



GCPP Support for Remote PHY

This document provides information on the Generic Control Protocol Principal (GCPP) support on Cisco cBR-8 series routers.

Finding Feature Information

Your software release may not support all the features documented in this module. For the latest feature information and caveats, see the release notes for your platform and software release. To find information about the features documented in this module, and to see a list of the releases in which each feature is supported, see the Feature Information Table at the end of this document.

Use Cisco Feature Navigator to find information about platform support and Cisco software image support. To access Cisco Feature Navigator, go to <http://tools.cisco.com/ITDIT/CFN/>. An account on <http://www.cisco.com/> is not required.

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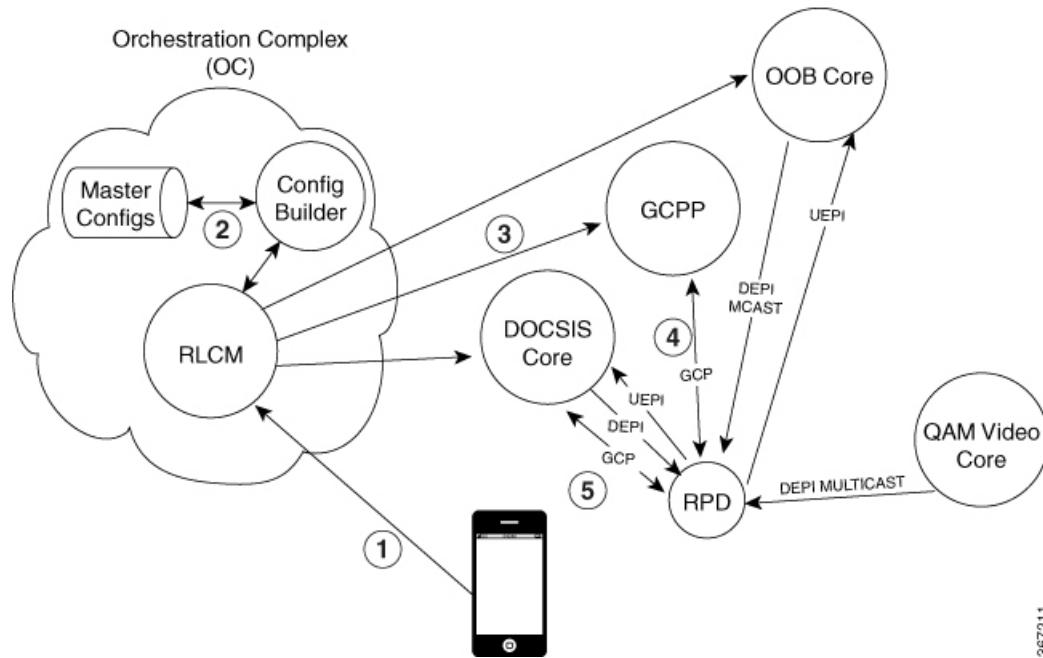
Information About GCPP Support

The Generic Control Protocol (GCP) sets up a control plane tunnel over a generic transport protocol such as TCP or UDP. GCP is used to program the remote PHY system upstream and downstream parameters from the CMTS. It is also used to control the remote PHY system.

The Remote PHY architecture with GCPP (Generic Control Protocol Principal) server, includes separate DOCSIS, QAM video and OOB cores. To enable the use of multiple RPHY cores, the architecture utilizes a GCP Principal Core (GCPP). Initially, the RPDs contact and authenticate with the GCPP core, which also configures the RPDs in its domain in coordination with the Cores (DOCSIS, QAM video, and OOB).

Without the GCPP core, cBR8 is the principal core for RPD. However, in this GCPP architecture, the GCPP server is the principal core and the Cisco cBR8 is an auxiliary core.

Figure 1: Remote PHY Architecture with GCPP



The Cisco 2x2 RPD software supports configurable GCP keepalive timeout parameter.

Hardware Compatibility Matrix for Cisco Remote PHY Device



Note Unless otherwise specified, the hardware components introduced in a given Cisco Remote PHY Device Software Release are supported in all subsequent releases.

Table 1: Hardware Compatibility Matrix for the Cisco Remote PHY Device

Cisco HFC Platform	Remote PHY Device
Cisco GS7000 Super High Output Node	Cisco 1x2 / Compact Shelf RPD Software 2.1 and Later Releases
Cisco GS7000 Super High Output Intelligent Node (iNode)	Cisco 1x2 / Compact Shelf RPD Software 4.1 and Later Releases Cisco Intelligent Remote PHY Device 1x2 <ul style="list-style-type: none"> • PID—iRPD-1X2= • PID—iRPD-1X2-PKEY=



Note The -PKEY suffix in the PID indicates units that enable the SCTE-55-2 Out-of-Band protocol support.

Configuration Example

This section provides example of Cisco cBR-8 Converged Broadband Router configuration when GCPP is the core.

Example: GCPP Configuration

```
cable rpd pl_0719
  identifier 0004.9f00.0719
  core-interface Te6/1/2
    rpd-ds 0 downstream-cable 6/0/17 profile 7
    rpd-us 0 upstream-cable 6/0/17 profile 7
  core-interface Te6/1/1
    rpd-ds 0 downstream-cable 6/0/3 profile 17
r-dti 6
  rpd-event profile 0
  rpd-55d1-us-event profile 0
```

Feature Information for GCPP Support

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Note The below table lists only the software release that introduced support for a given feature in a given software release train. Unless noted otherwise, subsequent releases of that software release train also support that feature.

Table 2: Feature Information for GCPP Support

Feature Name	Releases	Feature Information
GCPP Support	Cisco 1x2 RPD Software 4.1	This feature was introduced on the Cisco Remote PHY Devices.