    bits-input e1 crc-4 sa4 ami
  !
  frequency synchronization
  selection input
  priority 1
  wait-to-restore 0
  !
  !

```

Configuring BITS-OUT

```

RP/0/RP0/CPU0:ios#configure
Wed Aug 21 12:53:24.189 UTC
RP/0/RP0/CPU0:ios(config)#clock-interface sync 0 location 0/RP0/CPU0
RP/0/RP0/CPU0:ios(config-clock-if)#port-parameters
RP/0/RP0/CPU0:ios(config-clk-parms)#bits-output e1 crc-4 sa4 ami
RP/0/RP0/CPU0:ios(config-clk-parms)#commit
Wed Aug 21 12:53:39.411 UTC

RP/0/RP0/CPU0:ios#show running-config clock-interface sync 0 location 0/RP0/CPU0
Wed Aug 21 12:54:02.853 UTC
clock-interface sync 0 location 0/RP0/CPU0
  port-parameters
    bits-output e1 crc-4 sa4 ami
  !
  !

```



Note Based on the quality level chosen in global configuration, E1/T1 modes can be changed as required. But in all the cases, both TX and RX side modes and submodes must be the same.

For non-CRC-4/D4 modes, SSM is not present in BITS and manual receive quality level must be configured.

Verifying BITS-IN Configuration

```

RP/0/RP0/CPU0:ios#show controllers timing controller clock
Wed Aug 21 12:38:20.394 UTC

```

```

SYNCC Clock-Setting: 1 -1 -1 -1

```

	Port 0	Port 1	Port 2	Port 3
Config	: Yes	No	No	No
Mode	: E1	-	-	-
Submode1	: CRC-4	-	-	-
Submode2	: AMI	-	-	-
Submode3	: 0	0	0	0
Shutdown	: 0	0	0	0
Direction	: RX	RX/TX	RX/TX	RX/TX

```

Baud-Rate   : -           -           -           -
QL Option   : 01          01          -           -
RX_ssm(raw) : 99          -           -           -
TX_ssm      : -           -           -           -
If_state    : UP          DOWN        DOWN        DOWN

```

Verifying BITS-OUT Configuration

```

RP/0/RP0/CPU0:ios#show controllers timing controller clock
Wed Aug 21 12:49:32.923 UTC
SYNCC Clock-Setting: 1 -1 -1 -1

```

	Port 0	Port 1	Port 2	Port 3
Config	: Yes	No	No	No
Mode	: E1	-	-	-
Submodel	: CRC-4	-	-	-
Submode2	: AMI	-	-	-
Submode3	: 0	0	0	0
Shutdown	: 0	0	0	0
Direction	: TX	RX/TX	RX/TX	RX/TX
Baud-Rate	: -	-	-	-
QL Option	: 01	01	-	-
RX_ssm(raw)	: -	-	-	-
TX_ssm	: 22	-	-	-
If_state	: UP	DOWN	DOWN	DOWN

Verify Quality Level Received and Clock Interfaces

```

RP/0/RP0/CPU0:ios#show frequency synchronization clock-interfaces brief
Sat Mar 16 07:35:08.351 UTC
Flags:  > - Up                D - Down                S - Assigned for selection
         d - SSM Disabled      s - Output squelched  L - Looped back
Node 0/RP0/CPU0:
=====
Fl      Clock Interface      QLrcv  QLuse  Pri  QLsnd  Output driven by
=====
>S      Sync0                PRS    PRS    5   n/a    n/a
D        Sync1                n/a    n/a    n/a  n/a    n/a
D        Sync2                n/a    n/a    n/a  n/a    n/a
>S      Internal0            n/a    ST3    255 n/a    n/a

```




CHAPTER 5

Implementing NTP

Network Time Protocol (NTP) is a protocol designed to time-synchronize devices within a network. Cisco IOS XR software implements NTPv4. NTPv4 retains backwards compatibility with the older versions of NTP, including NTPv3 and NTPv2 but excluding NTPv1, which has been discontinued due to security vulnerabilities.

- [Information About Implementing NTP, on page 51](#)
- [Configuring NTP, on page 52](#)

Information About Implementing NTP

NTP synchronizes timekeeping among a set of distributed time servers and clients. This synchronization allows events to be correlated when system logs are created and other time-specific events occur.

NTP uses the User Datagram Protocol (UDP) as its transport protocol. All NTP communication uses Coordinated Universal Time (UTC). An NTP network usually receives its time from an authoritative time source, such as a radio clock or an atomic clock attached to a time server. NTP distributes this time across the network. NTP is efficient; no more than one packet per minute is necessary to synchronize two machines to within a millisecond of each other.

NTP uses the concept of a “stratum” to describe how many NTP “hops” away a machine is from an authoritative time source. A “stratum 1” time server typically has an authoritative time source (such as a radio or atomic clock, or a GPS time source) directly attached, a “stratum 2” time server receives its time via NTP from a “stratum 1” time server, and so on.

NTP avoids synchronizing to a machine whose time may not be accurate, in two ways. First, NTP never synchronizes to a machine that is not synchronized itself. Second, NTP compares the time reported by several machines and does not synchronize to a machine whose time is significantly different than the others, even if its stratum is lower. This strategy effectively builds a self-organizing tree of NTP servers.

The Cisco implementation of NTP does not support stratum 1 service; in other words, it is not possible to connect to a radio or atomic clock (for some specific platforms, however, you can connect a GPS time-source device). We recommend that time service for your network be derived from the public NTP servers available in the IP Internet.

If the network is isolated from the Internet, the Cisco implementation of NTP allows a machine to be configured so that it acts as though it is synchronized via NTP, when in fact it has determined the time using other means. Other machines can then synchronize to that machine via NTP.

Several manufacturers include NTP software for their host systems, and a publicly available version for systems running UNIX and its various derivatives is also available. This software also allows UNIX-derivative

servers to acquire the time directly from an atomic clock, which would subsequently propagate time information along to Cisco routers.

The communications between machines running NTP (known as associations) are usually statically configured; each machine is given the IP address of all machines with which it should form associations. Accurate timekeeping is made possible by exchanging NTP messages between each pair of machines with an association.

The Cisco implementation of NTP supports two ways that a networking device can obtain NTP time information on a network:

- By polling host servers
- By listening to NTP broadcasts

In a LAN environment, NTP can be configured to use IP broadcast messages. As compared to polling, IP broadcast messages reduce configuration complexity, because each machine can simply be configured to send or receive broadcast or multicast messages. However, the accuracy of timekeeping is marginally reduced because the information flow is one-way only.

An NTP broadcast client listens for broadcast messages sent by an NTP broadcast server at a designated IPv4 address. The client synchronizes the local clock using the first received broadcast message.

The time kept on a machine is a critical resource, so we strongly recommend that you use the security features of NTP to avoid the accidental or malicious setting of incorrect time. Two mechanisms are available: an access list-based restriction scheme and an encrypted authentication mechanism.

When multiple sources of time (VINES, hardware clock, manual configuration) are available, NTP is always considered to be more authoritative. NTP time overrides the time set by any other method.

Configuring NTP

PTP-NTP Interworking

Table 9: Feature History Table

Feature Name	Release Information	Feature Description
PTP-NTP Interworking	Release 24.1.1	<p>We have improved NTP synchronization and reliability to achieve nanosecond-level accuracy for applications that require high-precision timing. This is achieved by enabling NTP-PTP interworking which allows the use of PTP as the reference clock.</p> <p>As in previous releases, the NTP client continues to support polling NTP protocol-based external time servers to synchronize the local system clock and achieve accuracy within the millisecond range.</p>

Before the support of PTP-NTP interworking, NTP worked with NTP server to get the clock.

PTP-NTP interworking provides the ability to use PTP, and other valid time of day (TOD) sources such as Data over Cable Service Interface Specification (DOCSIS) Timing Interface (DTI) and global positioning system (GPS), as the time source for the operating system in the units of nanosecond-level accuracy. PTP is capable of achieving nanosecond-level accuracy, while NTP is typically only accurate to within milliseconds. By using PTP as a reference clock, NTP can improve its accuracy and meet the needs of applications that require high precision timing.

PTP-NTP interworking also provides the means to communicate status changes between PTP and NTP processes. It also supports the unambiguous control of the operating system time and backplane time in the event of bootstrap, switchovers, or card and process failures.

With PTP-NTP interworking, NTP is less likely to lose synchronization. As, PTP is more robust to network delays and disruptions than NTP. Hence, PTP can still maintain accurate synchronization even if there's a problem with the network.

Enable PTP-NTP Interworking

Prerequisites for PTP-NTP Interworking

Ensure that PTP is enabled, before configuring PTP-NTP Interworking.

Configuration Example for PTP-NTP Interworking

You can configure PTP-NTP Interworking in any of the following ways:

- Setting NTP Primary Reference Clock as PTP

```
Router # Configure
Router(config) # ntp
Router(config-ntp) # master primary-reference-clock
Router(config-ntp) # commit
```

- Configuring NTP Server with IP address

The following example shows an NTP configuration to allow the system clock to be synchronized by time server hosts at IP address 198.51.100.1. You can take IP address of a neighbouring PTP interface.

```
Router # Configure terminal
Router(config)# ntp server 198.51.100.1
Router(config-ntp) # commit
```

Verification

Router#show ntp status

```
Clock is synchronized, stratum 1, reference is 198.51.100.1
nominal freq is 1000000000.0000 Hz, actual freq is 101341889.2967 Hz, precision is 2**24
reference time is 8497CD13.A6AEB9DA (00:02:27.651 UTC Tue Jun 30 1970)
clock offset is -0.077 msec, root delay is 0.000 msec
root dispersion is 3937.89 msec, peer dispersion is 3937.74 msec
loopfilter state is 'CTRL' (Normal Controlled Loop), drift is 0.0000088676 s/s
system poll interval is 64, last update was 4 sec ago
authenticate is disabled, panic handling is disabled,
hostname resolution retry interval is 1440 minutes
```

Router#Show ntp associations

address	ref clock	st	when	poll	reach	delay	offset	disp
*~198.51.100.1	.PTP.	0	-	64	0	0.00	0.000	16000

Configuring Poll-Based Associations

The following example shows an NTP configuration in which the router's system clock is configured to form a peer association with the time server host at IP address 192.168.22.33, and to allow the system clock to be synchronized by time server hosts at IP address 10.0.2.1 and 172.19.69.1:

```
ntp
  server 10.0.2.1 minpoll 5 maxpoll 7
  peer 192.168.22.33
  server 172.19.69.1
```

Configuring Broadcast-Based Associations

The following example shows an NTP client configuration in which interface 0/2/0/0 is configured to receive NTP broadcast packets, and the estimated round-trip delay between an NTP client and an NTP broadcast server is set to 2 microseconds:

```
ntp
  interface tengige 0/2/0/0
    broadcast client
  exit
broadcastdelay 2
```

The following example shows an NTP server configuration where interface 0/2/0/2 is configured to be a broadcast server:

```
ntp
  interface tengige 0/2/0/0
    broadcast
```

Configuring NTP Access Groups

The following example shows a NTP access group configuration where the following access group restrictions are applied:

Peer restrictions are applied to IP addresses that pass the criteria of the access list named peer-acl. Serve restrictions are applied to IP addresses that pass the criteria of access list named serve-acl.

Serve-only restrictions are applied to IP addresses that pass the criteria of the access list named serve-only-acl.

Query-only restrictions are applied to IP addresses that pass the criteria of the access list named query-only-acl.

```
ntp
  peer 10.1.1.1
  peer 10.1.1.1
  peer 10.2.2.2
  peer 10.3.3.3
  peer 10.4.4.4
  peer 10.5.5.5
  peer 10.6.6.6
  peer 10.7.7.7
  peer 10.8.8.8
  access-group peer peer-acl
  access-group serve serve-acl
  access-group serve-only serve-only-acl
  access-group query-only query-only-acl
  exit
ipv4 access-list peer-acl
  10 permit ip host 10.1.1.1 any
  20 permit ip host 10.8.8.8 any
```

```
exit
ipv4 access-list serve-acl
 10 permit ip host 10.4.4.4 any
 20 permit ip host 10.5.5.5 any
exit
ipv4 access-list query-only-acl
 10 permit ip host 10.2.2.2 any
 20 permit ip host 10.3.3.3 any
exit
ipv4 access-list serve-only-acl
 10 permit ip host 10.6.6.6 any
 20 permit ip host 10.7.7.7 any
exit
```

Configuring NTP Authentication

The following example shows an NTP authentication configuration. In this example, the following is configured:
NTP authentication is enabled.

Two authentication keys are configured (key 2 and key 3).

The router is configured to allow its software clock to be synchronized with the clock of the peer (or vice versa) at IP address 10.3.32.154 using authentication key 2.

The router is configured to allow its software clock to be synchronized with the clock by the device at IP address 10.32.154.145 using authentication key 3.

The router is configured to synchronize only to systems providing authentication key 3 in their NTP packets.

```
ntp
authenticate
authentication-key 2 md5 encrypted 06120A2D40031D1008124
authentication-key 3 md5 encrypted 1311121E074110232621
trusted-key 3
server 10.3.32.154 key 3
peer 10.32.154.145 key 2
```

Disabling NTP on an Interface

The following example shows an NTP configuration in which 0/2/0/0 interface is disabled:

```
ntp
interface tengige 0/2/0/0
  disable
exit
authentication-key 2 md5 encrypted 06120A2D40031D1008124
authentication-key 3 md5 encrypted 1311121E074110232621
authenticate
trusted-key 3
server 10.3.32.154 key 3
peer 10.32.154.145 key 2
```

Configuring the System as an Authoritative NTP Server

The following example shows a NTP configuration in which the router is configured to use its own NTP server clock to synchronize with peers when an external NTP source becomes unavailable:

```
ntp
master 6
```

Updating the Hardware Clock

The following example shows an NTP configuration in which the router is configured to update its hardware clock from the software clock at periodic intervals:

```
ntp
server 10.3.32.154
update-calendar
```

Configuring NTP Server Inside VRF Interface



Note No specific command enables NTP; the first NTP configuration command that you issue enables NTP.

```
RP/0/RP0/CPU0:router# configure
RP/0/RP0/CPU0:router(config)# ntp
RP/0/RP0/CPU0:router(config)# ntp vrf Customer_A
RP/0/RP0/CPU0:router(config)# ntp vrf Customer_A source bvi 70
RP/0/RP0/CPU0:router(config-ntp)# end
or
RP/0/RP0/CPU0:router(config-ntp)# commit
```

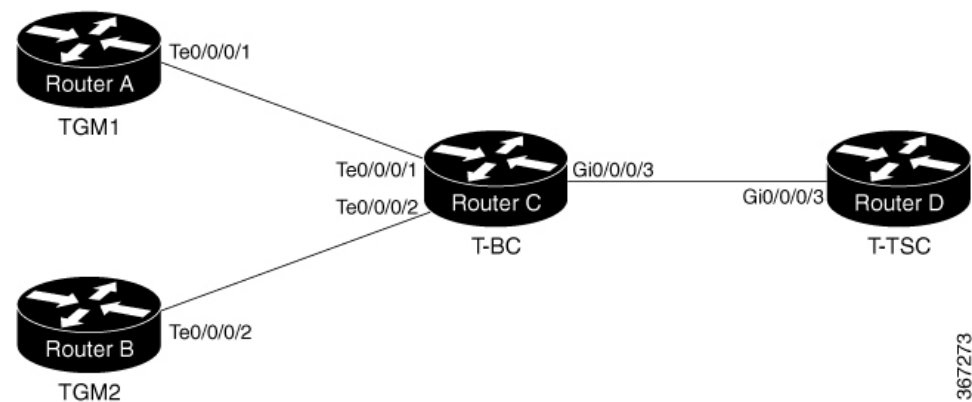


CHAPTER 6

Workflow and Use Case

Consider the following topology for configuring the G.8275.1:

Figure 5: Sample G.8275.1 Topology



Configuration on TGM1

```

frequency synchronization
quality itu-t option 1
clock-interface timing-mode system
!
clock-interface sync 2 location 0/RP0/CPU0
port-parameters
  gps-input tod-format cisco pps-input ttl
!
frequency synchronization
selection input
wait-to-restore 0
quality receive exact itu-t option 1 PRC
!
ptp clock
domain 24
  profile g.8275.1 clock-type T-GM
!
profile master
transport ethernet
sync frequency 16
announce frequency 8
delay-request frequency 16
!
interface GigabitEthernet0/0/0/1

```

```

ptp
  profile master
  multicast target-address ethernet 01-1B-19-00-00-00
  port state master-only
  transport ethernet
  sync frequency 16
  announce frequency 8
  delay-request frequency 16
!
frequency synchronization
!

```

Configuration on TGM2

```

frequency synchronization
  quality itu-t option 1
  clock-interface timing-mode system
!
clock-interface sync 2 location 0/RP0/CPU0
port-parameters
  gps-input tod-format cisco pps-input ttl
!
frequency synchronization
  selection input
  wait-to-restore 0
  quality receive exact itu-t option 1 PRC
!
ptp clock
domain 24
  profile g.8275.1 clock-type T-BC
!
profile master
  transport ethernet
  sync frequency 16
  announce frequency 8
  delay-request frequency 16
!
interface GigabitEthernet0/0/0/2
ptp
  profile master
  multicast target-address ethernet 01-1B-19-00-00-00
  port state master-only
  transport ethernet
  sync frequency 16
  announce frequency 8
  delay-request frequency 16
!
frequency synchronization
!

```

Configuration on T-BC

```

frequency synchronization
  quality itu-t option 1
  clock-interface timing-mode system
!
ptp clock
domain 24
  profile g.8275.1 clock-type T-BC
!
profile slave
  transport ethernet
  sync frequency 16
  announce frequency 8
  delay-request frequency 16

```



```

!
physical-layer frequency
!

profile master
  transport ethernet
  sync frequency 16
  announce frequency 8
  delay-request frequency 16
! !
interface TenGigE0/0/0/1
  ptp
  profile slave
  multicast target-address ethernet 01-1B-19-00-00-00
  transport ethernet
  sync frequency 16
  local-priority 10
  announce frequency 8
  delay-request frequency 16
!
frequency synchronization
  selection input
  priority 1
  wait-to-restore 0
! !
interface TenGigE0/0/0/2
  ptp
  profile slave
  multicast target-address ethernet 01-1B-19-00-00-00
  transport ethernet
  port state any
  sync frequency 16
  local-priority 20
  announce frequency 8
  delay-request frequency 16
!
frequency synchronization
  selection input
  priority 1
  wait-to-restore 0
! !
interface GigabitEthernet0/0/0/3
  ptp
  profile master
  multicast target-address ethernet 01-1B-19-00-00-00
  transport ethernet
  port state any
  sync frequency 16
  announce frequency 8
  delay-request frequency 16
!
frequency synchronization
! !

```

Configuration on T-TSC

```

frequency synchronization
  quality itu-t option 1
  clock-interface timing-mode system
! ptp
clock
  domain 24
  profile g.8275.1 clock-type T-TSC
!
profile slave

```

```
transport ethernet
sync frequency 16
announce frequency 8
delay-request frequency 16
!
physical-layer frequency
!
!
interface GigabitEthernet0/0/0/3
ptp
  profile slave
  multicast target-address ethernet 01-1B-19-00-00-00
  transport ethernet
  port state slave-only
  local-priority 10
!
frequency synchronization
  selection input
  priority 1
  wait-to-restore 0
!
```



CHAPTER 7

Configure the Global Navigation Satellite System

Effective Cisco IOS XR Release 7.4.1, GNSS is supported on the this routers.

This chapter describes the Global Navigation Satellite System (GNSS) and how to configure it.

In typical telecom networks, network synchronization works in a hierarchal manner where the core network is connected to a stratum-1 clock. The timing from the stratum-1 clock is then distributed along the network in a tree-like structure. However, with a GNSS receiver, clocking is changed to a flat architecture, where access networks can directly take clock from the satellites by using an on-board GPS chip.

Router now uses a satellite receiver, also called the Global Navigation Satellite System (GNSS), as the new timing interface.

This capability simplifies network synchronization planning and provides flexibility and resilience in resolving network synchronization issues in the hierarchical network.

- [Overview of GNSS, on page 61](#)
- [Operation of GNSS Module , on page 62](#)
- [Prerequisites for GNSS, on page 64](#)
- [Restrictions for GNSS, on page 64](#)
- [Configure GNSS, on page 64](#)

Overview of GNSS

No license is required to enable the GNSS module. The GNSS LED on the front panel indicates the status of the module. The following table describes the different status of GNSS LED:

LED Status	Description
Green	GNSS NormalState.Selfsurvey is complete.
Amber	All other states

When connected to an external antenna, the module can acquire satellite signals and track up to 32 GNSS satellites, and compute location, speed, heading, and time. GNSS provides an accurate one pulse-per-second (PPS), a stable 10 MHz frequency output to synchronize broadband wireless, aggregation and pre-aggregation routers, and an accurate time-of-day (ToD).



Note NCS-55A2-MOD-SE-S can also receive 1PPS, 10 MHz, and ToD signals from an external clocking and timing source. However, the timing signals from the GNSS module (when enabled) take precedence over those of the external source.



Note We do not recommend that you configure both the front panel (10M, 1PPS and ToD) input configuration and the GNSS input configuration.

By default, anti-jamming is enabled on the GNSS module.

Operation of GNSS Module

Operation of GNSS Module on the Routers

The GNSS module has the following stages of acquiring and providing timing signals to the Cisco router:

- Self-survey mode - When the router is reset, the GNSS module comes up in self-survey mode. It tries to lock on to a minimum of four different satellites and computes approximately 2000 different positions of the satellites to obtain a 3-D location (Latitude, Longitude, and Height) of its current position. This operation takes about 35 to 40 minutes. During this stage, the module is also able to generate accurate timing signals and achieve a Normal or Phase-locked state.

When GNSS moves into Normal state, you can start using the 1PPS, 10 MHz, and ToD inputs from GNSS. The quality of the signal in self-survey mode with Normal state is considered good enough to lock to GNSS.

- Over determined clock mode - The router switches to over determined (OD) mode when the self-survey mode is complete, and the position information is stored in non-volatile memory on the router. In this mode, the module only processes the timing information based on satellite positions captured in self-survey mode.

The router saves the tracking data, which is retained even when the router is reloaded.

The GNSS module stays in OD mode until one of the following conditions occur:

- A position relocation of the antenna of more than 100 meters is detected. This detection causes an automatic restart of the self-survey mode.
- A manual restart of the self-survey mode or when the stored reference position is deleted.
- A worst-case recovery option after a jamming-detection condition that cannot be resolved with other methods.

You can configure the GNSS module to automatically track any satellite or configure it to explicitly use a specific constellation. However, the module uses configured satellites in only the OD mode.



Note GLONASS and BeiDou satellites cannot be enabled simultaneously.

When the router is reloaded, it always comes up in OD mode unless:

- the router is reloaded when the self-survey mode is in progress.
- the physical location of the router is changed to more than 100 meters from its pre-reloaded condition.

When the system restarts the GNSS self-survey by using the default gnss slot R0/R1 command in config mode, the 10MHz, 1PPS, and ToD signals are not changed and remain up.

Operation of GNSS Module on the Routers

The GNSS module has the following stages of acquiring and providing timing signals to the Cisco router:

- Self-survey mode - Self-survey is the procedure that is performed prior to using time mode. It determines the position of a stationary receiver by building a weighted mean of all valid 3D position solutions.

To stop self-survey mode, the following two requirements must be met:

- The minimum observation time defines a minimum amount of observation time regardless of the actual number of valid fixes that are used for position calculation. Reasonable values range from one day for high accuracy position calculation to a few minutes for coarse position determination.
- The required 3D position standard deviation defines a limit on the spread of positions that contribute to the calculated mean. As the position error translates into a time error when using time mode, you should carefully evaluate the time accuracy requirements and choose an appropriate value.

Self-survey ends when both requirements are met. After self-survey is completed successfully, the receiver automatically enters time-fix mode.

Recommendations

- Self-survey must run for at least twenty-four hours because it is important to cover a full constellation run and a day-night cycle.
- CNO or signal strength for achieving time-fix during self-survey is 35dB.
- Time-fix mode - In order to use the time-fix mode, the exact position of the receiver must be known. The exact position of the receiver is determined by using self-survey. Errors in the fixed position translate into time errors depending on the satellite constellation.

There is no minimum and maximum value (Time) in the self-survey process and the receiver makes the best effort to achieve the time-fix mode.

For achieving the time-fix mode, a minimum of four satellites are required and it may take several days to get into the time-fix mode.

If the position is already known, the module can achieve time-fix mode even if there is only one satellite received.

You can configure the GNSS module to automatically track any satellite or configure it to explicitly use a specific constellation.

When the router is reloaded, it always comes up in the time-fix mode unless the router is reloaded when the self-survey mode is in progress.

Prerequisites for GNSS

To use GNSS, the antenna must see as much as possible from the sky. For proper timing, a minimum of four satellites must be locked. For more information, see the *Cisco NCS 560-4 Router Hardware Installation Guide*.

Restrictions for GNSS

- The GNSS module is not supported through SNMP; all configurations are performed through commands.
- The GNSS holdover performance is one microsecond in two hours of holdover after twelve hours of GNSS lock time.
- In Cisco IOS XR Release 7.4.1, on the standby route processor (RP), you cannot enable *frequency-synchronization* under the *gnss-receiver* configuration. This configuration always fails on the standby RP. This configuration can only be enabled either manually or through an EEM script after a redundancy switchover, when the standby RP becomes the active RP.



Note This restriction is no longer applicable in Cisco IOS XR Release 7.5.1 and later.

Configure GNSS

Configuration Example

This section describes how you can configure GNSS for a router.

```
/* Enable the GNSS receiver and enter the gnss-receiver submode */

Router(config)# gnss-receiver 0 location 0/0/CPU00/RP0/CPU0
Router(config-gnss)# frequency synchronization
Router(config-gnss-freqsync)# selection input
```

Optional Configuration Example

```
Router(config)# gnss-receiver 0 location 0/0/CPU00/RP0/CPU0
Router(config-gnss)# anti-jam disable
Router(config-gnss)# constellation GPS
Router(config-gnss)# snr threshold 10
Router(config-gnss)# frequency synchronization
Router(config-gnss-freqsync)# selection input
Router(config-gnss-freqsync)# priority 5 >>>Values can range from 1 (highest priority) to
254 (lowest priority). The default value is 100.
Router(config-gnss-freqsync)# wait-to-restore 0
```

Running Configuration

```
gnss-receiver 0 location 0/RP0/CPU0
frequency synchronization
  selection input
  priority 1
  wait-to-restore 0
  quality receive exact itu-t option 1 PRC
!
```

Verification

The following is the output of the **show gnss-receiver** command on the router models.

```
# show gnss-receiver
GNSS-receiver 0 location 0/RP0/CPU0
  Status: Available, Up
  Position: 741:12.12 N 4451:39.60 E 0.827km
  Time: 2019:01:17 14:43:08 (UTC offset: 18s)
  Firmware version: 1.4
  Lock Status: Phase Locked, Receiver Mode: 3D-fix
  Survey Progress: 100, Holdover Duration: 0
  Major Alarm: Not used
  Minor Alarm: Not used
  Anti-jam: Enabled, Cable-delay compensation: 0
  1PPS polarity: Positive
  PDOP: 6.000, HDOP: 0.000, VDOP: 0.000, TDOP: 1.000
  Constellation: GPS, Satellite Count: 10
```




CHAPTER 8

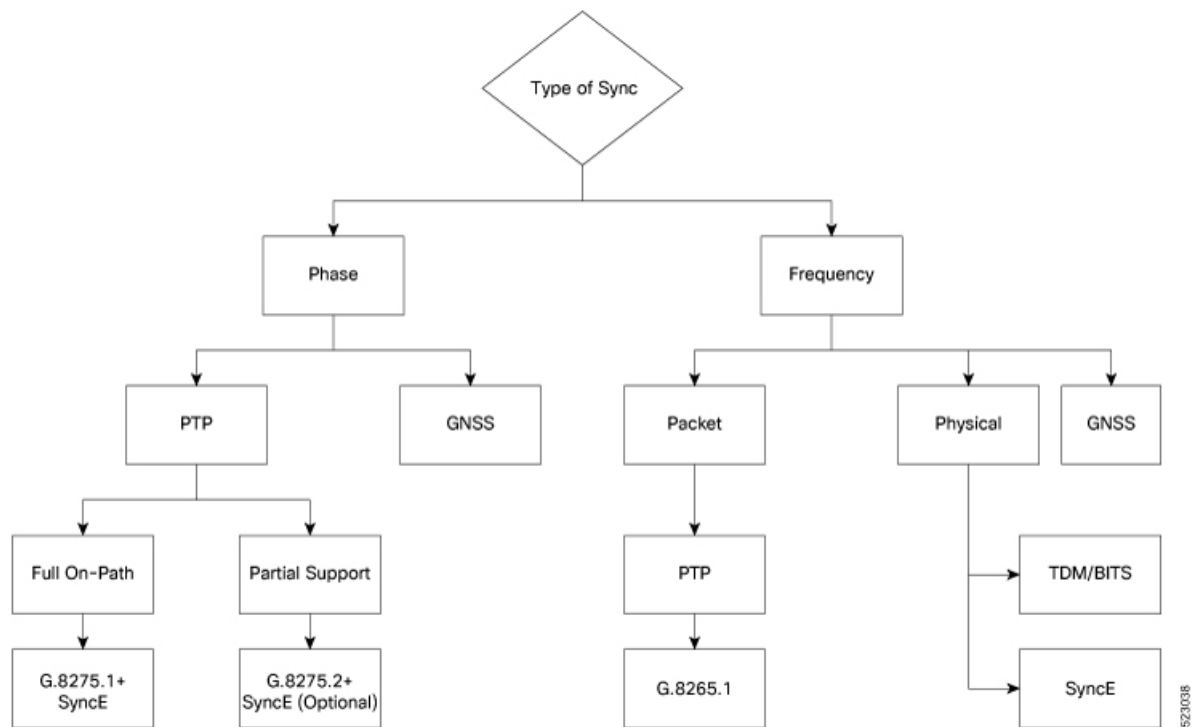
Network Synchronization Design Best Practices

The synchronization of a network is essential for ensuring that all devices in a network run on the same clock time. It also ensures that the applications in the network function correctly. To design your network synchronization accurately, you must have a clear understanding of your network requirements, timing budget, application requirements, and the desired level of synchronization accuracy. This section describes some best practices to follow when designing your network synchronization.

- [Network Synchronization Decision Tree, on page 67](#)
- [General Guidelines for Successful Synchronization Deployments, on page 68](#)
- [Guidelines for Phase Synchronization Deployments, on page 69](#)
- [PTP over IP Network Design, on page 70](#)
- [Selecting the Correct Profile For Network Synchronization, on page 71](#)
- [Reducing Asymmetry, on page 72](#)
- [Reducing Packet Delay Variation, on page 72](#)
- [Remediating Transport Asymmetry, on page 72](#)
- [Synchronizing Across Networks, on page 73](#)

Network Synchronization Decision Tree

Use the network synchronization decision tree for determining the appropriate synchronization solution for your network deployment. Network synchronization helps in ensuring that the network operates with accurate and synchronized time.



General Guidelines for Successful Synchronization Deployments

Network synchronization is crucial for maintaining reliable and efficient network operations, ensuring data integrity, complying with regulations, and facilitating troubleshooting and management tasks. The following guidelines help in deploying successful network synchronization for your network:

- Ensure that you use a standards-based solution designed for your need. For example, use the correct profile.
- Configure the appropriate clock source for your network. It can be Global Navigation Satellite System (GNSS) based such as a Global Positioning System (GPS) clock, or a Precision Time Protocol (PTP) grandmaster clock.
 - Frequency synchronization requires Building Integrated Timing Supply (BITS) or synchronous Ethernet, and Phase synchronization requires PTP and/or GNSS.
- Use a combination of GNSS over the air and/or PTP or synchronous Ethernet over transport.

For more information on [SyncE](#) and [PTP](#), refer to *Network Synchronization Configuration Guide for Cisco NCS 540 Series Routers*.

- Set up the synchronization protocols that are required, which includes PTP, Network Time Protocol (NTP), or synchronous Ethernet.
 - NTP uses the system clock for logging events in the system, or to show clock output, whereas PTP and GNSS work on the IEEE 1588 hardware clock in the system.
 - The NTP clock of a node can't be used to synchronize the downstream network using PTP. However, a node can synchronize its NTP clock with the available PTP or GNSS clock.

**Note**

Most NTP implementations are software-based. Software-based time synchronization is less accurate than hardware-based synchronization, but it's still useful for applications where low levels of accuracy, such as 10's or 100's of milliseconds, are acceptable.

- Use PTP for phase synchronization in the absence of a GNSS.
- Synchronous Ethernet (SyncE) is a recommendation from ITU Telecommunication Standardization Sector (ITU-T) on how to deliver a frequency in a network. If you require a frequency-only synchronization solution, use SyncE instead of PTP.
- Configure the appropriate synchronization profiles and preferences for your network. It might include the accuracy, priority, and other parameters that determine how your network handles synchronization events.
- Design your network for phase synchronization with optimal time error budgets.
 - Use boundary clocks to reduce time error and to reset Packet Delay Variation (PDV).
 - Ensure that PTP awareness is implemented consistently throughout, including the transport system, and that boundary clocks accurately transmit time to minimize accumulated time error.

- For phase synchronization, use a hybrid clock that incorporates both SyncE and PTP.

For more information on [PTP Hybrid Mode](#), refer to *Network Synchronization Configuration Guide for Cisco NCS 540 Series Routers*.

- Reduce the number of hops:
 - Distribute sources of time to meet the budget. If you have too many hops, install a GNSS receiver further out into the network.
 - Don't centralize two Primary Reference Time Clocks (PRTC) and Telecom Grandmasters (T-GM) in two different locations and try to run a synchronization signal accurately across the whole network.
- Minimize Packet Delay Variation (PDV) and jitter. Ensure that microwaves, Gigabit-capable Passive Optical Networks (GPON), Digital Subscriber Line (DSL), and Dense Wavelength Division Multiplexing (DWDM) are PTP aware.
- Monitor your synchronization deployment to ensure that it's functioning correctly and meeting your desired level of accuracy.

For more information, refer to [Verifying the Frequency Synchronization Configuration](#) in the *Network Synchronization Configuration Guide for Cisco NCS 540 Series Routers*.

- Be aware of any relevant industry standards and practices when deploying synchronization.

Guidelines for Phase Synchronization Deployments

Follow these guidelines for phase synchronization deployments.

- Set up the necessary network infrastructure to support phase synchronization. It includes installing timing devices such as GPS receivers, synchronous Ethernet interfaces, and timing servers.
- Configure the phase synchronization protocols such as setting up PTP as appropriate.
- As best practice, use the G.8275.1 telecommunication profile standard with complete on-path support, including Layer-2 multicast in combination with SyncE.
- Minimize phase time error by performing the following tasks:
 - Remove asymmetric routing issues.
 - Reduce the number of hops, unless telecommunication grandmaster (T-GM) clocks are deployed in the preaggregation network.
 - Decrease PDV or packet jitter.
- If you use IP protocols for PTP, you can run into issues with rerouting, asymmetric routing, Equal Cost Multi-Path (ECMP), bundles, and so on.
- If you need tight timing budgets over many hops, ensure that your hardware supports the highest levels of clock accuracy.
- For GNSS deployments:
 - Meet all the requirements for cable and antenna installations.
 - Consult with a professional if you don't have experience with GNSS installation and calibration.
- Make sure that your deployment is working as intended. Monitor it regularly to identify any potential issues.
- Consult with Cisco technical support if you encounter any issues or have questions.



Note When PTP is used with MACsec, achieving high accuracy can be challenging. PTP requires exact timestamping to maintain tight network synchronization. MACsec affixes and detaches a header that is between 24–32 bytes in size. This process can lead to significant inconsistencies in the time delays between where the link is connected and the location where the egress timestamps are applied.

PTP over IP Network Design

When using networks to carry frequency over Precision Time Protocol over Internet Protocol (PTPoIP), the goal is to minimize Packet Delay Variation (PDV) by reducing the number of hops. Use the following guidelines:

- The placement of the telecom grandmaster (T-GM) clock plays an important role in ensuring that the network operates within your timing budget. For example, place a pair of T-GM clocks in a centralized location only if the network has a small number of hops. In larger networks with multiple hops, it may be necessary to distribute T-GM clocks throughout the network to ensure proper timing management at each hop.

- Use a dedicated frequency synchronization protocol such as synchronous Ethernet or 1588v2, which is designed specifically to maintain precise frequency synchronization between devices.
- Use the G.8265.1 standard. Frequency synchronization using the G.8265.1 standard is a way to make sure multiple devices on a network are operating at the same frequency, allowing for more accurate and reliable communication.
- Configure Quality of Service (QoS) policies to prioritize network traffic and reduce delays. This can be done by using traffic shaping, traffic policing, and queue management.

Selecting the Correct Profile For Network Synchronization

G.8275.1 PTPoE

G.8275.1 is a technical specification standard for Precision Time Protocol over Ethernet (PTPoE). It defines how you can use the Precision Time Protocol (PTP) to synchronize clocks over Ethernet networks with layer 2 multicast. PTPoE is an extension of PTP that allows it to be used over Ethernet networks. It's used in applications where precise time synchronization is required.

For more information, refer to [G.8275.1](#) in the *Network Synchronization Configuration Guide for Cisco NCS 540 Series Routers*.

G.8275.2 PTPoIP

G.8275.2 is a technical specification standard for Precision Time Protocol over Internet Protocol (PTPoIP). It defines the use of the Precision Time Protocol (PTP) over packet-based networks such as Internet Protocol (IP) networks, to provide precise time synchronization of network devices.

For more information, refer to [G.8275.2](#) in the *Network Synchronization Configuration Guide for Cisco NCS 540 Series Routers*.

Feature Adaptability on Each Profile

The following table lists the adaptability of features on each profile:

Feature	G.8275.1 PTPoE	G.8275.2 PTPoIP
Network Model	Full on-path support	Partial on-path support
IP Routing	Not applicable	Can cause issues in rings and asymmetry from a number of causes
Transit Traffic	Not allowed	Can result in jitter and asymmetry
Performance	Optimal	Variable
Configuration Model	Physical port	L3 device
PTP over Bundles	No issues	Work in progress for Telecom Boundary Clocks (T-BC)

Feature	G.8275.1 PTPoE	G.8275.2 PTPoIP
Asymmetry	Reduced due to T-BC on every node	Optimal when deployed as a Partial Support Telecom Boundary Clock (T-BC-P)
PDV/Jitter	Reduced due to T-BC on every node	Optimal when deployed as a T-BC-P

Reducing Asymmetry

Asymmetry occurs in a PTP unaware network for the following scenarios:

- When routing large networks, complex topologies, rings, and Equal-cost multi-path (ECMP)
- When using PTP unaware transit nodes, especially with varying traffic patterns
- In the transport layer such as Passive Optical Network (PON), cable, DWDM, and complex optics



Note Every 2 seconds of asymmetry results in 1 microsecond of time error.

To reduce asymmetry in a PTP unaware network:

- Use QoS: QoS can help reduce asymmetry in an unaware network.
- Implement Telecom Boundary Clocks (T-BC): T-BCs can handle asymmetry in the nodes when implemented correctly.

Reducing Packet Delay Variation

To reduce the effects of Packet Delay Variation (PDV) on PTP clock recovery, you must have a steady layer of packets that arrive in minimum time.

- Implement Telecom Boundary Clocks (T-BC) in the PTP unaware node. T-BC introduces a time reference to the PTP unaware node, which then synchronizes its clock with the T-BC.
- Use a high-quality network connection between the T-BC and the PTP unaware node. A high-quality network connection, such as a dedicated fiber link, can help reduce PDV due to network impairments.

Remediating Transport Asymmetry

Transport asymmetry occurs when data is transported at varying rates in different directions over a communication link, leading to an imbalance in transport. To correct this issue:

- Ensure that your transport layer is PTP aware.

In optical devices, use a wavelength division multiplexing (WDM) technology such as Optical Service Channel (OSC) for managing your fiber optic infrastructure effectively.

Synchronizing Across Networks

To avoid synchronization issues when connecting to other mobile networks:

- Make sure to align all mobile networks to a common source of time. For example, align mobile networks to the Coordinated Universal Time (UTC) from a Global Navigation Satellite System (GNSS) such as Global Positioning System (GPS).
- Monitor your clocks at the interconnect points.



Note

In 5G networks, using standalone GNSS receivers at every radio site may not provide the sub-100 nanosecond accuracy required for the timing requirements of Fronthaul radio systems.
