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```
#!/bin/sh
```

```
# This file is part of avahi.
```

```
#
```

```

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```

```
set -e
```

```

# Command line arguments:
# $1 event that happened:
#      BIND: Successfully claimed address
#      CONFLICT: An IP address conflict happened
#      UNBIND: The IP address is no longer needed
#      STOP: The daemon is terminating
# $2 interface name
# $3 IP address

```

```
# We have the BSD ifconfig tool
```

```

case "$1" in
BIND)
    ifconfig "$2" "$3"/16
    ;;
CONFLICT|STOP|UNBIND)
    ifconfig "$2" "$3"/16 delete
    ;;
*)
    echo "Unknown event $1" >&2
    exit 1
    ;;
esac

exit 0

```

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1.2 e2fsprogs 1.42.9 :4.el7

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Index: tdbsa/tdb.c

--- tdbsa.orig/tdb.c

+++ tdbsa/tdb.c

@@@ -4,11 +4,11 @@ Rev: 23371

Last Changed Date: 2007-06-06 20:14:06 -0400 (Wed, 06 Jun 2007)

*/

/*

- Unix SMB/CIFS implementation.
- + trivial database library - standalone version

- trivial database library - private includes

-

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#

This is a Makefile stub which handles the creation of BSD shared
libraries.

#

In order to use this stub, the following makefile variables must be defined.

#

BSDLIB_VERSION = 1.0

BSDLIB_IMAGE = libce

BSDLIB_MYDIR = et

BSDLIB_INSTALL_DIR = \$(SHLIBDIR)

#

all:: image

real-subdirs:: Makefile

@echo " MKDIR pic"

@mkdir -p pic

BSD_LIB = \$(BSDLIB_IMAGE).so.\$(BSDLIB_VERSION)

BSDLIB_PIC_FLAG = -fpic

image: \$(BSD_LIB)

```

$(BSD_LIB): $(OBJS)
(cd pic; ld -Bshareable -o $(BSD_LIB) $(LDFLAGS) $(OBJS))
$(MV) pic/$(BSD_LIB) .
$(RM) -f ../$BSD_LIB
(cd ..; $(LN) $(LINK_BUILD_FLAGS) \
`echo $(my_dir) | sed -e 's;lib/;;'`/$(BSD_LIB) $(BSD_LIB))

install-shlibs install:: $(BSD_LIB)
@echo " INSTALL_PROGRAM $(BSDLIB_INSTALL_DIR)/$(BSD_LIB)"
@$(INSTALL_PROGRAM) $(BSD_LIB) \
$(DESTDIR)$(BSDLIB_INSTALL_DIR)/$(BSD_LIB)
@-$(LDCONFIG)

```

install-strip: install

install-shlibs-strip: install-shlibs

uninstall-shlibs uninstall::

```
$(RM) -f $(DESTDIR)$(BSDLIB_INSTALL_DIR)/$(BSD_LIB)
```

clean::

```
$(RM) -rf pic
$(RM) -f $(BSD_LIB)
$(RM) -f ../$BSD_LIB
```

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Gadi Oxman, August 1995

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Theodore Ts'o
23-June-2007

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1.3 kernel 3.10.0 :229.7.2.el7

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The reason we have a separate public license for some libraries is that they blur the distinction we usually make between modifying or adding to a program and simply using it. Linking a program with a library, without changing the library, is in some sense simply using the library, and is analogous to running a utility program or application program. However, in a textual and legal sense, the linked executable is a combined work, a derivative of the original library, and the ordinary General Public License treats it as such.

Because of this blurred distinction, using the ordinary General Public License for libraries did not effectively promote software sharing, because most developers did not use the libraries. We concluded that weaker conditions might promote sharing better.

However, unrestricted linking of non-free programs would deprive the users of those programs of all benefit from the free status of the libraries themselves. This Library General Public License is intended to permit developers of non-free programs to use free libraries, while preserving your freedom as a user of such programs to change the free libraries that are incorporated in them. (We have not seen how to achieve this as regards changes in header files, but we have achieved it as regards changes in the actual functions of the Library.) The hope is that this will lead to faster development of free libraries.

The precise terms and conditions for copying, distribution and modification follow. Pay close attention to the difference between a "work based on the library" and a "work that uses the library". The former contains code derived from the library, while the latter only works together with the library.

Note that it is possible for a library to be covered by the ordinary General Public License rather than by this special one.

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This option is useful when you wish to copy part of the code of the Library into a program that is not a library.

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Otherwise, if the work is a derivative of the Library, you may distribute the object code for the work under the terms of Section 6. Any executables containing that work also fall under Section 6, whether or not they are linked directly with the Library itself.

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QLogic Linux Networking HBA Driver

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(in case you are wondering where CyberLogin is, EON changed its login
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Kirk Lapray <kirk.lapray@gmail.com>
for the or51211 and or51132 frontend drivers, and
for merging the nxt2002 and nxt2004 modules into a
single nxt200x frontend driver.

(If you think you should be in this list, but you are not, drop a
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Version 1.0

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```
/* nicstar.c v0.22 Jawaid Bazyar (bazyar@hypermall.com)
 * nicstar.c, M. Welsh (matt.welsh@cl.cam.ac.uk)
 *
 * Hacked October, 1997 by Jawaid Bazyar, Interlink Advertising Services Inc.
 * http://www.hypermall.com/
 * 10/1/97 - commented out CFG_PHYIE bit - we don't care when the PHY
 * interrupts us (except possibly for removal/insertion of the cable?)
 * 10/4/97 - began heavy inline documentation of the code. Corrected typos
 * and spelling mistakes.
 * 10/5/97 - added code to handle PHY interrupts, disable PHY on
 * loss of link, and correctly re-enable PHY when link is
 * re-established. (put back CFG_PHYIE)
 *
 * Modified to work with the IDT7721 nicstar -- AAL5 (tested) only.
 *
 * R. D. Rechenmacher <ron@fnal.gov>, Aug. 6, 1997
 *
 * Linux driver for the IDT77201 NICStAR PCI ATM controller.
 * PHY component is expected to be 155 Mbps S/UNI-Lite or IDT 77155;
 * see init_nicstar() for PHY initialization to change this. This driver
 * expects the Linux ATM stack to support scatter-gather lists
 * (skb->atm.iovcnt != 0) for Rx skb's passed to vcc->push.
 *
 * Implementing minimal-copy of received data:
 * IDT always receives data into a small buffer, then large buffers
 * as needed. This means that data must always be copied to create
 * the linear buffer needed by most non-ATM protocol stacks (e.g. IP)
 * Fix is simple: make large buffers large enough to hold entire
 * SDU, and leave <small_buffer_data> bytes empty at the start. Then
 * copy small buffer contents to head of large buffer.
 * Trick is to avoid fragmenting Linux, due to need for a lot of large
 * buffers. This is done by 2 things:
 * 1) skb->destructor / skb->atm.recycle_buffer
```

```

*      combined, allow nicstar_free_rx_skb to be called to
*      recycle large data buffers
*      2) skb_clone of received buffers
* See nicstar_free_rx_skb and linearize_buffer for implementation
*      details.
*
*
*
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* Foundation, Inc., 675 Mass Ave, Cambridge, MA 02139, USA.
*
* M. Welsh, 6 July 1996
*
*
*/

```

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```
cmd/krb5/prop/prop.x
cmd/krb5/prop/prop_hdr.h
cmd/krb5/kadmin/server/propd_svc.c
cmd/krb5/kproplog/kproplog.c
cmd/krb5/slave/kpropd_rpc.c
lib/gss_mechs/mech_krb5/et/kdb5_err.c
lib/gss_mechs/mech_spnego/mecg/gssapiP_spnego.h
lib/gss_mechs/mech_spnego/mech_spnego_mech.c
lib/krb5/kadm5/kadm_host_srv_names.c
lib/krb5/kdb/kdb_convert.c
```

```
lib/krb5/kdb/kdb_hdr.h
lib/krb5/kdb/kdb_log.c
lib/krb5/kdb/kdb_log.h
lib/libgss/g_accept_sec_context.c
lib/libgss/g_acquire_cred.c
lib/libgss/g_canon_name.c
lib/libgss/g_compare_name.c
lib/libgss/g_context_time.c
lib/libgss/g_delete_sec_context.c
lib/libgss/g_dsp_name.c
lib/libgss/g_dsp_status.c
lib/libgss/g_dup_name.c
lib/libgss/g_exp_sec_context.c
lib/libgss/g_export_name.c
lib/libgss/g_glue.c
lib/libgss/g_imp_name.c
lib/libgss/g_imp_sec_context.c
lib/libgss/g_init_sec_context.c
lib/libgss/g_initialize.c
lib/libgss/g_inquire_context.c
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lib/libgss/g_inquire_names.c
lib/libgss/g_process_context.c
lib/libgss/g_rel_buffer.c
lib/libgss/g_rel_cred.c
lib/libgss/g_rel_name.c
lib/libgss/g_rel_oid_set.c
lib/libgss/g_seal.c
lib/libgss/g_sign.c
lib/libgss/g_store_cred.c
lib/libgss/g_unseal.c
lib/libgss/g_userok.c
lib/libgss/g_utils.c
lib/libgss/g_verify.c
lib/libgss/gssd_pname_to_uid.c
uts/common/gssapi/include/gssapi_err_generic.h
uts/common/gssapi/include/mechglueP.h
```

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The implementations of GSSAPI mechglue in GSSAPI-SPNEGO in "src/lib/gssapi", including the following files:

```
lib/gssapi/generic/gssapi_err_generic.et
lib/gssapi/mechglue/g_accept_sec_context.c
lib/gssapi/mechglue/g_acquire_cred.c
lib/gssapi/mechglue/g_canon_name.c
lib/gssapi/mechglue/g_compare_name.c
lib/gssapi/mechglue/g_context_time.c
lib/gssapi/mechglue/g_delete_sec_context.c
lib/gssapi/mechglue/g_dsp_name.c
lib/gssapi/mechglue/g_dsp_status.c
lib/gssapi/mechglue/g_dup_name.c
lib/gssapi/mechglue/g_exp_sec_context.c
lib/gssapi/mechglue/g_export_name.c
lib/gssapi/mechglue/g_glue.c
lib/gssapi/mechglue/g_imp_name.c
lib/gssapi/mechglue/g_imp_sec_context.c
lib/gssapi/mechglue/g_init_sec_context.c
lib/gssapi/mechglue/g_initialize.c
lib/gssapi/mechglue/g_inquire_context.c
lib/gssapi/mechglue/g_inquire_cred.c
lib/gssapi/mechglue/g_inquire_names.c
lib/gssapi/mechglue/g_process_context.c
lib/gssapi/mechglue/g_rel_buffer.c
lib/gssapi/mechglue/g_rel_cred.c
lib/gssapi/mechglue/g_rel_name.c
lib/gssapi/mechglue/g_rel_oid_set.c
lib/gssapi/mechglue/g_seal.c
lib/gssapi/mechglue/g_sign.c
lib/gssapi/mechglue/g_store_cred.c
lib/gssapi/mechglue/g_unseal.c
lib/gssapi/mechglue/g_userok.c
lib/gssapi/mechglue/g_utils.c
lib/gssapi/mechglue/g_verify.c
lib/gssapi/mechglue/gssd_pname_to_uid.c
lib/gssapi/mechglue/mglueP.h
lib/gssapi/mechglue/oid_ops.c
lib/gssapi/spnego/gssapiP_spnego.h
lib/gssapi/spnego/spnego_mech.c
```

and the initial implementation of incremental propagation, including the following new or changed files:

```
include/iprop_hdr.h
kadmin/server/ipropd_svc.c
```

lib/kdb/ipmap.x
lib/kdb/kdb_convert.c
lib/kdb/kdb_log.c
lib/kdb/kdb_log.h
lib/krb5/error_tables/kdb5_err.et
slave/kpropd_rpc.c
slave/kproplog.c

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1.7 libnet 1.1.6 :7.el7

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EOF

1.8 linux-firmware 20140213

:0.3.git4164c23.el7

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The README file from the original package from Micronas appears below. Only the part about the firmware redistribution in section 0 is relevant, all other sections are completely obsolete.

WIS GO7007SB Public Linux Driver

*** Please see the file RELEASE-NOTES for important last-minute updates ***

0. OVERVIEW AND LICENSING/DISCLAIMER

This driver kit contains Linux drivers for the WIS GO7007SB multi-format video encoder. Only kernel version 2.6.x is supported. The video stream is available through the Video4Linux2 API and the audio stream is available through the ALSA API (or the OSS emulation layer of the ALSA system).

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1. SYSTEM REQUIREMENTS

This driver requires Linux kernel 2.6. Kernel 2.4 is not supported. Using kernel 2.6.10 or later is recommended, as earlier kernels are known to have unstable USB 2.0 support.

A fully built kernel source tree must be available. Typically this will be linked from "/lib/modules/<KERNEL VERSION>/build" for convenience. If this link does not exist, an extra parameter will need to be passed to the `make` command.

All vendor-built kernels should already be configured properly. However, for custom-built kernels, the following options need to be enabled in the kernel as built-in or modules:

CONFIG_HOTPLUG	- Support for hot-pluggable devices
CONFIG_MODULES	- Enable loadable module support
CONFIG_KMOD	- Automatic kernel module loading
CONFIG_FW_LOADER	- Hotplug firmware loading support
CONFIG_I2C	- I2C support
CONFIG_VIDEO_DEV	- Video For Linux
CONFIG_SOUND	- Sound card support
CONFIG_SND	- Advanced Linux Sound Architecture
CONFIG_USB	- Support for Host-side USB
CONFIG_USB_DEVICEFS	- USB device filesystem
CONFIG_USB_EHCI_HCD	- EHCI HCD (USB 2.0) support

Additionally, to use the example application, the following options need to be enabled in the ALSA section:

CONFIG SND MIXER OSS	- OSS Mixer API
CONFIG SND PCM OSS	- OSS PCM (digital audio) API

The hotplug scripts, along with the fxload utility, must also be installed. These scripts can be obtained from <<http://linux-hotplug.sourceforge.net/>>. Hotplugging is used for loading firmware into the Cypress EZ-USB chip using fxload and for loading firmware into the driver using the firmware agent.

2. COMPILING AND INSTALLING THE DRIVER

Most users should be able to compile the driver by simply running:

```
$ make
```

in the top-level directory of the driver kit. First the kernel modules will be built, followed by the example applications.

If the build system is unable to locate the kernel source tree for the currently-running kernel, or if the module should be built for a kernel other than the currently-running kernel, an additional parameter will need to be passed to make to specify the appropriate kernel source directory:

```
$ make KERNELSRC=/usr/src/linux-2.6.10-custom3
```

Once the compile completes, the driver and firmware files should be installed by running:

```
$ make install
```

The kernel modules will be placed in "/lib/modules/<KERNEL VERSION>/extra" and the firmware files will be placed in the appropriate hotplug firmware directory, usually /lib/firmware. In addition, USB maps and scripts will be placed in /etc/hotplug/usb to enable fxload to initialize the EZ-USB control chip when the device is connected.

3. PAL/SECAM TUNER CONFIGURATION (TV402U-EU only)

The PAL model of the Plextor ConvertX TV402U may require additional configuration to correctly select the appropriate TV frequency band and audio subchannel.

Users with a device other than the Plextor ConvertX TV402U-EU should skip this section.

The wide variety of PAL TV systems used in Europe requires that additional information about the local TV standards be passed to the driver in order to properly tune TV channels. The two necessary parameters are (a) the PAL TV band, and (b) the audio subchannel format in use.

In many cases, the appropriate TV band selection is passed to the driver from applications. However, in some cases, the application only specifies that the driver should use PAL but not the specific information about the appropriate TV band. To work around this issue, the correct TV band may be specified in the "force_band" parameter to the wis-sony-tuner module:

TV band	force_band
---------	------------

PAL B/G	B
---------	---

PAL I	I
-------	---

PAL D/K	D
---------	---

SECAM L	L
---------	---

If the "force_band" parameter is specified, the driver will ignore any TV band specified by applications and will always use the band provided in the module parameter.

The other parameter that can be specified is the audio subchannel format. There are several stereo audio carrier systems in use, including NICAM and three varieties of A2. To receive audio broadcast on one of these stereo carriers, the "force_mpx_mode" parameter must be specified to the wis-sony-tuner module.

TV band	Audio subcarrier	force_mpx_mode
---------	------------------	----------------

PAL B/G	Mono (default)	1
---------	----------------	---

PAL B/G	A2	2
---------	----	---

PAL B/G	NICAM	3
---------	-------	---

PAL I	Mono (default)	4
-------	----------------	---

PAL I	NICAM	5
-------	-------	---

PAL D/K	Mono (default)	6
---------	----------------	---

PAL D/K	A2 (1)	7
---------	--------	---

PAL D/K	A2 (2)	8
---------	--------	---

PAL D/K	A2 (3)	9
---------	--------	---

PAL D/K	NICAM	10
---------	-------	----

SECAM L	Mono (default)	11
---------	----------------	----

SECAM L	NICAM	12
---------	-------	----

If the "force_mpx_mode" parameter is not specified, the correct mono-only mode will be chosen based on the TV band. However, the tuner will not receive stereo audio or bilingual broadcasts correctly.

To pass the "force_band" or "force_mpx_mode" parameters to the wis-sony-tuner module, the following line must be added to the modprobe configuration file, which varies from one Linux distribution to another.

```
options wis-sony-tuner force_band=B force_mpx_mode=2
```

The above example would force the tuner to the PAL B/G TV band and receive stereo audio broadcasts on the A2 carrier.

To verify that the configuration has been placed in the correct location, execute:

```
$ modprobe -c | grep wis-sony-tuner
```

If the configuration line appears, then modprobe will pass the parameters correctly the next time the wis-sony-tuner module is loaded into the kernel.

4. TESTING THE DRIVER

Because few Linux applications are able to correctly capture from Video4Linux2 devices with only compressed formats supported, the new driver should be tested with the "gorecord" application in the apps/ directory.

First connect a video source to the device, such as a DVD player or VCR. This will be captured to a file for testing the driver. If an input source is unavailable, a test file can still be captured, but the video will be black and the audio will be silent.

This application will auto-detect the V4L2 and ALSA/OSS device names of the hardware and will record video and audio to an AVI file for a specified number of seconds. For example:

```
$ apps/gorecord -duration 60 capture.avi
```

If this application does not successfully record an AVI file, the error messages produced by gorecord and recorded in the system log (usually in /var/log/messages) should provide information to help resolve the problem.

Supplying no parameters to gorecord will cause it to probe the available devices and exit. Use the -help flag for usage information.

5. USING THE DRIVER

The V4L2 device implemented by the driver provides a standard compressed format API, within the following criteria:

- * Applications that only support the original Video4Linux1 API will not be able to communicate with this driver at all.
- * No raw video modes are supported, so applications like xawtv that expect only uncompressed video will not function.
- * Supported compression formats are: Motion-JPEG, MPEG1, MPEG2 and MPEG4.
- * MPEG video formats are delivered as Video Elementary Streams only.

Program Stream (PS), Transport Stream (TS) and Packetized Elementary Stream (PES) formats are not supported.

- * Video parameters such as format and input port may not be changed while the encoder is active.
- * The audio capture device only functions when the video encoder is actively capturing video. Attempts to read from the audio device when the encoder is inactive will result in an I/O error.
- * The native format of the audio device is 48Khz 2-channel 16-bit little-endian PCM, delivered through the ALSA system. No audio compression is implemented in the hardware. ALSA may convert to other uncompressed formats on the fly.

The include/ directory contains a C header file describing non-standard features of the GO7007SB encoder, which are described below:

GO7007IOC_S_COMP_PARAMS, GO7007IOC_G_COMP_PARAMS

These ioctls are used to negotiate general compression parameters.

To query the current parameters, call the GO7007IOC_G_COMP_PARAMS ioctl with a pointer to a struct go7007_comp_params. If the driver is not set to MPEG format, the EINVAL error code will be returned.

To change the current parameters, initialize all fields of a struct go7007_comp_params and call the GO7007_IOC_S_COMP_PARAMS ioctl with a pointer to this structure. The driver will return the current parameters with any necessary changes to conform to the limitations of the hardware or current compression mode. Any or all fields can be set to zero to request a reasonable default value. If the driver is not set to MPEG format, the EINVAL error code will be returned. When I/O is in progress, the EBUSY error code will be returned.

Fields in struct go7007_comp_params:

__u32 gop_size	The maximum number of frames in each Group Of Pictures; i.e. the maximum number of frames minus one between each key frame.
-------------------	---

__u32 max_b_frames	The maximum number of sequential bidirectionally-predicted frames. (B-frames are not yet supported.)
-----------------------	---

enum go7007_aspect_ratio	The aspect ratio to be encoded in the
--------------------------	---------------------------------------

`aspect_ratio` meta-data of the compressed format.

Choices are:

GO7007_ASPECT_RATIO_1_1
GO7007_ASPECT_RATIO_4_3_NTSC
GO7007_ASPECT_RATIO_4_3_PAL
GO7007_ASPECT_RATIO_16_9_NTSC
GO7007_ASPECT_RATIO_16_9_PAL

`_u32 flags` Bit-wise OR of control flags (below)

Flags in struct go7007_comp_params:

GO7007_COMP_CLOSED_GOP Only produce self-contained GOPs, used to produce streams appropriate for random seeking.

GO7007_COMP OMIT_SEQ_HEADER Omit the stream sequence header.

GO7007IOC_S_MPEG_PARAMS, GO7007IOC_G_MPEG_PARAMS

These ioctls are used to negotiate MPEG-specific stream parameters when the pixelformat has been set to V4L2_PIX_FMT_MPEG.

To query the current parameters, call the GO7007IOC_G_MPEG_PARAMS ioctl with a pointer to a struct go7007_mpeg_params. If the driver is not set to MPEG format, the EINVAL error code will be returned.

To change the current parameters, initialize all fields of a struct `go7007_mpeg_params` and call the `GO7007_IOC_S_MPEG_PARAMS` ioctl with a pointer to this structure. The driver will return the current parameters with any necessary changes to conform to the limitations of the hardware or selected MPEG mode. Any or all fields can be set to zero to request a reasonable default value. If the driver is not set to MPEG format, the `EINVAL` error code will be returned. When I/O is in progress, the `EBUSY` error code will be returned.

Fields in struct go7007_mpeg_params:

enum go7007_mpeg_video_standard
mpeg_video_standard The MPEG video standard in which to compress the video.

Choices are:

GO7007_MPEG_VIDEO_MPEG1
GO7007_MPEG_VIDEO_MPEG2

GO7007_MPEG_VIDEO_MPEG4

__u32 flags	Bit-wise OR of control flags (below)
__u32 pali	The profile and level indication to be stored in the sequence header. This is only used as an indicator to the decoder, and does not affect the MPEG features used in the video stream. Not valid for MPEG1.

Choices for MPEG2 are:

GO7007_MPEG2_PROFILE_MAIN_MAIN

Choices for MPEG4 are:

GO7007_MPEG4_PROFILE_S_L0
GO7007_MPEG4_PROFILE_S_L1
GO7007_MPEG4_PROFILE_S_L2
GO7007_MPEG4_PROFILE_S_L3
GO7007_MPEG4_PROFILE_ARTS_L1
GO7007_MPEG4_PROFILE_ARTS_L2
GO7007_MPEG4_PROFILE_ARTS_L3
GO7007_MPEG4_PROFILE_ARTS_L4
GO7007_MPEG4_PROFILE_AS_L0
GO7007_MPEG4_PROFILE_AS_L1
GO7007_MPEG4_PROFILE_AS_L2
GO7007_MPEG4_PROFILE_AS_L3
GO7007_MPEG4_PROFILE_AS_L4
GO7007_MPEG4_PROFILE_AS_L5

Flags in struct go7007_mpeg_params:

GO7007_MPEG_FORCE_DVD_MODE Force all compression parameters and bitrate control settings to comply with DVD MPEG2 stream requirements.
This overrides most compression and bitrate settings!

GO7007_MPEG OMIT GOP HEADER Omit the GOP header.

GO7007_MPEG_REPEAT_SEQHEADER Repeat the MPEG sequence header at the start of each GOP.

GO7007IOC_S_BITRATE, GO7007IOC_G_BITRATE

These ioctls are used to set and query the target bitrate value for the

compressed video stream. The bitrate may be selected by storing the target bits per second in an int and calling GO7007IOC_S_BITRATE with a pointer to the int. The bitrate may be queried by calling GO7007IOC_G_BITRATE with a pointer to an int where the current bitrate will be stored.

Note that this is the primary means of controlling the video quality for all compression modes, including V4L2_PIX_FMT_MJPEG. The VIDIOC_S_JPEGCOMP ioctl is not supported.

Installing the WIS PCI Voyager Driver

The WIS PCI Voyager driver requires several patches to the Linux 2.6.11.x kernel source tree before compiling the driver. These patches update the in-kernel SAA7134 driver to the newest development version and patch bugs in the TDA8290/TDA8275 tuner driver.

The following patches must be downloaded from Gerd Knorr's website and applied in the order listed:

<http://dl.bytesex.org/patches/2.6.11-2/i2c-tuner>
<http://dl.bytesex.org/patches/2.6.11-2/i2c-tuner2>
<http://dl.bytesex.org/patches/2.6.11-2/v4l2-api-mpeg>
<http://dl.bytesex.org/patches/2.6.11-2/saa7134-update>

The following patches are included with this SDK and can be applied in any order:

patches/2.6.11/saa7134-voyager.diff
patches/2.6.11/tda8275-newaddr.diff
patches/2.6.11/tda8290-ntsc.diff

Check to make sure the CONFIG_VIDEO_SAA7134 option is enabled in the kernel configuration, and build and install the kernel.

After rebooting into the new kernel, the GO7007 driver can be compiled and installed:

```
$ make SAA7134_BUILD=y  
$ make install  
$ modprobe saa7134-go7007
```

There will be two V4L video devices associated with the PCI Voyager. The first device (most likely /dev/video0) provides access to the raw video capture mode of the SAA7133 device and is used to configure the source

video parameters and tune the TV tuner. This device can be used with xawtv or other V4L(2) video software as a standard uncompressed device.

The second device (most likely /dev/video1) provides access to the compression functions of the GO7007. It can be tested using the gorecord application in the apps/ directory of this SDK:

```
$ apps/gorecord -vdevice /dev/video1 -noaudio test.avi
```

Currently the frame resolution is fixed at 720x480 (NTSC) or 720x576 (PAL), and the video standard must be specified to both the raw and the compressed video devices (xawtv and gorecord, for example).

RELEASE NOTES FOR WIS GO7007SB LINUX DRIVER

Last updated: 5 November 2005

- Release 0.9.7 includes new support for using udev to run fxload. The install script should automatically detect whether the old hotplug scripts or the new udev rules should be used. To force the use of hotplug, run "make install USE_UDEV=n". To force the use of udev, run "make install USE_UDEV=y".
- Motion detection is supported but undocumented. Try the `modet` app for a demonstration of how to use the facility.
- Using USB2.0 devices such as the TV402U with USB1.1 HCDs or hubs can cause buffer overruns and frame drops, even at low framerates, due to inconsistency in the bitrate control mechanism.
- On devices with an SAA7115, including the Plextor ConvertX, video height values of 96, 128, 160, 192, 256, 320, and 384 do not work in NTSC mode. All valid heights up to 512 work correctly in PAL mode.
- The WIS Star Trek and PCI Voyager boards have no support yet for audio or the TV tuner.

Firmware provided by Patrick Boettcher <pboettcher@dibcom.fr> to Devin Heitmueller <dheitmueller@kernellabs.com> on October 8, 2009.

The USB firmware file "dvb-usb-dib0700.1.20.fw" for DiBcom's DiB0700, used together with the Linux driver module dvb-usb-dib0700, is provided under the following licensing terms:

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Firmware provided as part of an XC5000 Linux developers kit by Brian Mathews <bmathews@xceive.com> to Devin Heitmueller <dheitmueller@linuxtv.org> on July 1, 2009.

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agere_sto_fw.bin -- 9.48 Hermes I

agere_ap_fw.bin -- 9.48 Hermes I

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The Linux driver architecture was based on two modules, the MSF (Module specific functions) and the HCF (Hardware Control Functions). Included in the HCF is run-time firmware (binary format) which is downloaded into the RAM of the Hermes 1/2/2.5 WMAC.

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Hope this helps.

Sincerely,

Viren Pathare
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1.9 lldpad 0.9.46 :10.el7

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* @version 3.0 (December 2000)

*

* Optimised ANSI C code for the Rijndael cipher (now AES)

*

* @author Vincent Rijmen <vincent.rijmen@esat.kuleuven.ac.be>

* @author Antoon Bosselaers <antoon.bosselaers@esat.kuleuven.ac.be>

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*

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sFlow Specification, located at
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References

1. <http://sflow.org/developers/specifications.php>

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```
# charset=UTF-8
# vim600: encoding=UTF-8
```

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1998/11/10 sgk implementation in C++
1999/4/25 sgk C
1999/4/26 sgk

1999/6/?? Unicode

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1.17 php55-php-pecl-jsonc 1.3.5 :1.el7

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1.18 python-ecdsa 0.11 :3.el7.centos

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1.19 python-paramiko 1.15.1 :1.el7

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"Source code" for a work means the preferred form of the work for making modifications to it. For a library, complete source code means all the source code for all modules it contains, plus any associated interface definition files, plus the scripts used to control compilation and installation of the library.

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This option is useful when you wish to copy part of the code of the Library into a program that is not a library.

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Section 6 states terms for distribution of such executables.

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If such an object file uses only numerical parameters, data structure layouts and accessors, and small macros and small inline functions (ten lines or less in length), then the use of the object file is unrestricted, regardless of whether it is legally a derivative work. (Executables containing this object code plus portions of the Library will still fall under Section 6.)

Otherwise, if the work is a derivative of the Library, you may distribute the object code for the work under the terms of Section 6. Any executables containing that work also fall under Section 6, whether or not they are linked directly with the Library itself.

6. As an exception to the Sections above, you may also combine or link a "work that uses the Library" with the Library to produce a work containing portions of the Library, and distribute that work under terms of your choice, provided that the terms permit modification of the work for the customer's own use and reverse engineering for debugging such modifications.

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1.20 python-scp 0.7.1 :3.el7

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1.21 python-websockify 0.5.1 :1.el7

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Finally, every program is threatened constantly by software patents. States should not allow patents to restrict development and use of software on general-purpose computers, but in those that do, we wish to avoid the special danger that patents applied to a free program could make it effectively proprietary. To prevent this, the GPL assures that patents cannot be used to render the program non-free.

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